

## **Access Technologies**

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- Broadcast Bus Capacity=10 Mb/s
- Xerox-Intel-Digital inventors
- Standardized at the beginning of the 80s as IEEE 802.3
- Big Success and Several Extensions



#### Addressing (on a broadcast medium)





The switch is like a repeater: whenever a frame is received from a station, it is transmitted towards <u>all other</u> stations

#### IEEE 802.3 Frame

#### Ethernet Frame



- □ Frame minimum length = 512 bit (1 slot) equivalent to 51.2 us
- **Propagation speed 2 x 10^8 m/s (5 us/Km)**
- Maximum LAN diameter = 2.5 Km

## **802.3 vs Ethernet**

#### □ They're not the same:

- 802.3 has a LLC (802.2)
- ethernet is directly connected with the network layer

□ E.g.:



# 802.3 vs Ethernet

- The protocol field in Ethernet is used to identify the network SAP
- □ In many LANs Ethernet and 802.3 coexist.
  - The Frame Length Field can be in the range 0-1500
  - The protocol field is >1500 (to be precise, the standard says ">1536", decimal notation, which means 0600 in hexadecimal)

	7	1	6	6	2	0-1500		4	
	Sync	SD	Destination	Source	Frame Lenght	payload	PAD	FCS	802.3
_	7	1	6	6	2	0-1500		4	
	Sync	SD	Destination	Source	Protocol	payload	PAD	FCS	Ethernet

<u>Note:</u> in this latter case, the standard MAC says that it is the MAC client protocol (e.g., IP or the upper level that uses Ethernet) that must operate correctly in case Padding is introduced at the MAC layer (in other words, the correct functioning is demanded at the upper layer)

#### **Access Protocols**

#### Problem:

If two (or more) stations try to transmit at the same time, we have a **collision —** the signal (hence, the frames) is not received correctly



- We need *protocols* (rules) to control the access to the broadcast medium, in order to avoid (or at least, to limit) collisions
- If collision occur, they must be correctly <u>individuated</u> by all stations, in order to re-send the collided frames
- This function is performed in Ethernet at the <u>MAC</u> (Medium Access Control) sublayer



#### **Conceptual Model of Multiple Access**



- The Master does not know *if* and *how many* packets are present in each queue (i.e., if and how many packets are produced by each station)
- □ Each station does not know the state of other stations' queue

## Multiple Access Techniques Classification

- We have two types of access techniques
  - Ordered Access
    - TDMA
    - Round Robin
    - Polling
      - Roll Call Polling
      - Hub Polling
  - Random Access
    - □ CSMA/CD (Ethernet)
    - □ CSMA/CA (IEEE 802.11, WiFi)

## **Example: TDMA**



In LANs, taffic is **bursty**, and we have **several stations** 



TDMA is *inefficient*: **high delays, low throughput** 

## **Example: Round Robin**

- Each station has, in each round, the <u>opportunity</u> to transmit
- When it is the turn of the station:
- if she has no packet to transmit:

she declines the transmission opportunity, which will be given to the subsequent station

if she does have packets to transmit:

she transmits her packets up to a maximum number (K), defined by the protocol itself

Then, the transmission opportunity (the right to transmit) is sent to the subsequent station

#### **Example: Round Robin**



#### **Ordered Access: Polling**





The token comes back to the Master only at the end of the cycle

#### **Random Access Protocols**

 Random access protocols do not have an explicit coordination among stations...

hence, collisions may occur

They differ in how they resolve collisions ...

 ... and also in the feed-back from the channel (i.e., the information that derives from listening to the channel)

 Collisions are overcome by introducing a random mechanism

#### **Random Access Protocol Example: Slotted Aloha**

- Slotted channel (time is divided into slots)
- When a packet arrives at a station, she tries to send it in the first available slot
- If a collision occurs, the station tries to re-send it after a random number of slots ...
- ... such random number is chosen uniformly at random in an interval [0,r]



## Slotted Aloha: Collision Resolution

• If  $r = 0 \rightarrow \text{collision repeats infinite times!}$   $\rightarrow \text{throughput} = 0$  r = 0r = 0

If the offered traffic is high, we need a high r value to avoid instability

To summarize: we would like to have <u>small *r* values</u> when the network is empty and <u>large *r* values</u> when the network is congested !!!

