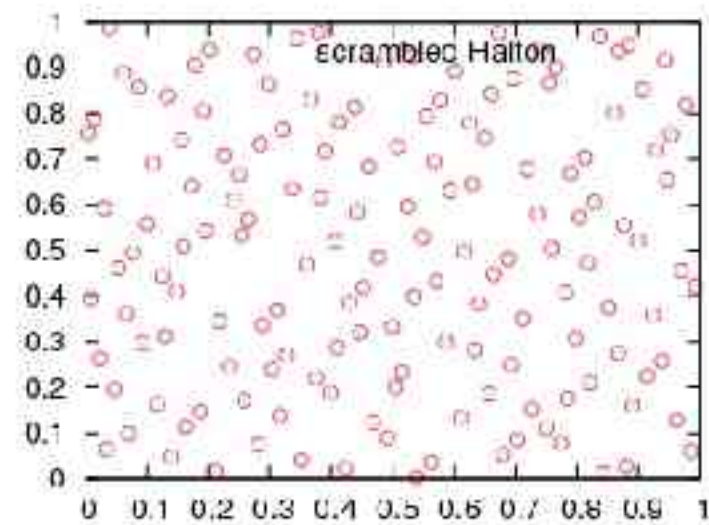
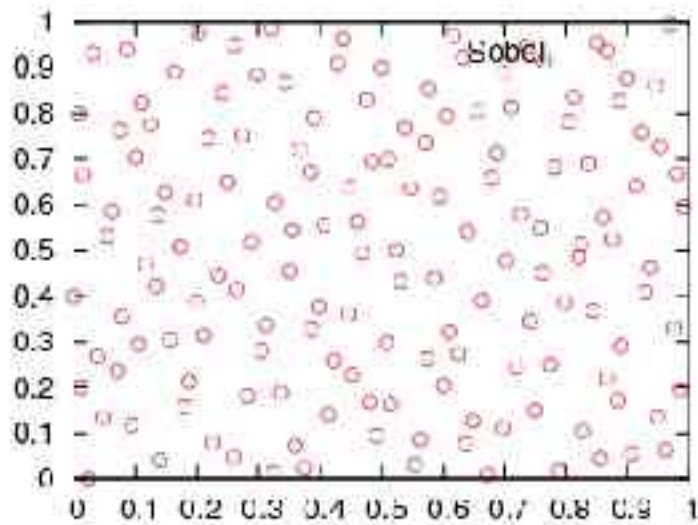
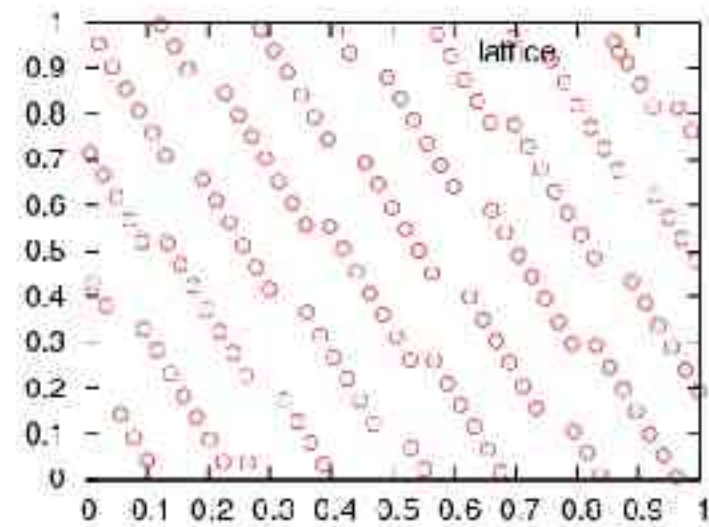
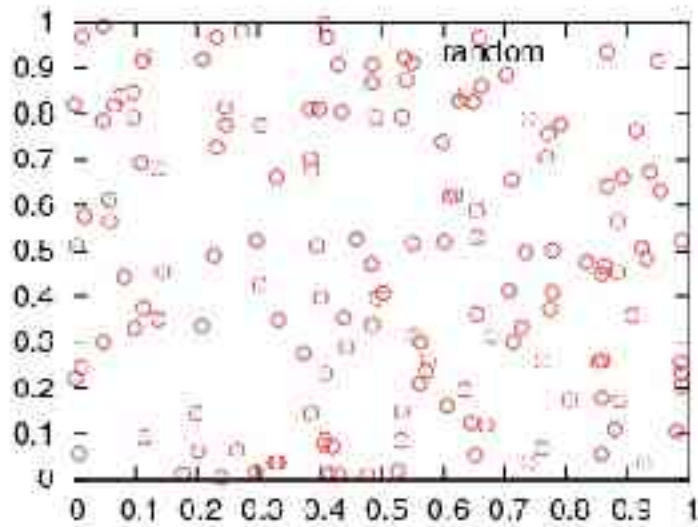


# Quasi-random points

*(Teytaud, Tao (Inria), Lri (Paris-Sud), UMR-Cnrs 8623;  
collabs with S. Gelly, J. Mary, S. Lallich, E. Prudhomme,...)*

- Quasi-random points ?
- Dimension 1
- Dimension  $n$
- Better in dimension  $n$
- Strange spaces

