

NeuroComp

Machine Learning and Validation

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<http://tao.lri.fr/tiki-index.php>

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Validation, the questions

1. What is the result ?
2. My results look good. Are they ?
3. Does my system outperform yours ?
4. How to set up my system ?

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Position of the problem

- Background notations

- Difficulties

- The learning process

- The villain

Validation

- Performance indicators

- Estimating an indicator

- Testing a hypothesis

- Comparing hypotheses

Validation Campaign

- The point of parameter setting

- Racing

- Expected Global Improvement

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Supervised Machine Learning

Context

World \rightarrow instance $\mathbf{x}_i \rightarrow$ Oracle
 \downarrow
 y_i



Input: Training set $\mathcal{E} = \{(\mathbf{x}_i, y_i), i = 1 \dots n, \mathbf{x}_i \in \mathcal{X}, y_i \in \mathcal{Y}\}$

Output: Hypothesis $h : \mathcal{X} \mapsto \mathcal{Y}$

Criterion: few mistakes (details later)

Definitions

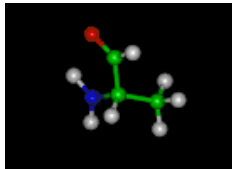
Example

- ▶ row : example/ case
- ▶ column : feature/variables/attribute
- ▶ attribute : class/label

age	employe	education	educ	marital	...	job	relation	race	gender	hour	country	wealth
39	State_gov	Bachelors	13	Never_mar	...	Adm_clerk	Not_in_fam	White	Male	40	United_States	poor
51	Self_employ	Bachelors	13	Married	...	Exec_manager	Husband	White	Male	13	United_States	poor
39	Private	HS_grad	9	Divorced	...	Handlers_cleaners	Not_in_fam	White	Male	40	United_States	poor
54	Private	11th	7	Married	...	Handlers_cleaners	Husband	Black	Male	40	United_States	poor
28	Private	Bachelors	13	Married	...	Prof_spec	Wife	Black	Female	40	Cuba	poor
38	Private	Masters	14	Married	...	Exec_manager	Wife	White	Female	40	United_States	poor
50	Private	9th	5	Married_spl	...	Other_serv	Not_in_fam	Black	Female	16	Jamaica	poor
52	Self_employ	HS_grad	9	Married	...	Exec_manager	Husband	White	Male	45	United_States	rich
31	Private	Masters	14	Never_mar	...	Prof_spec	Not_in_fam	White	Female	50	United_States	rich
42	Private	Bachelors	13	Married	...	Exec_manager	Husband	White	Male	40	United_States	rich
37	Private	Some_college	10	Married	...	Exec_manager	Husband	Black	Male	80	United_States	rich
30	State_gov	Bachelors	13	Married	...	Prof_spec	Husband	Asian	Male	40	India	rich
24	Private	Bachelors	13	Never_mar	...	Adm_clerk	Own_child	White	Female	30	United_States	poor
33	Private	Assoc_degree	12	Never_mar	...	Sales	Not_in_fam	Black	Male	50	United_States	poor
41	Private	Assoc_degree	11	Married	...	Craft_repair	Husband	Asian	Male	40	MissingValue	rich
34	Private	7th_8th	4	Married	...	Transportation	Husband	Amer_Indian	Male	45	Mexico	poor
26	Self_employ	HS_grad	9	Never_mar	...	Farming_fishing	Own_child	White	Male	35	United_States	poor
33	Private	HS_grad	9	Never_mar	...	Machine_op	Unmarried	White	Male	40	United_States	poor
38	Private	11th	7	Married	...	Sales	Husband	White	Male	50	United_States	poor
44	Self_employ	Masters	14	Divorced	...	Exec_manager	Unmarried	White	Female	45	United_States	rich
41	Private	Doctorate	16	Married	...	Prof_spec	Husband	White	Male	60	United_States	rich
:	:	:	:	:	:	:	:	:	:	:	:	:

Instance space \mathcal{X}

- ▶ Propositional :
 $\mathcal{X} \equiv \mathbb{R}^d$
- ▶ Relational : ex. chemistry.



molecule: alanine

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Difficulty factors

Quality of examples / of representation

- + Relevant features Feature extraction
- Not enough data
- Noise ; missing data
- Structured data : spatio-temporal, relational, textual, videos ..

Distribution of examples

- + Independent, identically distributed examples
- Other: robotics; data stream; heterogeneous data

Prior knowledge

- + Constraints on sought solution
- + Criteria; loss function

Difficulty factors, 2

Learning criterion

- + Convex function: a single optimum
- ↘ Complexity : n , $n \log n$, n^2
- Combinatorial optimization

Scalability

What is your agenda ?

