

KD Ubiq Summer School 2008

Behavioural Modelling of a Grid System

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Overview of the Tutorial

Autonomic Computing

- ▶ ML & DM for Systems:
Introduction, motivations, applications
- ▶ Zoom on an application: Performance management

Autonomic Grid

- ▶ EGEE: Enabling Grids for e-Science in Europe
- ▶ Data acquisition, Logging and Bookkeeping files
- ▶ (change of) Representation, Dimensionality reduction

Modelling Jobs

- ▶ Exploratory Analysis and Clustering
- ▶ Standard approaches, stability, affinity propagation

Part 2

- ▶ Grid Systems

Presentation of EGEE, Enabling Grids for e-Science in Europe

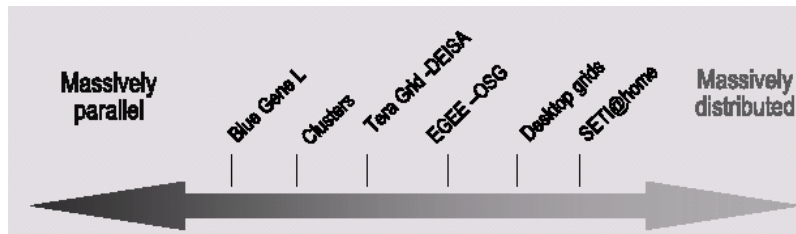
- ▶ Acquiring the data

The grid observatory

- ▶ Preparation of the data

- ▶ Functional dependencies
- ▶ Dimensionality reduction
- ▶ Propositionalization

Computing Systems: The landscape



parallel

- ▶ homogeneous soft and hard resources
 - ▶ dedicated
 - ▶ static
 - ▶ controlled
- ▶ reduced software stack
- ▶ no built-in fault tolerance

distributed

- ▶ heterogeneous soft and hard resources
 - ▶ shared
 - ▶ dynamic
 - ▶ aggregated
- ▶ middleware
- ▶ faults: the norm

Storage and Computation have to be distributed



EGEE: Enabling Grids for E-Science in Europe



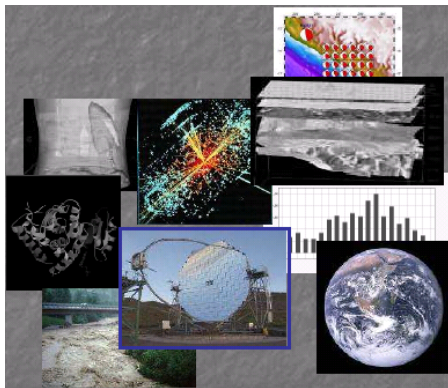
EGEE, 2

- ▶ Infrastructure project started in 2001 → FP6 and FP7
- ▶ Large scale, production quality grid
- ▶ Core node: Lab. Accélérateur Linéaire, Université Paris-Sud
- ▶ 240 partners, 41,000 CPUs, all over the world
- ▶ 5 Peta bytes storage
- ▶ 24×7 , 20 K concurrent jobs
- ▶ Web: www.eu-egee.org

Storage as important as CPU

Applications

- ▶ High energy physics
- ▶ Life sciences
- ▶ Astrophysics
- ▶ Computational chemistry
- ▶ Earth sciences
- ▶ Financial simulation
- ▶ Fusion
- ▶ Multimedia
- ▶ Geophysics



Autonomic Grid

Requisite: The Grid Observatory

- ▶ Cluster in the EGEE-III proposal 2008-2010
- ▶ Data collection and publication: filtering, clustering

Workload management

- ▶ Models of the grid dynamics
- ▶ Models of requirements and middleware reaction: time series and beyond
- ▶ Utility based-scheduling, local and global: MAB problem
- ▶ Policy evaluations: very large scale optimization

Fault detection and diagnosis

- ▶ Categorization of failure modes from the Logging and Bookkeeping: feature construction, clustering,
- ▶ Abrupt changepoint detection

Autonomic Grid: The Grid Observatory

Data acquisition

- ▶ Data have not been stored with DM in mind never
- ▶ Data [partially] automatically generated for EGEE services here
 - ▶ redundant
 - ▶ little expert help

It's no longer: the expert feeds the machine with data. Rather, machines feed machines... J. Gama

Data preprocessing

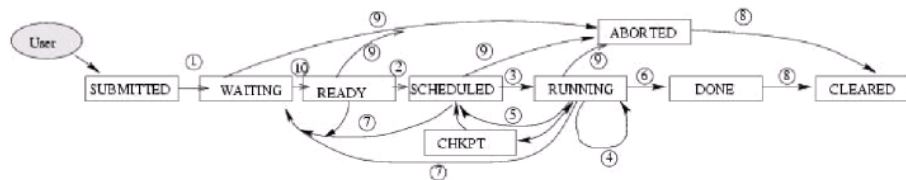
- ▶ 80% of the human cost
- ▶ Governs the quality of the output