# Quasi-random points ?

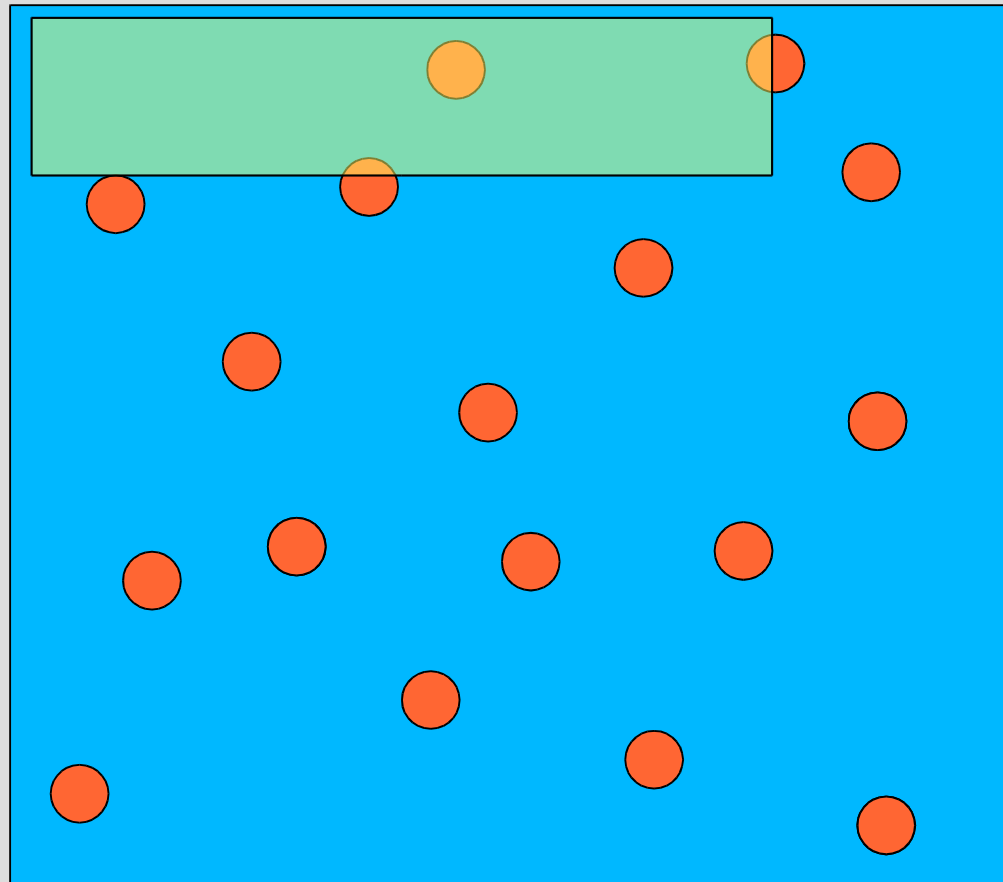


# For what ?

- Numerical integration [thousands of papers; Niederreiter 92]
- Learning [Cervellera et al, IEEE TNN 2004, Mary PhD 2005]
- Optimization [Teytaud et al, EA'2005]
- Modelizat<sup>o</sup> of random-process [Grove-Kruska et al, IEEE BPTP'03]
- Path planning [Tuffin]

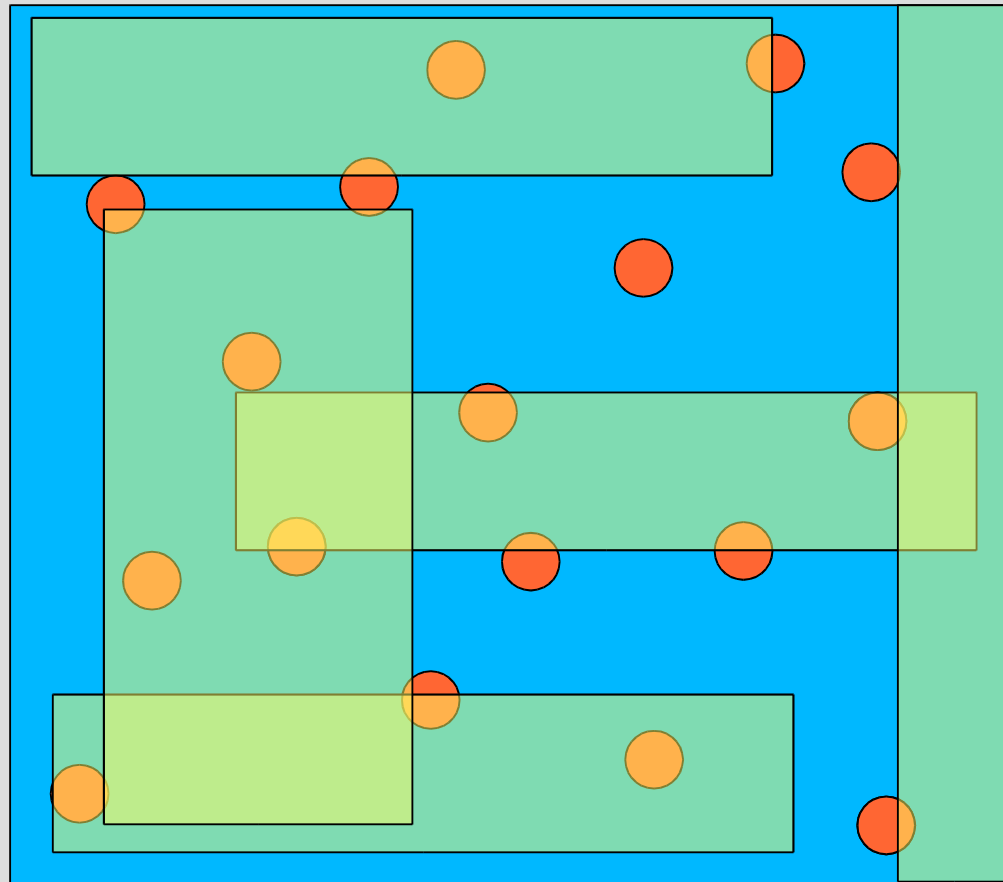
# Low Discrepancy ?