- ▶ Prediction performance
- ▶ Causality
- ▶ INTELLIGIBILITY
- ▶ Simplicity
- ▶ Stability
- ▶ Interactivity, visualisation

Difficulty factors, 3

Crossing the chasm

- ▶ There exists no *killer algorithm*
- ▶ Few general recommendations about algorithm selection

Performance criteria

- ▶ Consistency

When number n of examples goes to ∞
and the target concept h^* is in \mathcal{H}
Algorithm finds \hat{h}_n , with

$$\lim_{n \rightarrow \infty} h_n = h^*$$

- ▶ Convergence speed

$$||h^* - h_n|| = \mathcal{O}(1/n), \mathcal{O}(1/\sqrt{n}), \mathcal{O}(1/\ln n)$$

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Context

Related approaches

- ▶ Data Mining, KDD

criteria

scalability

- ▶ Statistics and data analysis

Model selection and fitting; hypothesis testing

- ▶ Machine Learning

Prior knowledge; representations; distributions

- ▶ Optimisation

well-posed / ill-posed problems

- ▶ Computer Human Interface

No ultimate solution: a dialog

- ▶ High performance computing

Distributed data; privacy

Methodology

Phases

1. Collect data expert, DB
2. Clean data stat, expert
3. Select data stat, expert
4. Data Mining / Machine Learning
 - ▶ Description *what is in data ?*
 - ▶ Prediction *Decide for one example*
 - ▶ Agregate *Take a global decision*
5. Visualisation chm
6. Evaluation stat, chm
7. Collect new data expert, stat

An interactive process

depending on expectations, data, prior knowledge, current results

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Input

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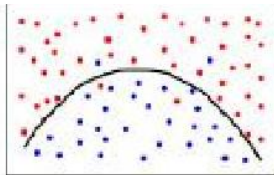
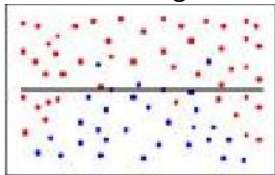
Tasks

- ▶ Select hypothesis space \mathcal{H}
- ▶ Assess hypothesis $h \in \mathcal{H}$
- ▶ Find best hypothesis h^*

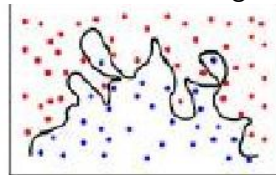
$score(h)$

What is the point ?

Underfitting



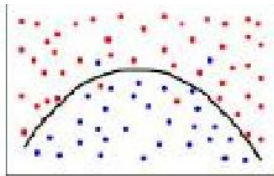
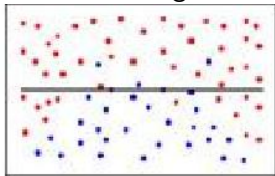
Overfitting



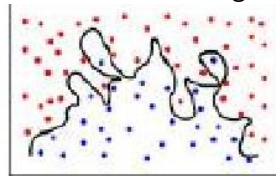
The point is not to be perfect on the training set

What is the point ?

Underfitting

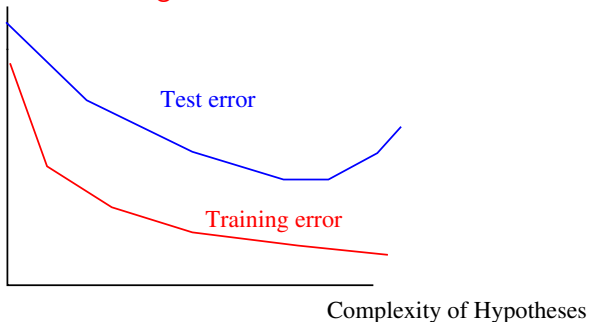


Overfitting



The point is not to be perfect on the training set

The villain: overfitting



What is the point ?

Prediction good on future instances

Necessary condition:

Future instances must be similar to training instances
“identically distributed”

Minimize (cost of) errors
not all mistakes are equal.

$$\ell(y, h(x)) \geq 0$$

Error: theoretical approach

Minimize expectation of error cost

$$\text{Minimize } E[\ell(y, h(x))] = \int_{\mathbf{X} \times \mathbf{Y}} \ell(y, h(x)) p(x, y) dx dy$$

Error: theoretical approach

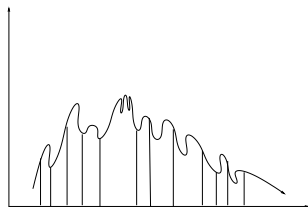
Minimize expectation of error cost

$$\text{Minimize } E[\ell(y, h(x))] = \int_{X \times Y} \ell(y, h(x)) p(x, y) dx dy$$

Principle

Si h “is well-behaved” on \mathcal{E} , and h is “sufficiently regular” h will be well-behaved in expectation.

$$E[F] \leq \frac{\sum_{i=1}^n F(x_i)}{n} + c(F, n)$$



Classification, Problem posed

INPUT

$$\sim P(x, y)$$

$$\mathcal{E} = \{(x_i, y_i), x_i \in \mathcal{X}, y_i \in \{0, 1\}, i = 1 \dots n\}$$

HYPOTHESIS SPACE

SEARCH SPACE

$$\mathcal{H} \quad h : \mathcal{X} \mapsto \{0, 1\}$$

LOSS FUNCTION

$$\ell : \mathcal{Y} \times \mathcal{Y} \mapsto \mathbb{R}$$

OUTPUT

$$h^* = \arg \max \{score(h), h \in \mathcal{H}\}$$

Classification, criteria

Generalisation error

$$Err(h) = E[\ell(y, h(x))] = \int \ell(y, h(x)) dP(x, y)$$

Empirical error

$$Err_e(h) = \frac{1}{n} \sum_{i=1}^n \ell(y_i, h(x_i))$$

Bound

risk minimization

$$Err(h) < Err_e(h) + \mathcal{F}(n, d(\mathcal{H}))$$

$$d(\mathcal{H}) = \text{VC-dimension of } \mathcal{H}$$

Dimension of Vapnik Cervonenkis

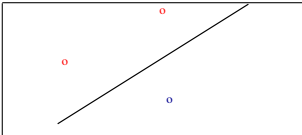
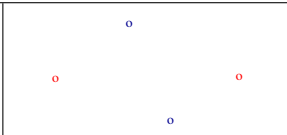
Principle Given hypothesis space $\mathcal{H}: \mathcal{X} \mapsto \{0, 1\}$ Given n points x_1, \dots, x_n in \mathcal{X} .