The grid system and the data

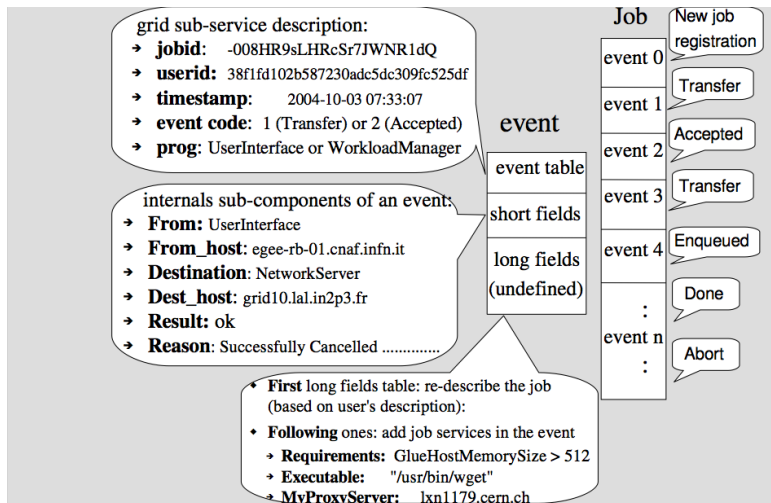
The Workload Management System

- ▶ **User Interface** User submits job description and requirements, and gets the results
- ▶ **Resource Broker** Decides Computing Element
- ▶ **Job Submission Service** Submits to CE and Checks
- ▶ **Logging and Bookkeeping Service** Archive the data

Job Lifecycle



The data



Data Tables

Events

jobid	event	code	host	time_stamp	arrived	level
---BrI1BgbIqkwtzsqGfma	0	17	atlfarm008.mi.infn.it	2004-09-17 16:17:48	2004-09-17 16:17:49	8
---BrI1BgbIqkwtzsqGfma	1	1	atlfarm008.mi.infn.it	2004-09-17 16:17:48	2004-09-17 16:17:49	8
---BrI1BgbIqkwtzsqGfma	2	2	lxb0728.cern.ch	2004-09-17 16:17:53	2004-09-17 16:17:53	8
---BrI1BgbIqkwtzsqGfma	3	4	lxb0728.cern.ch	2004-09-17 16:18:00	2004-09-17 16:18:01	8
---BrI1BgbIqkwtzsqGfma	4	1	atlfarm008.mi.infn.it	2004-09-17 16:18:00	2004-09-17 16:18:01	8
---BrI1BgbIqkwtzsqGfma	5	5	lxb0728.cern.ch	2004-09-17 16:18:01	2004-09-17 16:18:01	8

Short Fields

0	JOBTYPE	SIMPLE
0	NS	lxb0728.cern.ch:7772
0	NSUBJOBS	0
0	SEED	uLU0BArndV98041PLThJ5Q
0	SEQCODE	UI=000001:NS=0000000000:WM=000000:BH=0000000000:JSS=000000:LM=000000:LRMS=000000:APP=000000
0	SRC_INSTANCE	
1	DESTINATION	NetworkServer
1	DEST_HOST	lxb0728.cern.ch
1	DEST_INSTANCE	lxb0728.cern.ch:7772
1	DEST_JOBID	
1	REASON	
1	RESULT	START
1	SEQCODE	UI=000002:NS=0000000000:WM=000000:BH=0000000000:JSS=000000:LM=000000:LRMS=000000:APP=000000
1	SRC_INSTANCE	
2	FROM	UserInterface
2	FROM_HOST	lxb0728.cern.ch
2	FROM_INSTANCE	
2	LOCAL_JOBID	
2	SEQCODE	UI=000003:NS=0000000001:WM=000000:BH=0000000000:JSS=000000:LM=000000:LRMS=000000:APP=000000
2	SRC_INSTANCE	7772
3	QUEUE	/var/edgwl/workload_manager/input.fl
3	REASON	
3	RESULT	OK
3	SEQCODE	UI=000003:NS=0000000003:WM=000000:BH=0000000000:JSS=000000:LM=000000:LRMS=000000:APP=000000
3	SRC_INSTANCE	