$$\text{Discrepancy} = \text{Max } |\text{Area} - \text{Frequency}|$$



# Low Discrepancy ?

$$\text{Discrepancy}_2 = \text{mean} ( | \text{Area} - \text{Frequency} |^2 )$$



# Low Discrepancy ?

Random --> Discrepancy  $\sim \sqrt{1/n}$

Quasi-random --> Discrepancy  $\sim \log(n)^d/n$

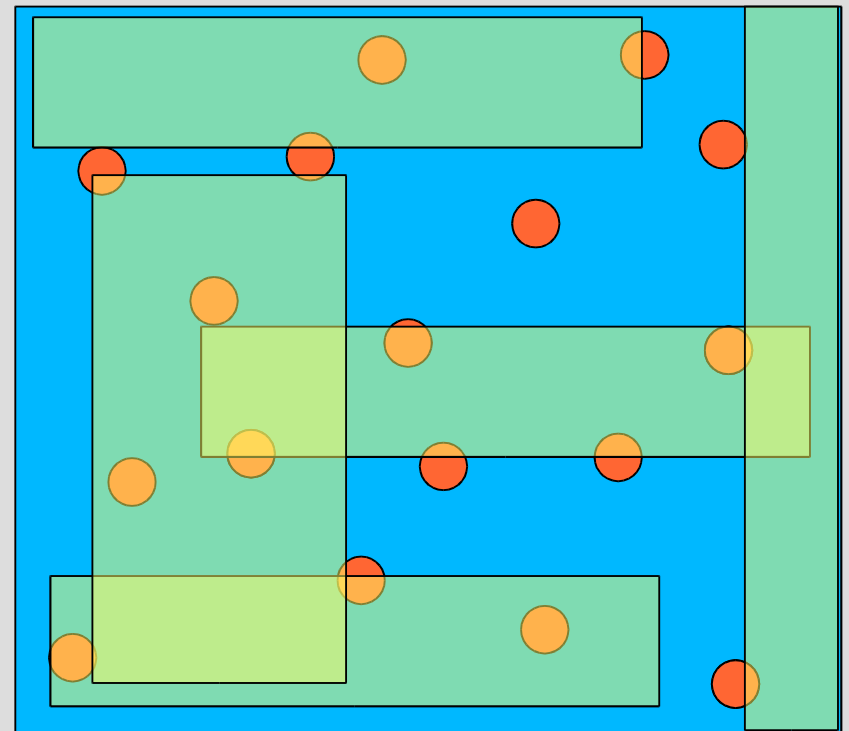
Koksma & Hlawka :

error in Monte-Carlo integration

$< \text{Discrepancy} \times V$

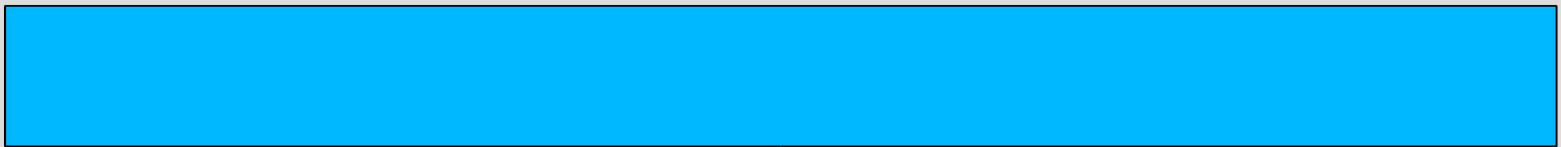
$V =$  total variation (Hardy & Krause)

( many generalizations in Hickernel,  
A Generalized Discrepancy  
and Quadrature Error Bound, 1997 )



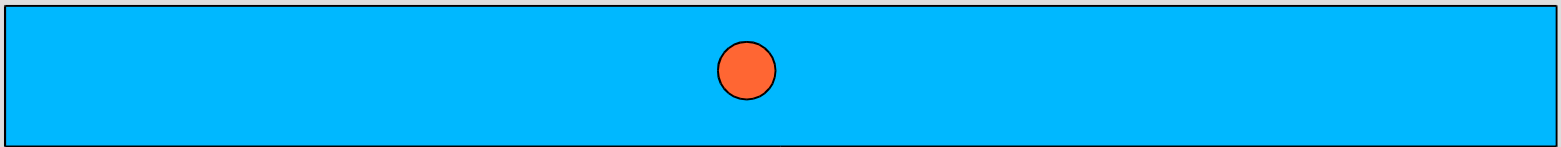
# Dimension 1

- What would you do ?



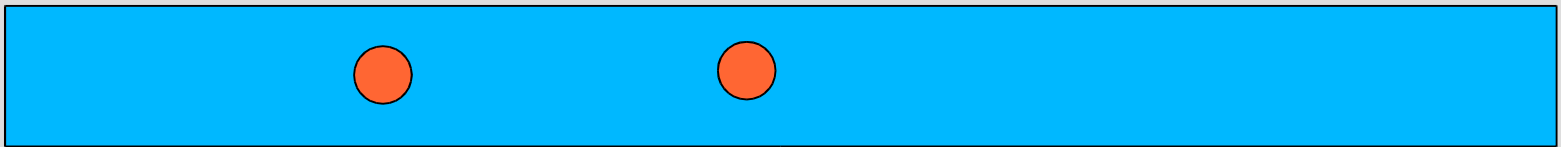
# Dimension 1

- What would you do ?



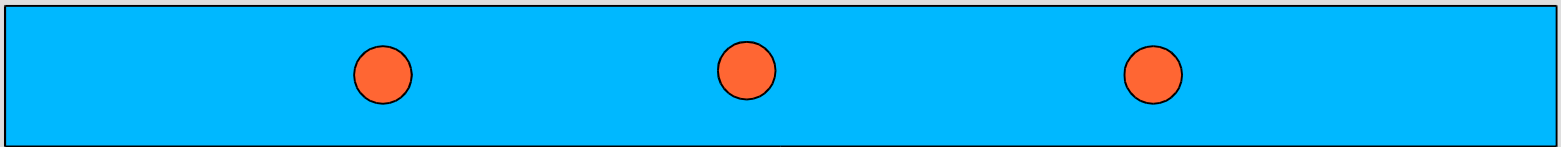
# Dimension 1

- What would you do ?



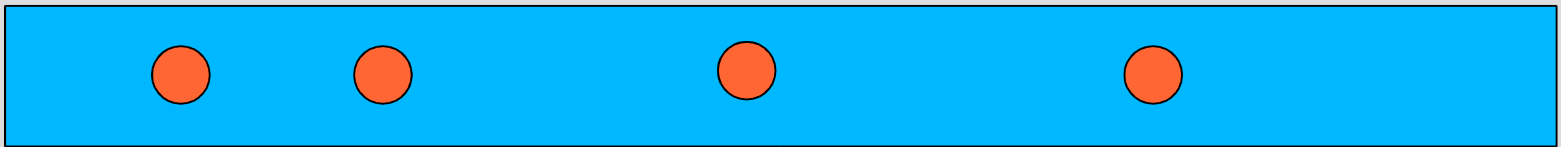
# Dimension 1

- What would you do ?



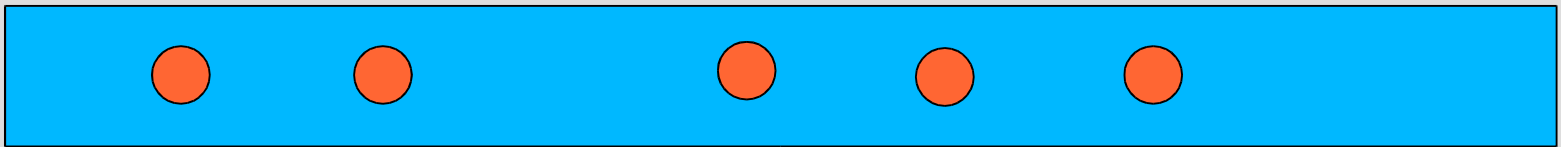
# Dimension 1

- What would you do ?