If, $\forall (y_i)_{i=1}^n \in \{0, 1\}^n, \exists h \in \mathcal{H} / h(x_i) = y_i$,
 \mathcal{H} shatters $\{x_1, \dots, x_n\}$

Example: $\mathcal{X} = \mathbb{R}^p$

$d(\text{hyperplanes in } \mathbb{R}^p) = p + 1$

WHY: if \mathcal{H} shatters \mathcal{E} , \mathcal{E} doesn't tell anything

	
3 pts shattered by a line	4 points, non shattered

Definition

$$d(\mathcal{H}) = \max\{n / \exists (x_1, \dots, x_n) \text{ shattered by } \mathcal{H}\}$$

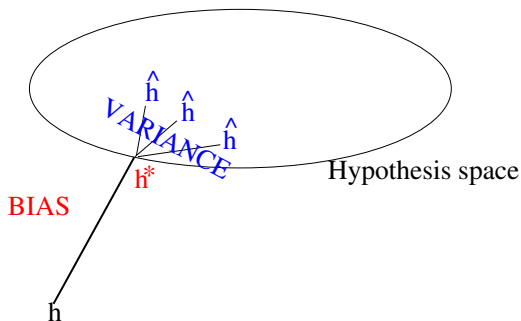
Classification: Ingredients of error

Bias

Bias (\mathcal{H}): error of the best hypothesis h^* in \mathcal{H}

Variance

Variance of h_n depending on \mathcal{E}



Optimization

negligible in small scale
takes over in large scale

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Validation: Three questions

Define a good indicator of quality

- ▶ Misclassification cost
- ▶ Area under the ROC curve

Computing an estimate thereof

- ▶ Validation set
- ▶ Cross-Validation
- ▶ Leave one out
- ▶ Bootstrap

Compare estimates: Tests and confidence levels

Which indicator, which estimate: it depends.

Settings

- ▶ Large/few data

Data distribution

- ▶ Dependent/independent examples
- ▶ balanced/imbalanced classes

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Performance indicators

Binary class

- ▶ h^* the truth
- ▶ \hat{h} the learned hypothesis

Confusion matrix

\hat{h} / h^*	1	0	
1	a	b	a + b
0	c	d	c + d
	a + c	b + d	a + b + c + d

Performance indicators, 2

\hat{h} / h^*	1	0	
1	a	b	a + b
0	c	d	c + d
	a + c	b + d	a + b + c + d

- ▶ Misclassification rate $\frac{b+c}{a+b+c+d}$
- ▶ Sensitivity, True positive rate (TP) $\frac{a}{a+c}$
- ▶ Specificity, False negative rate (FN) $\frac{b}{b+d}$
- ▶ Recall $\frac{a}{a+c}$
- ▶ Precision $\frac{a}{a+b}$

Note: always compare to random guessing / baseline alg.

Performance indicators, 3

The Area under the ROC curve

- ▶ ROC: Receiver Operating Characteristics
- ▶ Origin: Signal Processing, Medicine

Principle

$h : X \mapsto \mathbb{R}$ $h(x)$ measures the risk of patient x

h leads to order the examples:

+ + + - + - + + + + - - - + - - - + - - - - - - - - - - - - - - - -

Performance indicators, 3

The Area under the ROC curve

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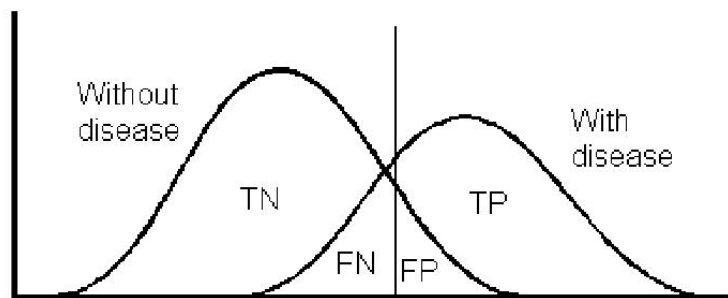
+++ - + - + + + + - - - + - - - - - - - - - - - - - - - -

Given a threshold θ , h yields a classifier: Yes iff $h(x) > \theta$.

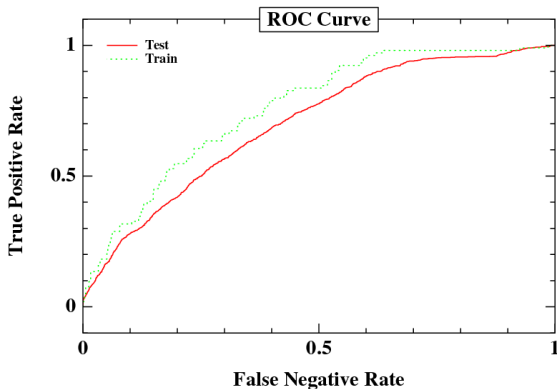
+++ - + - + + + + | - - - + - - - + - - - - - - - - - - - - - - - -

Here, TP $(\theta) = .8$; FN $(\theta) = .1$

ROC



The ROC curve



Ideal classifier: (0 False negative, 1 True positive)

Diagonal (True Positive = False negative) \equiv nothing learned.