Data Tables

Long Fields (4Gb)

jobid	event	name	value
---	BrI1BgbiqkwtzsqGfmA	0	JDL [[requirements = ((((Member("VO-atlas-lcg-release-0.0.2", other.GlueHostApplicationSoftwareRunTimeEnvironment)) && Member("VO-atlas-release-8.0.5", other.GlueHostApplicationSoftwareRunTimeEnvironment)) && (other.GlueCEPolicyMaxCPUTime >= (Member("LCG-2\1_0", other.GlueHostApplicationSoftwareRunTimeEnvironment) ? (36000000 / 60) : 36000000) / other.GlueHostBenchmarkSI00)) && (other.GlueHostNetworkAdapterOutboundIP == true)) && (other.GlueHostMainMemoryRAMSize >= 512); RetryCount = 0; edg_jobid = "https://lxb0728.cern.ch:9000/---BrI1BgbiqkwtzsqGfmA"; Arguments = "dc2.003048.evgen.H4_170_WW_00002.pool.root dc2.003048.simul.H4_170_WW_00208.pool.root.2 -6 6 50 350 208"; Environment = { "LEXOR_WRAPPER_LOG=lexor_wrapper.log", "LEXOR_STAGEOUT_MAXATTEMPT=5", "LEXOR_STAGEOUT_INTERVAL=60", "LEXOR_LCG_GFAL_INFOSYS=lxb2011.cern.ch:2170", "LEXOR_T_RELEASE=8.0.5", "LEXOR_T_PACKAGE=8.0.5.6/JobTransforms", "LEXOR_T_BASEDIR=JobTransforms-08-00-05-06", "LEXOR_TRANSFORMATION=share/dc2.g4sim.trf", "LEXOR_STAGEIN_LOG=dq_233387_stagein.log", "LEXOR_STAGEIN_SCRIPT=dq_233387_stagein.sh", "LEXOR_STAGEOUT_LOG=dq_233387_stageout.log", "LEXOR_STAGEOUT_SCRIPT=dq_233387_stageout.sh" }; MyProxyServer = "lxb0727.cern.ch"; JobType = "normal"; Executable = "lexor_wrap.sh"; StdOutput = "dc2.003048.simul.H4_170_WW_00208.job.log.2"; OutputSandbox = { "metadata.xml", "lexor_wrapper.log", "dq_233387_stagein.log", "dq_233387_stageout.log", "dc2.003048.simul.H4_170_WW_00208.job.log.2" }; VirtualOrganisation = "atlas"; rank = (other.GlueCEStateEstimatedResponseTime > 999) ? -(other.GlueCEStateEstimatedResponseTime) : -(other.GlueCEStateRunningJobs); Type = "job"; StdError = "dc2.003048.simul.H4_170_WW_00208.job.log.2"; DefaultRank = -other.GlueCEStateEstimatedResponseTime; InputSandbox = { "/home/negri/windmill-0.9.15/lexor/inputsandbox/lexor_wrap.sh", "/home/negri/windmill-0.9.15/lexor/inputsandbox/dqlcg.py", "/home/negri/windmill-0.9.15/lexor/inputsandbox/edgrmpi.sh", "/home/negri/windmill-0.9.15/lexor/inputsandbox/dqrep.pl", "/home/negri/windmill-0.9.15/lexor/inputsandbox/run_dqlcg.sh", "/tmp/lexor/negri/dq_233387_stagein.sh", "/tmp/lexor/negri/dq_233387_stageout.sh" }]

Preparation of the data

1. Functional dependencies
2. Dimensionality reduction curse of dimensionality
 - ▶ Principal Component Analysis
 - ▶ Random Projection
 - ▶ Non linear Dimensionality Reduction
3. Propositionalization

Functional dependency

Definition

Given attributes X and X' , X' depends on X on \mathcal{E} ($X' \prec X$) iff

$$\exists f : \text{dom}(X') \mapsto \text{dom}(X) \text{ s.t. } \forall i = 1 \dots N, X(\mathbf{x}_i) = f(X'(\mathbf{x}_i))$$

Examples

- ▶ $X' = \text{City code}$, $X = \text{City name}$
- ▶ $X' = \text{Machine name}$, $X = \text{IP}$
- ▶ $X' = \text{Job ID}$, $X = \text{User ID}$

Why removing FD ?