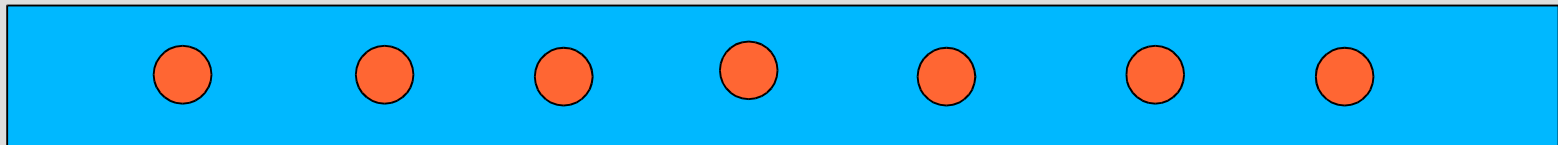
# Dimension 1

- What would you do ?



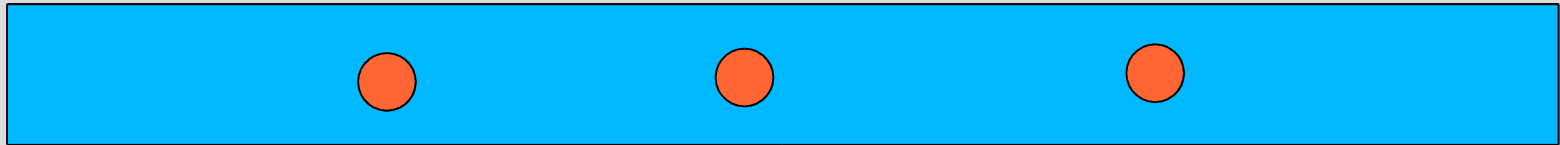
# Dimension 1

- What would you do ?
- --> Van Der Corput
- $n=1, n=2, n=3\dots$
- $n=1, n=10, n=11, n=100, n=101, n=110\dots$
- $x=.1, x=.01, x=.11, x=.001, x=.101, \dots$

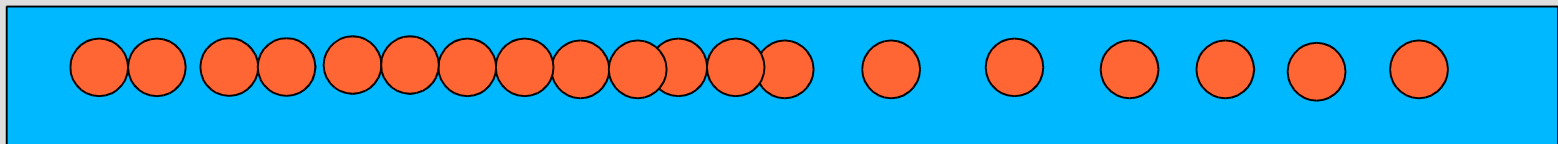
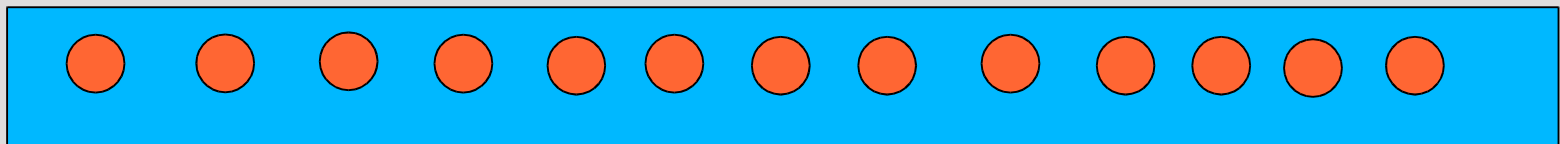
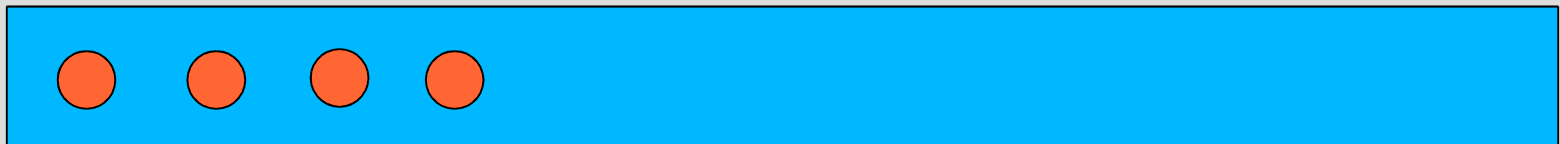