ROC Curve, Properties

Properties

ROC depicts the trade-off True Positive / False Negative.

Standard: misclassification cost (Domingos, KDD 99)

$$\text{Error} = \# \text{ false positive} + c \times \# \text{ false negative}$$

In a multi-objective perspective, ROC = Pareto front.

Best solution: intersection of Pareto front with $\Delta(-c, -1)$

ROC Curve, Properties, foll'd

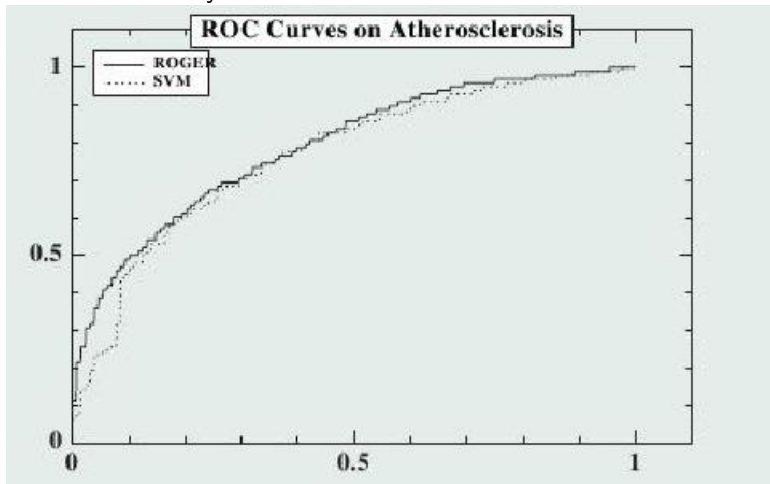
Used to compare learners

Bradley 97

multi-objective-like

insensitive to imbalanced distributions

shows sensitivity to error cost.



Area Under the ROC Curve

Often used to select a learner

Don't ever do this !

Hand, 09

Sometimes used as learning criterion

Mann Whitney Wilcoxon

$$AUC = Pr(h(x) > h(x') | y > y')$$

WHY

Rosset, 04

- ▶ More stable $\mathcal{O}(n^2)$ vs $\mathcal{O}(n)$
- ▶ With a probabilistic interpretation

Clemençon et al. 08

HOW

- ▶ SVM-Ranking
- ▶ Stochastic optimization

Joachims 05; Usunier et al. 08, 09

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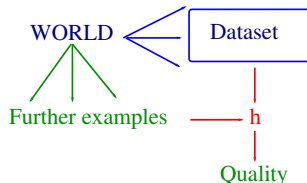
The point of parameter setting

Racing

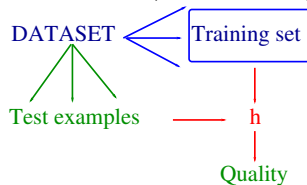
Expected Global Improvement

Validation, principle

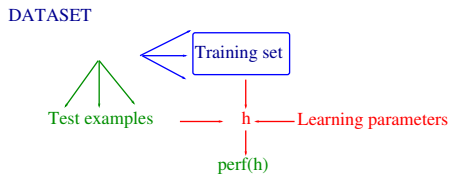
Desired: performance on further instances



Assumption: Dataset is to World, like Training set is to Dataset.



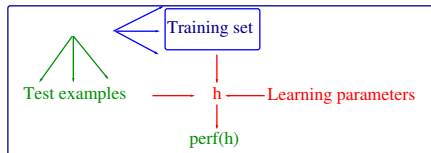
Validation, 2



Unbiased Assessment of Learning Algorithms
T. Scheffer and R. Herbrich, 97

Validation, 2

DATASET

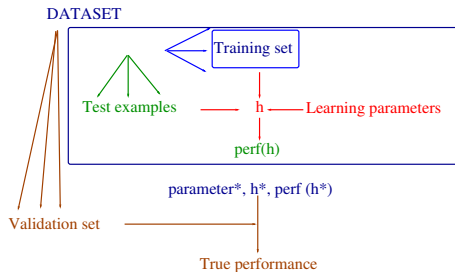


parameter*, h^* , $\text{perf}(h^*)$

Unbiased Assessment of Learning Algorithms

T. Scheffer and R. Herbrich, 97

Validation, 2



Unbiased Assessment of Learning Algorithms

T. Scheffer and R. Herbrich, 97

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Confidence intervals

Definition

Given a random variable X on \mathbb{R} , a $p\%$ -confidence interval is $I \subset \mathbb{R}$ such that

$$\Pr(X \in I) > p$$

Binary variable with probability ϵ

Probability of r events out of n trials:

$$P_n(r) = \frac{n!}{r!(n-r)!} \epsilon^r (1-\epsilon)^{n-r}$$

- ▶ Mean: $n\epsilon$
- ▶ Variance: $\sigma^2 = n\epsilon(1-\epsilon)$

Gaussian approximation

$$P(x) = \frac{1}{\sqrt{2\pi\sigma^2}} \exp^{-\frac{1}{2} \frac{x-\mu}{\sigma}^2}$$