- ▶ Curse of dimensionality
- ▶ Biased distance

Functional dependency, 2

Trivial cases

$$\#dom(X) = \#dom(X') = N \text{ number of examples}$$

Algorithm

► Size:

$$(X' \prec X) \Rightarrow \#dom(X) \leq \#dom(X')$$

► Sample

Repeat

 Select $v \in dom(X')$

$\mathcal{E}_v = \text{select } \mathbf{x}_i \text{ where } X'(\mathbf{x}_i) = v$

 Define $X(\mathcal{E}_v) = \{w \in dom(X), \exists x \in \mathcal{E}_v / X(x) = w\}$

 If $(\#X(\mathcal{E}_v) > 1)$ return false

Until stop

return true

Dimensionality Reduction – Intuition

Degrees of freedom

- ▶ Image: 4096 pixels; but not independent
- ▶ Robotics: ($\#$ camera pixels + $\#$ infra-red) \times time; but not independent

Goal

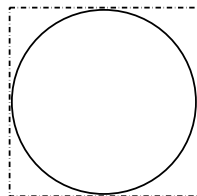
Find the (low-dimensional) structure of the data:

- ▶ Images
- ▶ Robotics
- ▶ Genes

Dimensionality Reduction

In high dimensions

- ▶ Everybody lives in the corners of the space
- ▶ Volume of Sphere $V_n = \frac{2\pi r^2}{n} V_{n-2}$
- ▶ All points are far from each other



Approaches

- ▶ Linear dimensionality reduction
 - ▶ Principal Component Analysis
 - ▶ Random Projection
- ▶ Non-linear dimensionality reduction

Criteria

- ▶ Complexity/Size
- ▶ Prior knowledge

e.g., relevant distance

Linear Dimensionality Reduction

Training set

unsupervised

$$\mathcal{E} = \{(\mathbf{x}_k), \mathbf{x}_k \in \mathbb{R}^D, k = 1 \dots N\}$$

Projection from \mathbb{R}^D onto \mathbb{R}^d

$$\mathbf{x} \in \mathbb{R}^D \rightarrow \begin{aligned} h(\mathbf{x}) &\in \mathbb{R}^d, \quad d \ll D \\ h(\mathbf{x}) &= A\mathbf{x} \end{aligned}$$

$$\text{s.t. minimize } \sum_{k=1}^N \|\mathbf{x}_k - h(\mathbf{x}_k)\|^2$$

Principal Component Analysis

Covariance matrix S

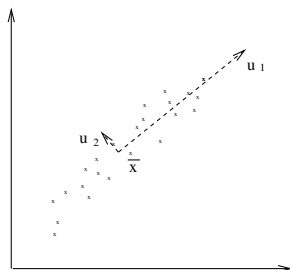
Mean

$$\mu_i = \frac{1}{N} \sum_{k=1}^N X_i(\mathbf{x}_k)$$

$$S_{ij} = \frac{1}{N} \sum_{k=1}^N (X_i(\mathbf{x}_k) - \mu_i)(X_j(\mathbf{x}_k) - \mu_j)$$

symmetric \Rightarrow can be diagonalized

$$S = U\Delta U' \quad \Delta = \text{Diag}(\lambda_1, \dots, \lambda_D)$$



Thm: Optimal projection in dimension d

projection on the first d eigenvectors of S

Let u_i the eigenvector associated to eigenvalue λ_i $\lambda_i > \lambda_{i+1}$

$$h : \mathbb{R}^D \mapsto \mathbb{R}^d, h(\mathbf{x}) = \langle \mathbf{x}, u_1 \rangle u_1 + \dots + \langle \mathbf{x}, u_d \rangle u_d$$

Sketch of the proof

1. Maximize the variance of $h(\mathbf{x}) = A\mathbf{x}$

$$\sum_k \|\mathbf{x}_k - h(\mathbf{x}_k)\|^2 = \sum_k \|\mathbf{x}_k\|^2 - \sum_k \|h(\mathbf{x}_k)\|^2$$

$$\text{Minimize } \sum_k \|\mathbf{x}_k - h(\mathbf{x}_k)\|^2 \Rightarrow \text{Maximize } \sum_k \|h(\mathbf{x}_k)\|^2$$

$$\text{Var}(h(\mathbf{x})) = \frac{1}{N} \left(\sum_k \|h(\mathbf{x}_k)\|^2 - \left\| \sum_k h(\mathbf{x}_k) \right\|^2 \right)$$

As

$$\left\| \sum_k h(\mathbf{x}_k) \right\|^2 = \left\| A \sum_k \mathbf{x}_k \right\|^2 = N^2 \|A\mu\|^2$$

where $\mu = (\mu_1, \dots, \mu_D)$.

Assuming that \mathbf{x}_k are centered ($\mu_i = 0$) gives the result.