# Dimension 1 more general

- $p=2$ , but also  $p=3, 4, \dots$

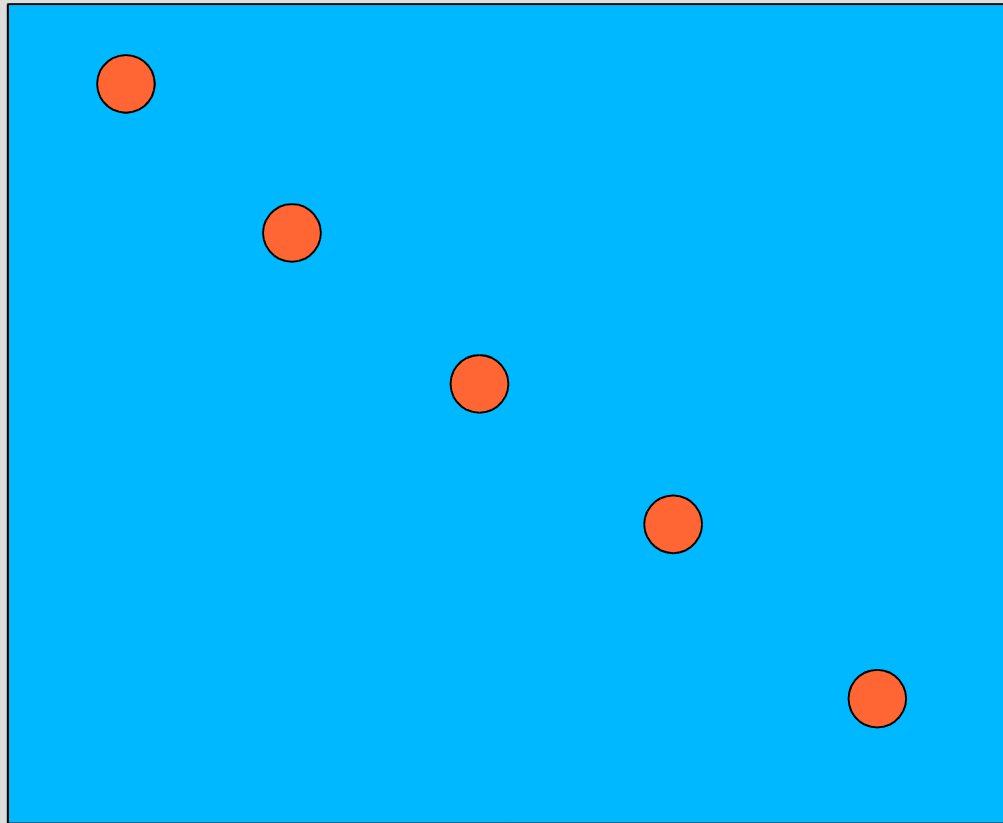


but  $p=13$  is not very nice :



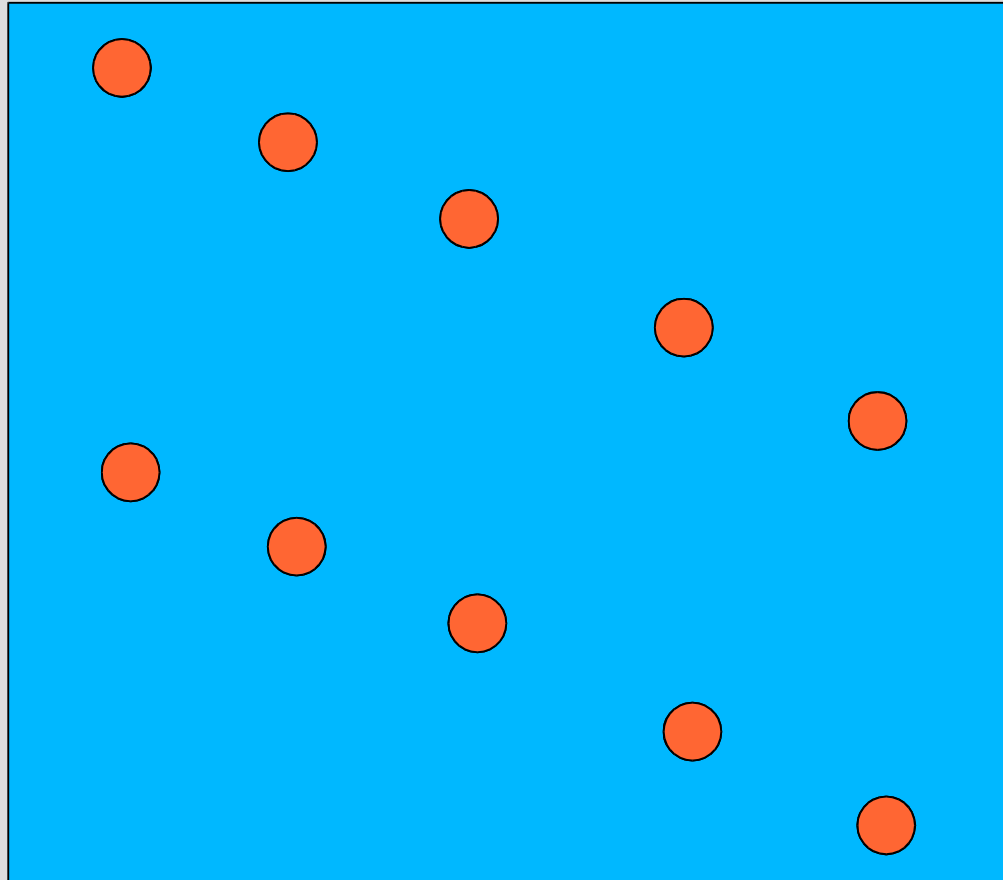
# Dimension n

- $x \mapsto (x, x)$  ?