Confidence intervals

Bounds on (true value, empirical value) for n trials, $n > 30$

$$Pr(|\hat{x}_n - x^*| > \underset{z}{1.96} \sqrt{\frac{\hat{x}_n \cdot (1 - \hat{x}_n)}{n}}) < \underset{\varepsilon}{.05}$$

Table

| | | | | | | | |
|---------------|-----|----|------|------|------|------|------|
| z | .67 | 1. | 1.28 | 1.64 | 1.96 | 2.33 | 2.58 |
| ε | 50 | 32 | 20 | 10 | 5 | 2 | 1 |

Empirical estimates

When data abound

(MNIST)



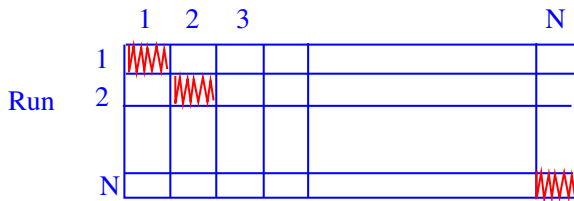
Training

Test



Validation

Cross validation

Fold



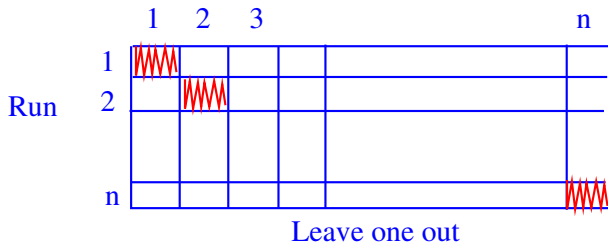
N-fold Cross Validation

Error = Average (error on  of h
learned from )

Empirical estimates, foll'd

Cross validation → Leave one out

Fold



Same as N-fold CV, with $N = \text{number of examples}$.

Properties

Low bias; high variance; underestimate error if data not independent

Empirical estimates, foll'd

Bootstrap



Dataset

uniform sampling
with replacement

Training set

Test set.

rest of examples

Average indicator over all (Training set, Test set) samplings.

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Is \hat{h} better than random ?

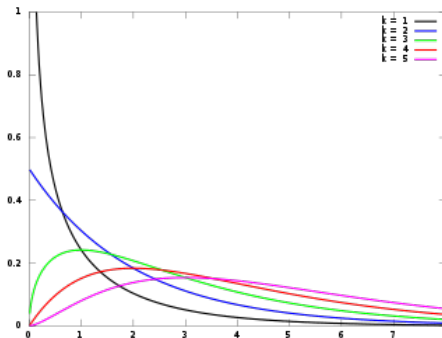
The McNemar test

McNemar 47

| \hat{h} / h^* | 1 | 0 | |
|-----------------|-------|-------|---------------|
| 1 | a | b | a + b |
| 0 | c | d | c + d |
| | a + c | b + d | a + b + c + d |

Property

$\frac{|b-c|-1}{b+c}$ follows a χ^2 law with degree of freedom 1



Types of test error

Type I error

The hypothesis is not significant, and the test thinks it's significant

Type II error

The hypothesis is valid, and the test discards it.

Comparing algorithms A and B

| | A | B | A-B |
|-------|----|----|-----|
| run 1 | 30 | 28 | 2 |
| run 2 | 17 | 25 | -8 |
| | 28 | 25 | 3 |
| | 17 | 28 | -11 |
| | 30 | 26 | 4 |

Assumption

A and B have normal distribution

Simplest case

two samples with same size, (quasi)
same variance.

Define

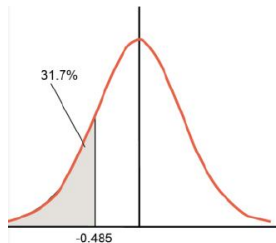
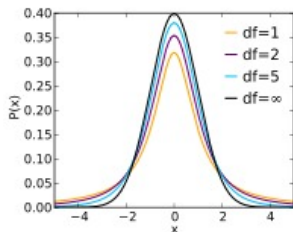
$$t = \frac{\bar{A} - \bar{B}}{S_{A,B} \cdot \sqrt{\frac{2}{n}}}$$

with $S_{A,B} = \sqrt{\frac{1}{2}(S_A^2 + S_B^2)}$ and $S_A^2 = \frac{1}{n} \sum (A_i - \bar{A})^2$

Comparing algorithms A and B

t follows a Student law with $(2n-2)$ -dof

- ▶ Compute t
- ▶ See confidence of t



Comparing algorithms A and B

Recommended: Use paired t-test

- ▶ Apply A and B with same (training, test) sets
- ▶ Variance is lower:

$$\text{Var}(A - B) = \text{Var}(A) + \text{Var}(B) - 2\text{coVar}(A, B)$$

- ▶ Thus easier to make significant differences

What if variances are different ?

See Welch' test:

$$\frac{\bar{A} - \bar{B}}{\sqrt{\frac{S_A^2}{N_A} + \frac{S_B^2}{N_B}}}$$

Summary: single dataset (if we had enough data...)

The 5 x 2CV

Dietterich 98

- ▶ 5 times
- ▶ split the data into 2 halves
- ▶ gives 10 estimates of error indicator
- + More independent
- Each training set is 1/2 data.