Sketch of the proof, 2

2. Projection on eigenvectors u_i of S

Assume $h(\mathbf{x}) = \mathbf{Ax} = \sum_{i=1}^d \langle \mathbf{x}, v_i \rangle v_i$ and show $v_i = u_i$.

$$\text{Var}(AX) = (AX)(AX)' = A(XX')A' = ASA' = A(U\Delta U')A'$$

Consider $d = 1$, $v_1 = \sum w_i u_i$

$$\sum w_i^2 = 1$$

remind $\lambda_i > \lambda_{i+1}$

$$\text{Var}(AX) = \sum \lambda_i w_i^2$$

maximized for $w_1 = 1, w_2 = \dots = w_N = 0$

that is, $v_1 = u_1$.

Principal Component Analysis, Practicalities

Data preparation

- ▶ Mean centering the dataset

$$\begin{aligned}\mu_i &= \frac{1}{N} \sum_{k=1}^N X_i(\mathbf{x}_k) \\ \sigma_i &= \sqrt{\frac{1}{N} \sum_{k=1}^N X_i(\mathbf{x}_k)^2 - \mu_i^2} \\ z_k &= \left(\frac{1}{\sigma_i} (X_i(\mathbf{x}_k) - \mu_i) \right)_{i=1}^D\end{aligned}$$

Matrix operations

- ▶ Computing the covariance matrix

$$S_{ij} = \frac{1}{N} \sum_{k=1}^N X_i(z_k) X_j(z_k)$$

- ▶ Diagonalizing $S = U' \Delta U$
might be not affordable...

Complexity $\mathcal{O}(D^3)$

Random projection

Random matrix

$$A : \mathbb{R}^D \mapsto \mathbb{R}^d \quad A[d, D] \quad A_{i,j} \sim \mathcal{N}(0, 1)$$

define

$$h(\mathbf{x}) = \frac{1}{\sqrt{d}} A \mathbf{x}$$

Property: h preserves the norm in expectation

$$E[\|h(\mathbf{x})\|^2] = \|\mathbf{x}\|^2$$

With high probability

$$1 - 2\exp\{-(\varepsilon^2 - \varepsilon^3)\frac{d}{4}\}$$

$$(1 - \varepsilon)\|\mathbf{x}\|^2 \leq \|h(\mathbf{x})\|^2 \leq (1 + \varepsilon)\|\mathbf{x}\|^2$$

Random projection

Proof

$$h(\mathbf{x}) = \frac{1}{\sqrt{d}} A \mathbf{x}$$

$$\begin{aligned} E(\|h(\mathbf{x})\|^2) &= \frac{1}{d} E \left[\sum_{i=1}^d \left(\sum_{j=1}^D A_{i,j} X_j(\mathbf{x}) \right)^2 \right] \\ &= \frac{1}{d} \sum_{i=1}^d E \left[\left(\sum_{j=1}^D A_{i,j} X_j(\mathbf{x}) \right)^2 \right] \\ &= \frac{1}{d} \sum_{i=1}^d \sum_{j=1}^D E[A_{i,j}^2] E[X_j(\mathbf{x})^2] \\ &= \frac{1}{d} \sum_{i=1}^d \sum_{j=1}^D \frac{\|\mathbf{x}\|^2}{D} \\ &= \|\mathbf{x}\|^2 \end{aligned}$$

Random projection, 2

Johnson Lindenstrauss Lemma

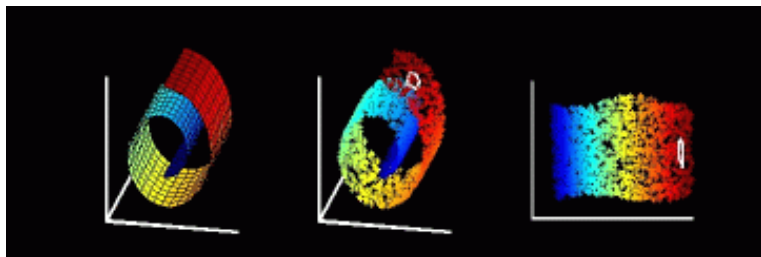
For $d > \frac{9 \ln N}{\varepsilon^2 - \varepsilon^3}$, with high probability

$$(1 - \varepsilon) \|\mathbf{x}_i - \mathbf{x}_j\|^2 \leq \|h(\mathbf{x}_i) - h(\mathbf{x}_j)\|^2 \leq (1 + \varepsilon) \|\mathbf{x}_i - \mathbf{x}_j\|^2$$

More:

<http://www.cs.yale.edu/clique/resources/RandomProjectionMethod.pdf>

Non-Linear Dimensionality Reduction



Conjecture

Examples live in a manifold of dimension $d \ll D$

Goal: consistent projection of the dataset onto \mathbb{R}^d

Consistency:

- ▶ Preserve the structure of the data
- ▶ e.g. preserve the distances between points

Multi-Dimensional Scaling

Position of the problem

- ▶ Given $\{\mathbf{x}_1, \dots, \mathbf{x}_N, \mathbf{x}_i \in \mathbb{R}^D\}$
- ▶ Given $sim(\mathbf{x}_i, \mathbf{x}_j) \in \mathbb{R}^+$
- ▶ Find projection Φ onto \mathbb{R}^d

$$\begin{aligned}x \in \mathbb{R}^D &\rightarrow \Phi(x) \in \mathbb{R}^d \\sim(\mathbf{x}_i, \mathbf{x}_j) &\sim sim(\Phi(\mathbf{x}_i), \Phi(\mathbf{x}_j))\end{aligned}$$

Optimisation

Define X , $X_{i,j} = sim(\mathbf{x}_i, \mathbf{x}_j)$; X^Φ , $X_{i,j}^\Phi = sim(\Phi(\mathbf{x}_i), \Phi(\mathbf{x}_j))$

Find Φ minimizing $\|X - X^\Phi\|$

Rq : Linear Φ = Principal Component Analysis

But linear MDS does not work: preserves all distances, while

only *local* distances are meaningful

Non-linear projections

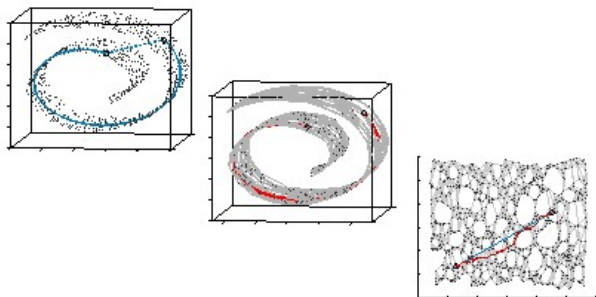
Approaches

- ▶ Reconstruct global structures from local ones and find global projection
- ▶ Only consider local structures

Isomap

LLE

Intuition: locally, points live in \mathbb{R}^d



Isomap

Tenenbaum, da Silva, Langford 2000

<http://isomap.stanford.edu>

Estimate $d(x_i, x_j)$

- ▶ Known if \mathbf{x}_i and \mathbf{x}_j are close
- ▶ Otherwise, compute the shortest path between \mathbf{x}_i and \mathbf{x}_j
geodesic distance (dynamic programming)

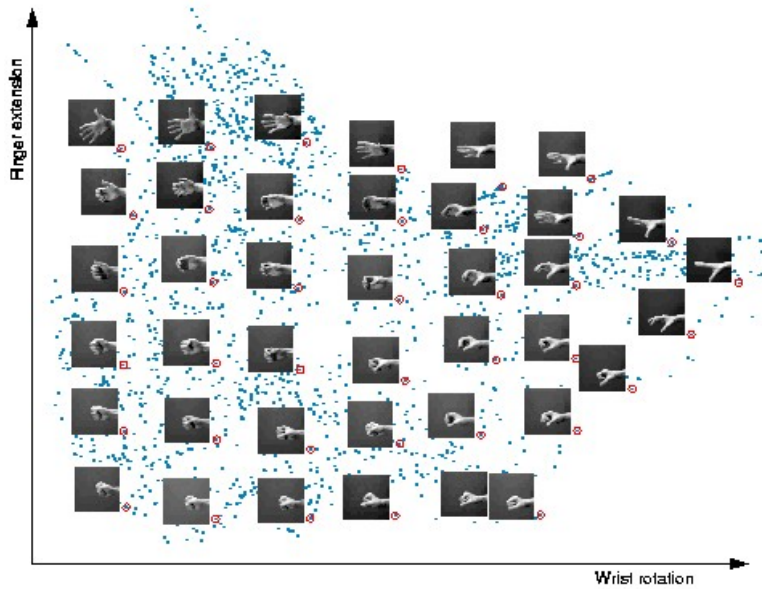
Requisite

If data points sampled in a convex subset of \mathbb{R}^d ,
then geodesic distance \sim Euclidean distance on \mathbb{R}^d .