#### **Carrier Sense Multiple Access**

 CSMA has been created for systems in which the station can *listen* to the channel (Carrier Sense)

 Transmission is possible <u>only</u> if the channel is sensed free (*listening before transmitting*)

 Collisions are still possible due to the so called vulnerable period



 $t_1$ ,  $t_2$ : instants at which the fartherst stations (A and D) start transmitting a frame after having seen that the channel is (apparently) free

#### **Vulnerable Period**



au : propagation time between the two farthest stations (A and D)

T : frame duration, must be larger than  $2\tau$ 

## **Variations to Carrier Sense**

 If a station senses the channel and finds it already active (i.e., not free):

→ the transmission is postponed after a random time (just as if a collision occurred) (*non persistent*)

→ the transmission starts immediately when the channel becomes free again (*persistent*)

→ with probability p the station uses the persistent approach, with 1-p the non persistent one (*p-persistent*)

#### **CSMA-** Collision Detect (CSMA/CD)

In some channels (e.g., wired ones) it is possible for a station to discover if a collision occurred
The time necessary for all stations on the bus to see that a collision really occurred depends on the propagation time (which is smaller than the frame transmission time in LANs)



Why continue transmitting after the station knows that the frame experienced a collision? Idea: whener the station knows that a collision occurred, she stops immediately sending the rest of the frame



#### Ethernet - IEEE 802.3 Protocol (CSMA/CD)

- □ If the channel is sensed <u>free</u>, the transmission is performed
- If the channel is <u>busy</u>, transmission is refrained; transmission happens as soon as the channel is free again (1-persistent)
- If a collision happens, transmission is aborted after transmitting 32 more bits of jamming sequence
- After a collision, the next transmission is attempted after X time slots
- X is randomly chosen between 0 and 2<sup>min(K,10)</sup> K number of consecutive collisions, K<=16 (exponential binary backoff)
- □ After 16 failed attempts the frame is dropped

## Interconnecting Local Networks



#### **Single Broadcast Domain, Different Collisions Domains**



- □ Functionalities:
  - Filtering: if a frame generated within LAN 1 is destined to LAN 1 it remains confined within LAN 1
  - Relaying: if a frame originated within LAN 1 is destined to LAN 2 it is relayed by the bridge (possible MAC translation)

## **Repeaters & Bridges**



## **Bridge Architecture**

Filtering and Relaying are performed according to a local *Forwarding Data Base* (or *FDB*)



## **Bridge Forwarding**



## How to Fill/Update the FDB: Backward Learning



## **An Example**



## **An Example**







#### **Complete FDB D.MAC E.MAC F.MAC G.MAC** $|\Pi ||$ ΠΠ $\overline{\Pi}$ Ethernet 2 Filtering Database Port 2 MAC address Port BRIDGE A.MAC 1 B.MAC Port 1 $\boldsymbol{F}$ Ethernet 1 C.MAC D.MAC 2 2 E.MAC $\overline{\Pi}$ 2 F.MAC A.MAC B.MAC C.MAC 2 G.MAC





#### **Broadcast Storm** A is not in FDB Frame is forwarded A.MAC FDB Entry Updated ΠΠ Lan 1 2) MAC **Port** MAC **Port** Ζ A address address **B.MAC** X **B.MAC** Z BRIDGE BRIDGE Lan 2 W Y 1111 **B.MAC**



# **Spanning Tree**

Problem: LAN topologies are usually meshed for *fault* tolerance



Bridging and Backward Learning work on a tree topology
 Broadcast Storm is due to cycles in the topology graph

## **The Spanning Tree Algorithm**

- To get a logical tree topology from a physical mesh one.
- The tree topology is obtained blocking some ports
- A blocked port filters data frame and relays control frames (spanning tree)



## **The Spanning Tree Algorithm**



## **The Spanning Tree Algorithm**

- □ *Root bridge* election
- Each bridge selects a root port
  - Iowest distance to the root bridge
- □ In each LAN a *designated bridge* is chosen.
  - The port interconnecting the designated bridge with its LAN is the designated port
- The root ports and the designated ports are active, the others are blocked.

# **Root Bridge Election**

- □ The first Step is the *Root Bridge* Selection.
- The choice is based on the Bridge ID (64 bits)



The bridge with the <u>lowest</u> Bridge ID is the Root Bridge

## **Root Port Selection**

 Once the *Root Bridge* is elected, <u>each</u> *Bridge* selects the *Root Port* lowest distance to the *Root Bridge* The distance is expressed as a cost through the *Root Path Cost* parameter (it often corresponds to the *number of hops*)

## **Designated Bridge Port Selection**

- A Designated Bridge for each LAN segment is selected. It forwards the frames towards the root Bridge
  - The bridge with minimum distance towards the Root Bridge becomes the Designated Bridge (if equivalent, lowest Bridge ID criteria)
- The Designated Bridge is connected to the LAN segment through the Designated Bridge Port

All the ports of a Root Bridge are Designated Bridge Ports !

# **Spanning Tree: An Example**



Before the ST algorithm

# **Spanning Tree: An Example**



After the ST algorithm

# Logical Bridging Graphs