With a single dataset

- ▶ 5x2 CV
- ▶ paired t-test
- ▶ McNemar test on a validation set

Multiple datasets

If A and B results don't follow a normal distribution

$$Z_i = A_i - B_i$$

Wilcoxon signed rank test

| A | B | Z | rank | sign |
|----|----|---|------|------|
| 19 | 23 | 4 | 6th | - |
| 22 | 21 | 1 | 1st | + |
| 21 | 19 | 2 | 2nd | + |
| 25 | 28 | 3 | 4th | - |
| 24 | 22 | 2 | 2nd | + |
| 23 | 20 | 3 | 4th | + |

1. Rank the $|Z_i|$
2. W_+ = sum of ranks when $Z_i > 0$
3. W_- = sum of ranks when $Z_i < 0$
4. $W_{min} = \min(W_+, W_-)$

$$z = \frac{1/4n(n+1) - W_{min} - 1/2}{\sqrt{1/24n(n+1)(2n+1)}}$$

5. $z \sim \mathcal{N}(0, 1)$ $n > 20$

Multiple hypothesis testing

Beware

- ▶ If you test many hypotheses on the same dataset
- ▶ one of them will appear confidently true...
increase in type I error

Corrections Over n tests, the global significance level α_{global} is related to the elementary significance level α_{unit} :

$$\alpha_{global} = 1 - (1 - \alpha_{unit})^n$$

- ▶ Bonferroni correction

pessimistic

$$\alpha_{unit} = \frac{\alpha_{global}}{n}$$

- ▶ Sidak correction

$$\alpha_{unit} = 1 - (1 - \alpha_{global})^{\frac{1}{n}}$$

Contents

Position of the problem

Background notations

Difficulties

The learning process

The villain

Validation

Performance indicators

Estimating an indicator

Testing a hypothesis

Comparing hypotheses

Validation Campaign

The point of parameter setting

Racing

Expected Global Improvement

How to set up my system ?

Parameter tuning

- ▶ Setting the parameters for feature extraction
- ▶ Select the best learning algorithm
- ▶ Setting the learning parameters (e.g. type of kernel, the parameters in SVMs)
- ▶ Setting the validation parameters

Goal: find the best setting

a pervasive concern

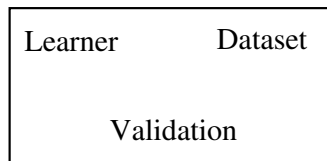
- ▶ Algorithm selection in Operational Research
- ▶ Parameter tuning in Stochastic Optimization
- ▶ Meta-Learning in Machine Learning

From Design of Experiments to ...

Main approaches

1. Design of experiments (Latin square)
2. Anova (Analysis of variance)-like methods:
 - ▶ Racing
 - ▶ Sequential parameter optimization

Parameter Tuning: A Meta-Optimization problem

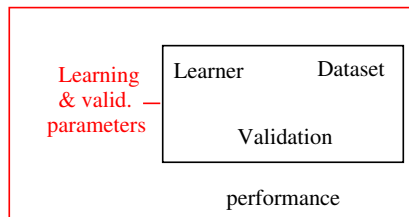


performance

Optimization: the Black-Box Scenario

- ▶ Need to perform several runs to compute performance
Cross-Validation
- ▶ Need to specify the # runs and tune it optimally
- ▶ Overall cost is the total number of evaluations
- ▶ And don't forget to tune the parameters of the meta-optimizer!

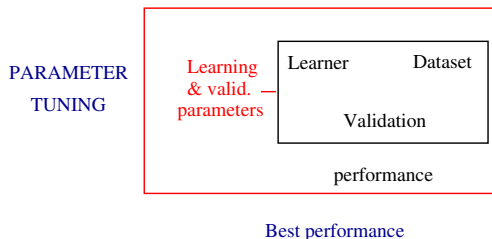
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Parameter Tuning: A Meta-Optimization problem



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Ingredients

Design Of Experiments (DOE)

- ▶ A long-known method from statistics
- ▶ Choose a finite number of parameter sets
- ▶ Compute their performance
- ▶ Return the *statistically significantly* best sets

Analysis of Variance (ANOVA)

- ▶ Assumes normally distributed data
- ▶ Tests if means are significantly different
for a given confidence level; generalizes T-Test
- ▶ Perform pairwise tests if ANOVA reports some difference
T-Test, rank-based tests, ...

DOE: Issues

Choice of sample parameter sets

- ▶ *Full Factorial Design*
 - ▶ Discretize all parameters if continuous
 - ▶ Choose all possible combinations
- ▶ *Latin Hypercube Sampling*: to generate k sets,
 - ▶ Discretize all parameters in k values
 - ▶ Repeat k times:
 - for each parameter, (uniformly) choose one value out of k
 - ▶ For each parameter, each value is taken once
fine if no correlation

Cost

- ▶ For each parameter set, the full cost of learning validation
- ▶ Combinatorial explosion with number of parameters and precision

Racing algorithms

Birattari & al. 02, Yuan & Gallagher 04

Rationale

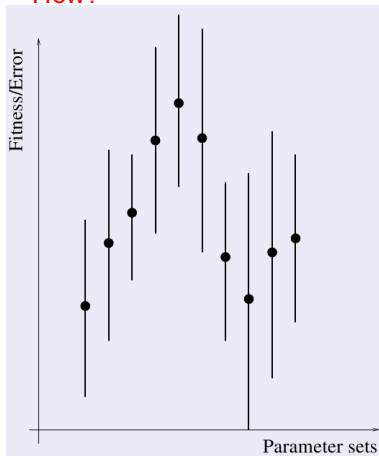
- ▶ All parameter settings are run the same number of times
whereas very bad settings could be detected earlier

Implementation

- ▶ Repeat
 - ▶ Perform only a few runs per parameter set
 - ▶ Statistically check all sets against the best one
at given confidence level
 - ▶ Discard the bad ones
- ▶ Until only survivor, or maximum number of runs per setting reached

Racing algorithms

How?