General case

- ▶ Given $d(\mathbf{x}_i, \mathbf{x}_j)$, estimate $\langle \mathbf{x}_i, \mathbf{x}_j \rangle$
- ▶ Project points in \mathbb{R}^d

Isomap, 2



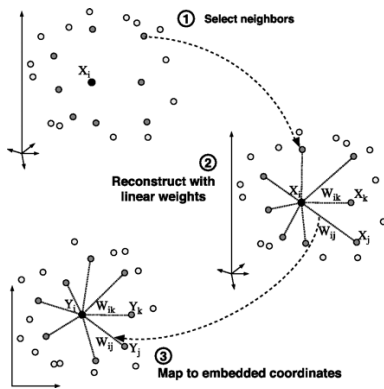
Locally Linear Embedding

Roweis and Saul, 2000

<http://www.cs.toronto.edu/~roweis/lle/>

Principle

- Find local description for each point: depending on its neighbors



Local Linear Embedding, 2

Find neighbors

For each \mathbf{x}_i , find its nearest neighbors $\mathcal{N}(i)$

Parameter: number of neighbors

Change of representation

Goal Characterize \mathbf{x}_i wrt its neighbors:

$$\mathbf{x}_i = \sum_{j \in \mathcal{N}(i)} w_{i,j} \mathbf{x}_j \quad \text{with} \quad \sum_{j \in \mathcal{N}(i)} w_{ij} = 1$$

Property: invariance by translation, rotation, homothety

How Compute the local covariance matrix:

$$C_{j,k} = \langle \mathbf{x}_j - \mathbf{x}_i, \mathbf{x}_k - \mathbf{x}_i \rangle$$

Find vector w_i s.t. $Cw_i = 1$

Local Linear Embedding, 3

Algorithm

Local description: Matrix W such that

$$\sum_j w_{i,j} = 1$$

$$W = \underset{W}{\operatorname{argmin}} \left\{ \sum_{i=1}^N \left\| \mathbf{x}_i - \sum_j w_{i,j} \mathbf{x}_j \right\|^2 \right\}$$

Projection: Find $\{z_1, \dots, z_n\}$ in \mathbb{R}^d minimizing

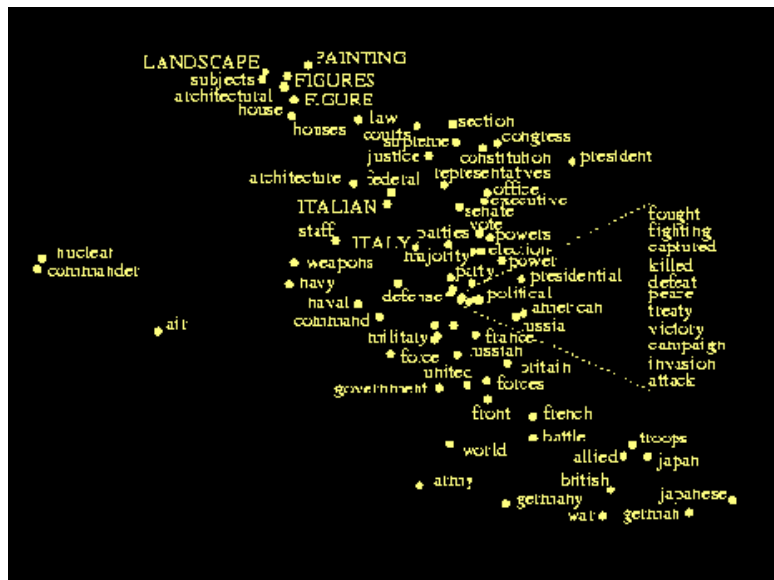
$$\sum_{i=1}^N \left\| z_i - \sum_j w_{i,j} z_j \right\|^2$$

Minimize $((I - W)Z)'((I - W)Z) = Z'(I - W)'(I - W)Z$

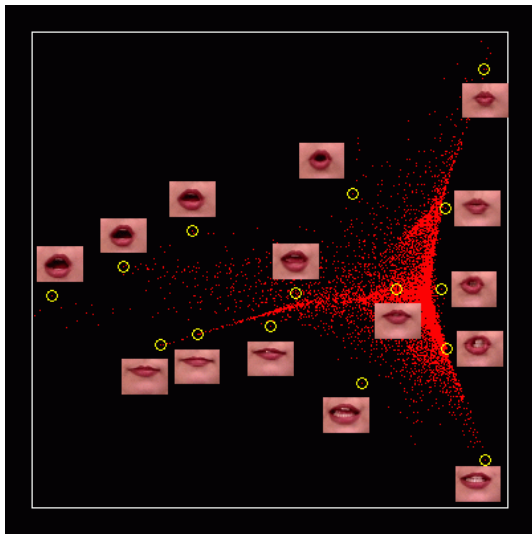
Solutions: vectors z_i are eigenvectors of $(I - W)'(I - W)$