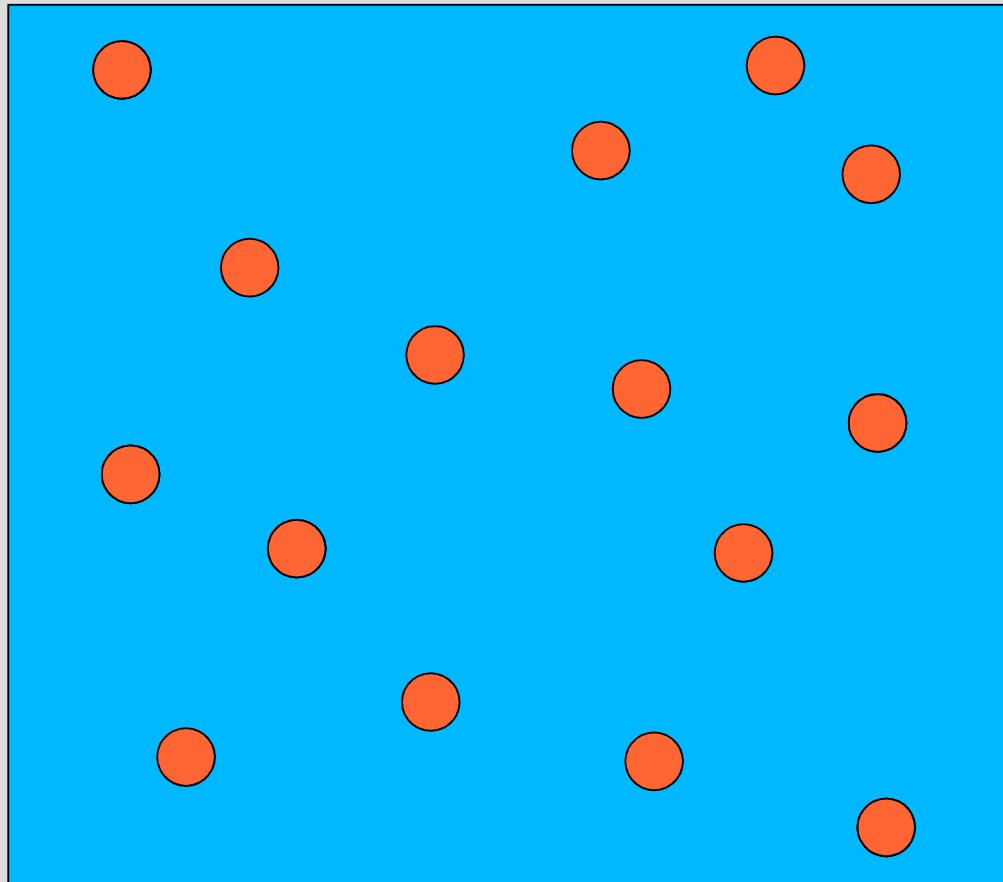
# Dimension n

- $x \dashrightarrow (x, x')$  ?