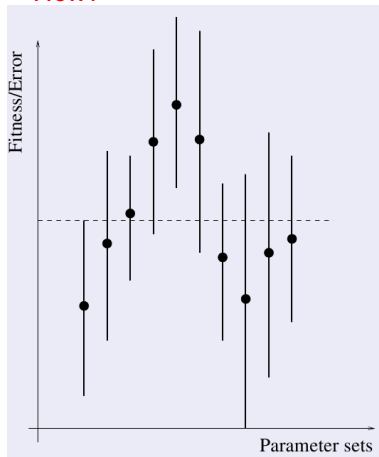


Example: Initialization

- ▶ $R = 0$
- ▶ while $R < R_{max}$ and more than 1 set
 - ▶ Compute empirical value of performance for all sets doing r additional runs
average, median, ...
 - ▶ Compute $X\%$ confidence intervals
Hoeffding bounds, Friedman tests, ...
 - ▶ Remove sets whose best possible value is worse than worst possible value of the best empirical set.
 - ▶ $R+ = r$

Racing algorithms

How?

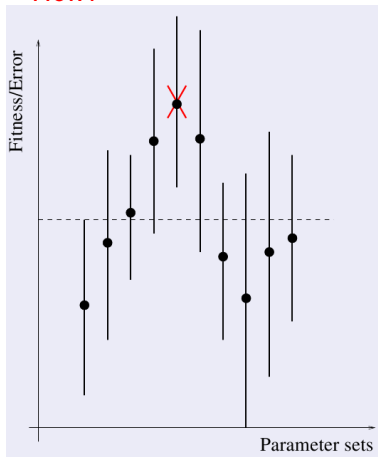


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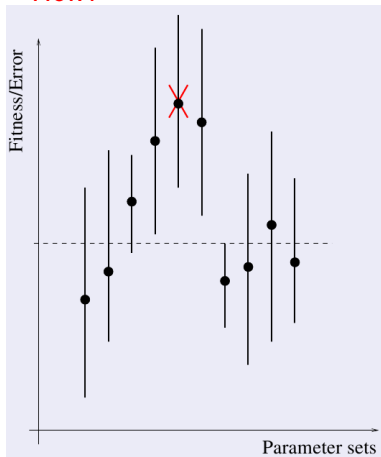


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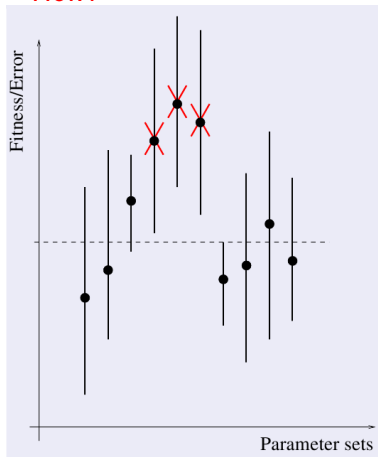


Example: Iteration 1

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Racing algorithms

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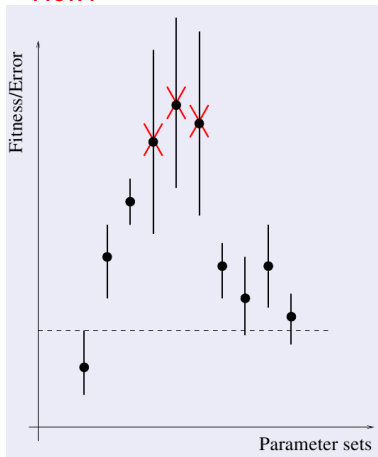


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Racing algorithms

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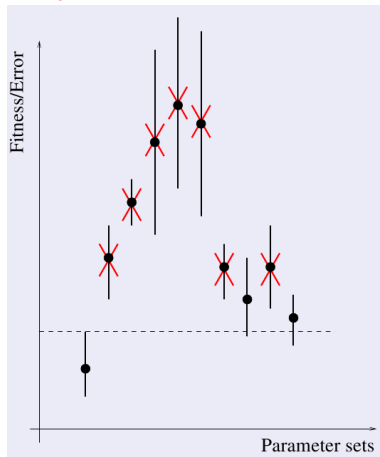


Example: Iteration N

- ▶ $R = 0$
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Racing algorithms

How?

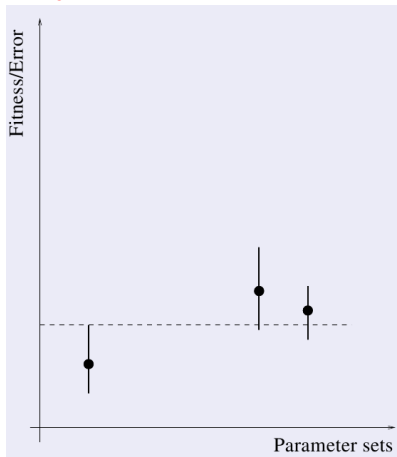


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 - ▶ Remove sets whose best possible value is worse than worst possible value of the best empirical set.
 - ▶ $R+ = r$

Racing algorithms

How?