- ▶ Keeping the d eigenvectors with lowest eigenvalues > 0

Example, Texts



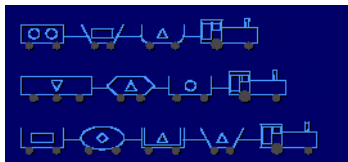
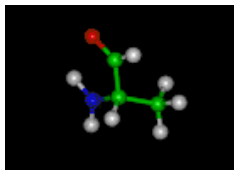
Example, Images



LLE

Propositionalization

Relational domains



Relational learning

PROS

Use domain knowledge

CONS

Covering test \equiv subgraph matching

Inductive Logic Programming

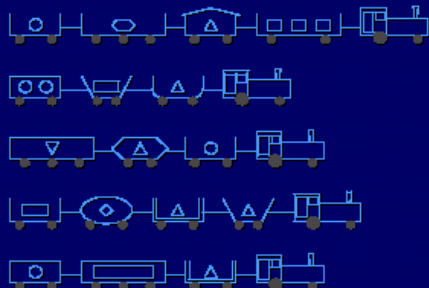
Data Mining
exponential complexity

Getting back to propositional representation: **propositionalization**

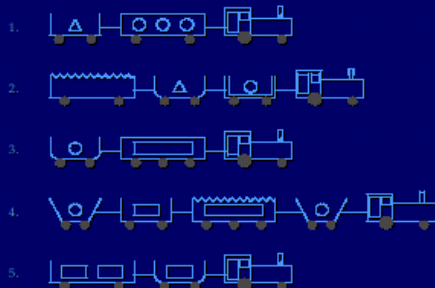
West - East trains

Michalski 1983

1. TRAINS GOING EAST



2. TRAINS GOING WEST



Propositionalization

Linus (ancestor)

Lavrac et al, 94

$West(a) \leftarrow Engine(a, b), first_wagon(a, c), roof(c), load(c, square, 3)...$
 $West(a') \leftarrow Engine(a', b'), first_wagon(a', c'), load(c', circle, 1)...$

West	Engine(X)	First Wagon(X,Y)	Roof(Y)	Load ₁ (Y)	Load ₂ (Y)
a	b	c	yes	square	3
a'	b'	c'	no	circle	1

Each column: a role predicate, where the predicate is determinate linked to former predicates (left columns) with a single instantiation in every example

Propositionalization

Stochastic propositionalization

Kramer, 98

Construct random formulas \equiv boolean features

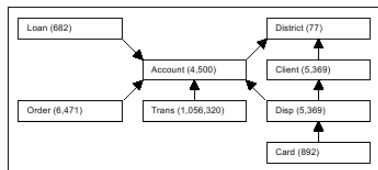
SINUS – RDS

<http://www.cs.bris.ac.uk/home/rawles/sinus>

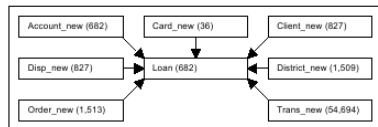
<http://labe.felk.cvut.cz/~zelezny/rsd>

- ▶ Use modes (user-declared) `modeb(2,hasCar(+train,-car))`
- ▶ Thresholds on number of variables, depth of predicates...
- ▶ Pre-processing (feature selection)

Propositionalization



DB Schema



Propositionalization

RELAGGS

Database aggregates

- ▶ average, min, max, of numerical attributes
- ▶ number of values of categorical attributes

Going ubiquitous in Data Preparation

Principles: same as usual

- ▶ Act locally
- ▶ Think globally

The local level

- ▶ An ideal feature \equiv a good hypothesis
- ▶ What is a promising hypothesis ?
 - ▶ Behaves well on (part of) the data
 - ▶ Is not trivial

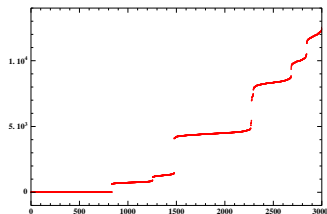
Going ubiquitous in Data Preparation, 2

What is a good behaviour?

- ▶ Showing regularities
- ▶ Locally constant

How to test triviality?

- ▶ Syntactical analysis:
 $xy - yx = 0$
- ▶ Statistical triviality:
 - ▶ Test on random data
 - ▶ Test on permutations of the data



Going ubiquitous in Data Preparation, 3

Internally: an optimization problem

- ▶ Define bins
- ▶ Compute histogram, associated quantity of information
- ▶ Compare histograms on real data / on random data

Externally: an optimization problem

- ▶ Upon receiving a new feature
- ▶ Check whether this is relevant to your data
- ▶ Check whether this brings new information