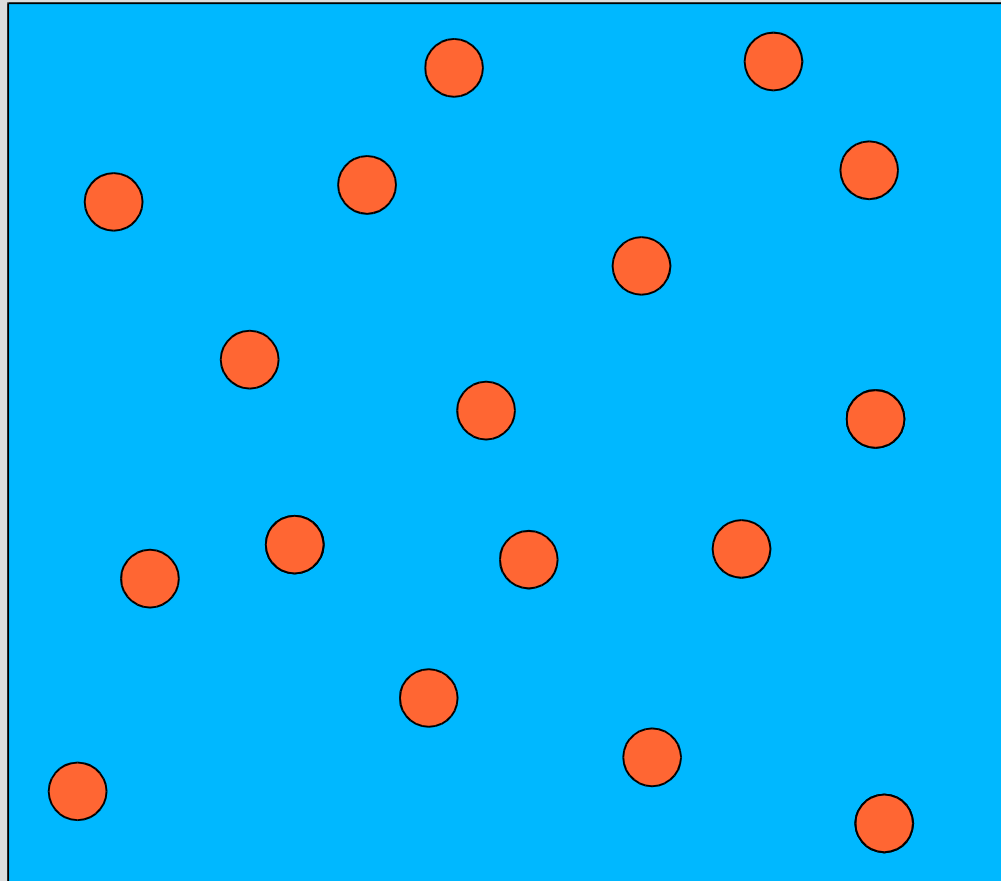
# Dimension n : Halton

- $x \mapsto (x, x')$  with prime numbers



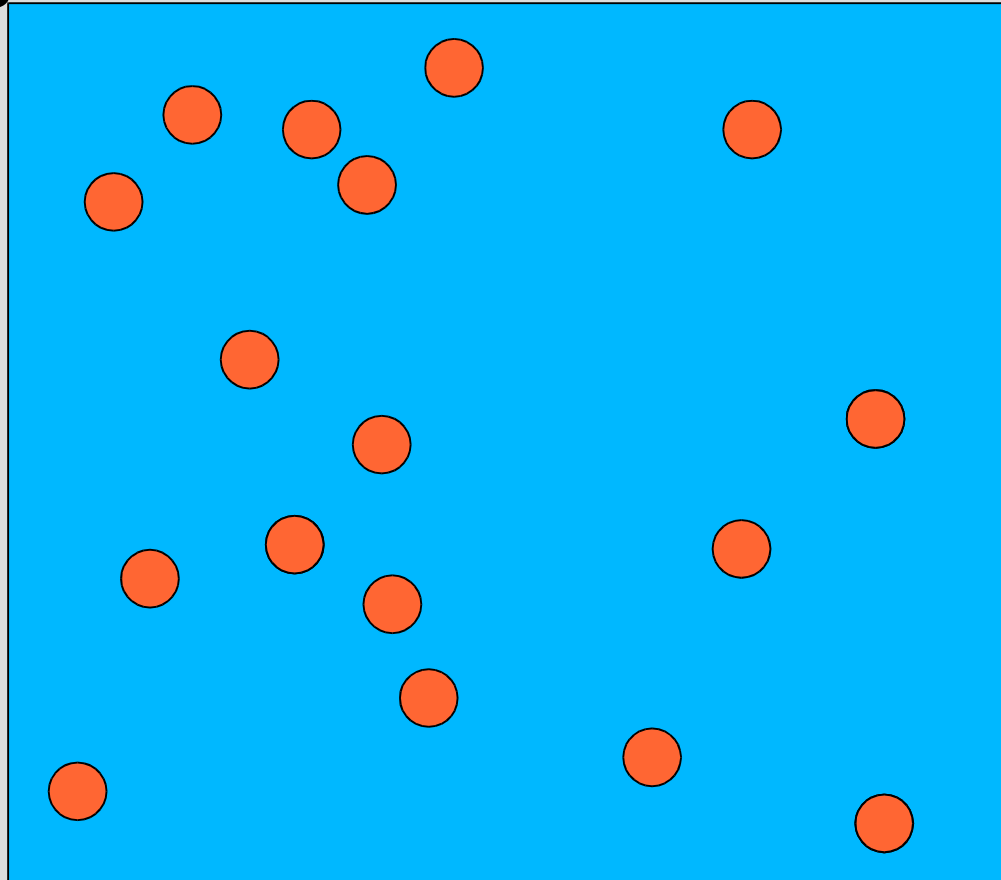
# Dimension $n+1$ : Hammersley

- $x \rightarrow (n/N, x, x')$  but  $\rightarrow$  closed sequence



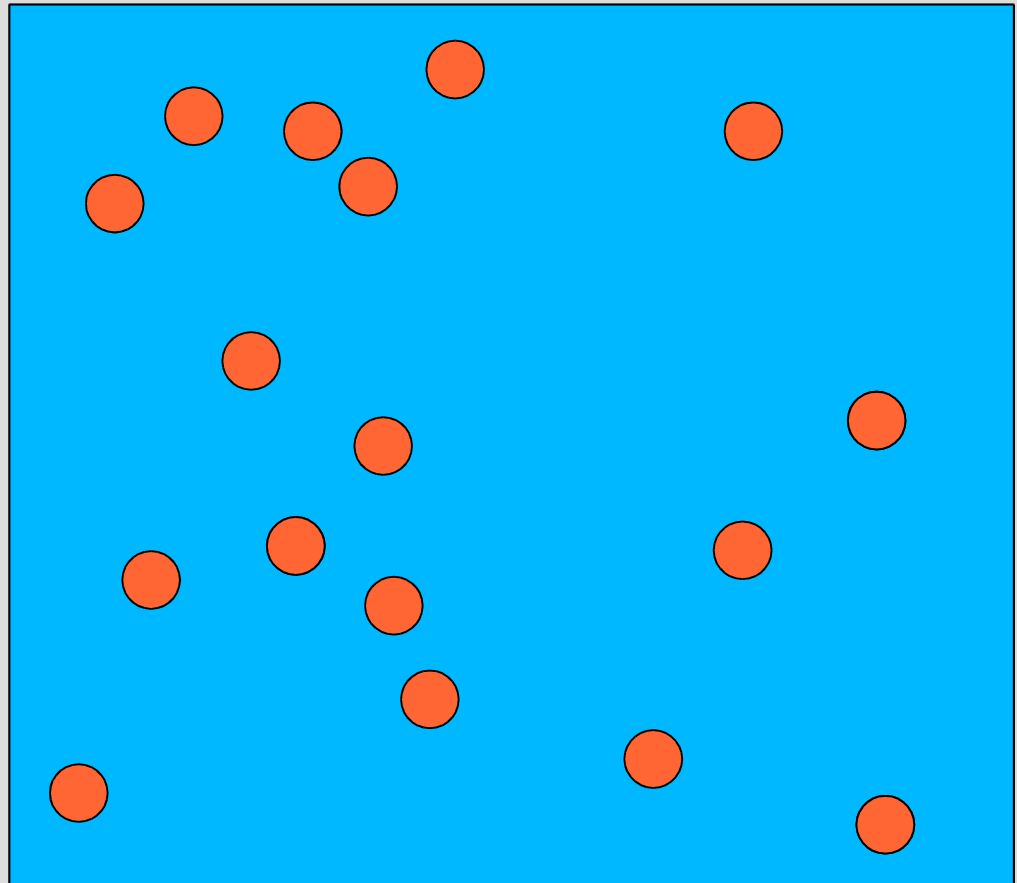
# Dimension n : the trouble

- There are not so many small prime numbers



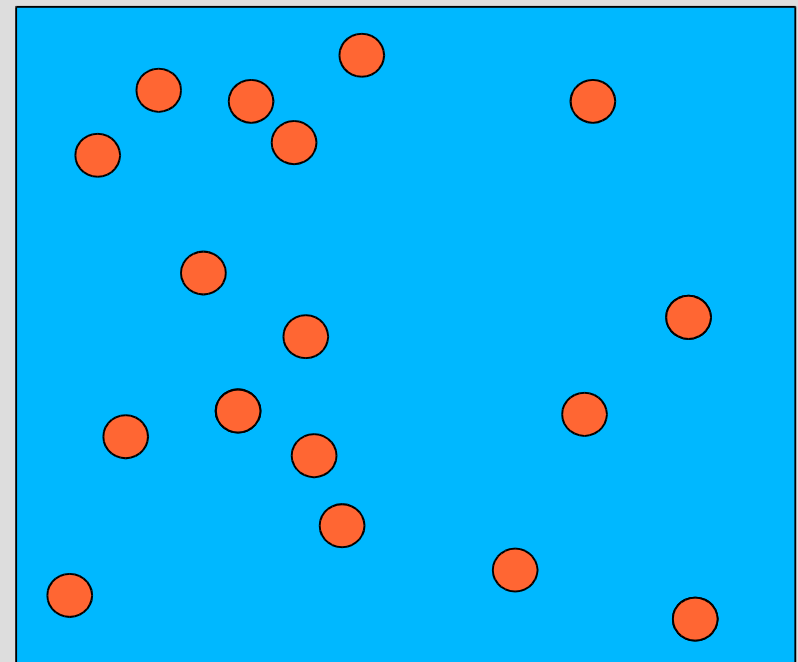
# Dimension n : scrambling (when random comes back)

- $\text{Pi}(p) : [1, p-1] \rightarrow [1, p-1]$
- $\text{Pi}(p)$  applied to ordinate with prime  $p$



# Dimension n : scrambling

- $P_i(p) : [1, p-1] \rightarrow [1, p-1]$  (randomly chosen)
- $P_i(p)$  applied to ordinate with prime  $p$  (there is much more complicated)