Example: Best parameter sets

- ▶ $R = 0$
- ▶ while $R < R_{max}$ and more than 1 set
 - ▶ Compute empirical value of performance for all sets doing r additional runs
average, median, ...
 - ▶ Compute $X\%$ confidence intervals
Hoeffding bounds, Friedman tests, ...
 - ▶ Remove sets whose best possible value is worse than worst possible value of the best empirical set.
 - ▶ $R+ = r$

Racing algorithms: Discussion

Results

- ▶ Published results claim saving between 50 and 90% of the runs

Useful for

- ▶ Multiple algorithms on single problem for efficiency
- ▶ Single algorithm on multiple problems to assess problem difficulties
- ▶ Multiple algorithms on multiple problems for robustness

Issues

- ▶ Nevertheless costly
- ▶ Can only find the best one in initial sample

Sequential Parameter Optimization

Bartz-Beielstein & al. 05-07

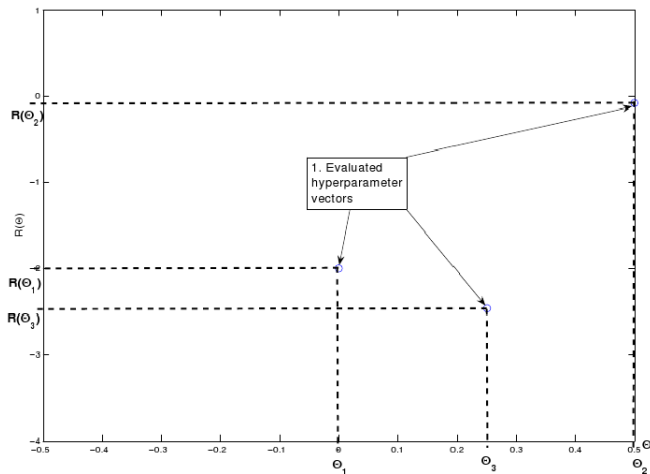
Rationale

- ▶ Start with some very coarse sampling DOE
- ▶ Evaluate performance using few runs per set
- ▶ Build a model of the performance landscape using *Gaussian Processes* aka Kriging
- ▶ Select best points based on *Expected Improvement* according to current model Monte-Carlo sampling
- ▶ Compute actual performance of best estimates using same number of runs as current best
- ▶ Increase # runs of best if unchanged

Gaussian Processes in one slide

An optimization algorithm for expensive functions

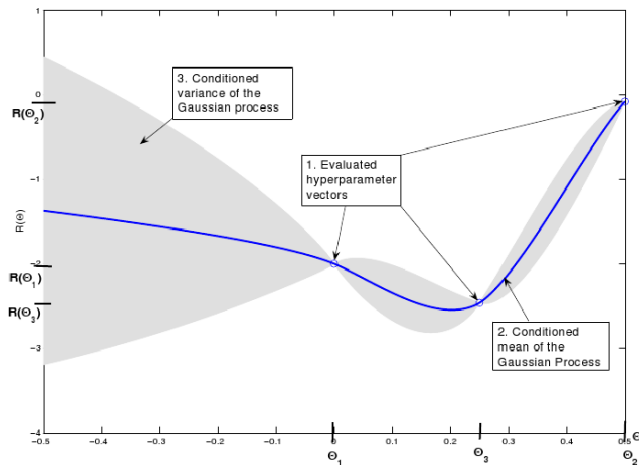
D.R. Jones, Schonlau, & Welch, 98



Gaussian Processes in one slide

An optimization algorithm for expensive functions

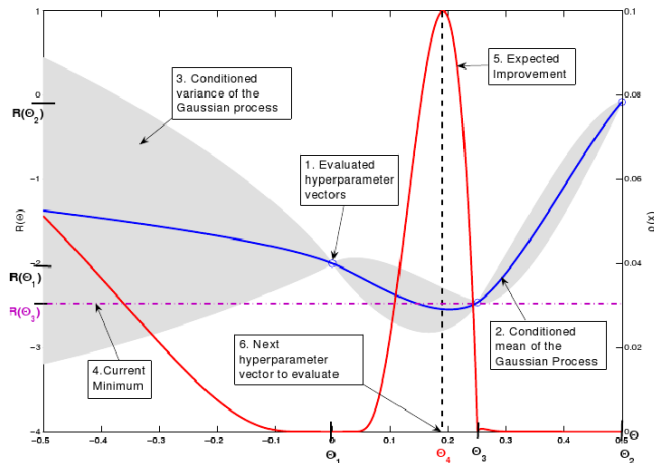
D.R. Jones, Schonlau, & Welch, 98



Gaussian Processes in one slide

An optimization algorithm for expensive functions

D.R. Jones, Schonlau, & Welch, 98



SPO: Discussion

Pros

- ▶ Similar ideas as racing,
- ▶ but allows to *refine initial sampling* a true optimization algorithm
- ▶ Compatible with a *fixed budget* scenario racing is not
- ▶ Authors also report gains up to 90%

Cons

- ▶ Works best with ... some tuning

Take home messages

What is the performance criterion

- ▶ Cost function
- ▶ Account for class imbalance
- ▶ Account for data correlations

Assessing a result

- ▶ Compute confidence intervals
- ▶ Consider baselines
- ▶ Use a validation set

If the result looks too good, beware