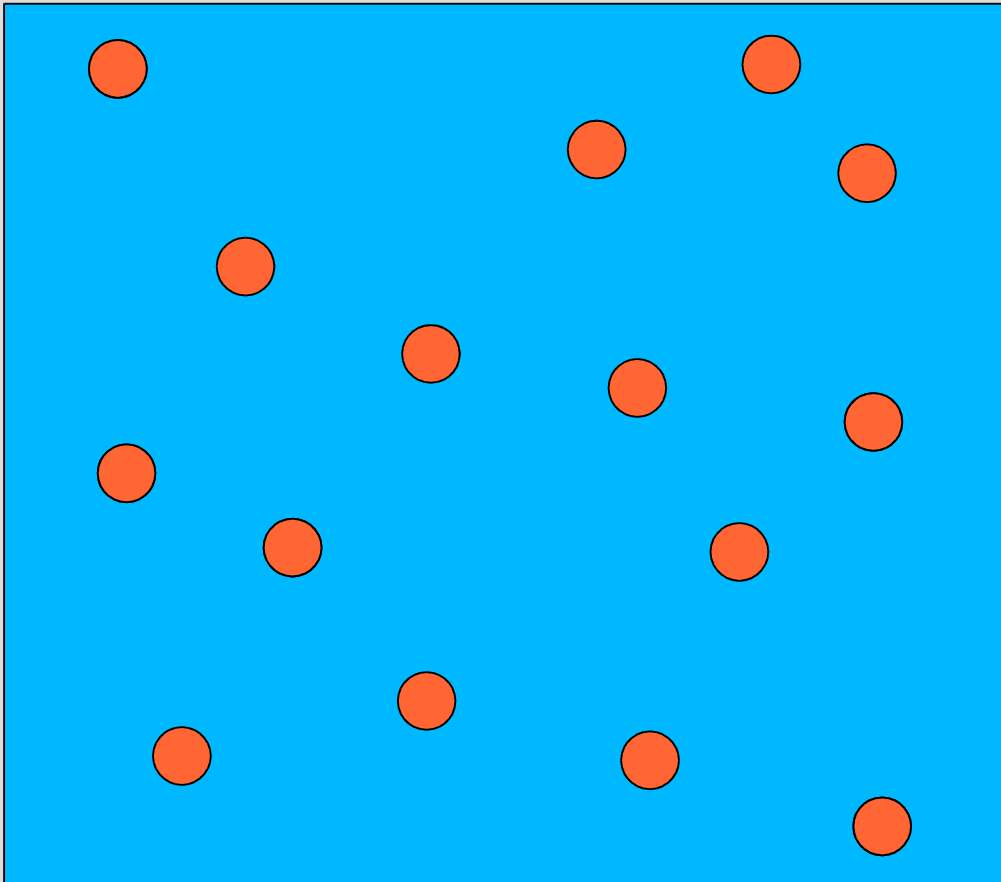


# Others ?

- Other discrepancies : why rectangles ?
- Other solutions : lattices  
 $\{x_0 + nx\}$  modulo 1

# Why in the square ?

- Other spaces : gaussians --> spheres



# Why in the square ?

- Other spaces : gaussians  $\rightarrow$  spheres
  - $x$  in  $]0,1[^d$
  - $y(i)$  such that  $P(N > y(i)) = x(i)$   
with  $N$  standard gaussian
  - then  $y$  is quasi-random and gaussian

# Why in the square ?

- Other random variables : PDF

$$z = \inf \{ t ; P(Z < t) > x \}$$

==> strange spaces or variables



(C) CR-PHOTO / G.Nowak e-mail: cr-photo@t-online.de

# Why in the square ?

- Other random variables : CDF

$$0 < x < 1 \quad \text{-->} \quad z = \inf \{ t ; P(Z < t) > x \}$$

==> ok for discrete spaces

e.g.

Samplings [IIIA'2006] :

- quasi-random bagging
- quasi-random cross-validation
- quasi-random bootstrap
- quasi-random subbagging

# We open a parenthesis on quasi-random bagging

(

# Quasi-random bagging : hkgnz ?

- Bagging is based on Monte-Carlo sampling :
  - Generate plenty of hypothesis
  - Take the average
- This is exactly like Monte-Carlo integration :
  - Generate plenty of values
  - Take the average
- We can do quasi-Monte-Carlo

# Quasi-random bagging (i)

- Bagging:
  - Consider  $n$  examples
  - For  $i=1$  to  $N$ 
    - Randomly draw  $n$  examples with replacement
    - Learn an hypothesis  $H_i$
  - Hypothesis =  $\text{sum } H_i / N$
- Subbagging : idem but draw  $m \ll n$  examples
- Quasi-random (su-)bagging ?

# Quasi-random bagging (ii)

- Drawing  $n$  examples among  $n$  :
  - Build  $k$  clusters
  - Choose the number of examples in the first cluster ;
  - Choose the number of examples in the second cluster ;
  - ...
  - Choose the number of examples in the last cluster.

# Quasi-random bagging (iii)

- Drawing  $n$  examples among  $n$  :
  - Build  $k$  clusters
  - Choose the number of examples in the first cluster (= binomial = first ordinate) ;
  - Choose the number of examples in the second cluster (= binomial = second ordinate) ;
  - ...
  - Choose the number of examples in the last cluster (= binomial =  $k^{\text{th}}$  ordinate).

# Quasi-random bagging (iv)

- Evaluate the *CDF* of the number of examples in cluster  $i$  (binomial)
- $CDF^{-1}(x_i) = \text{number in cluster } i$

therefore, quasi-random in dimension  $k$

**We close the parenthesis**

)

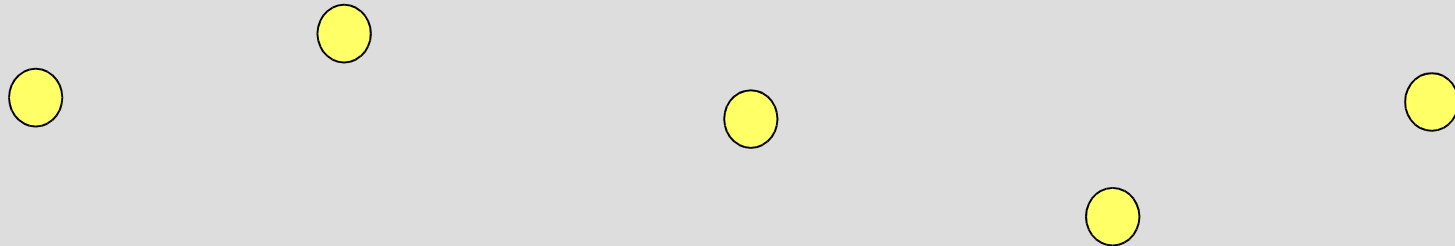
# Why not for random walks ?

- 500 steps of random walks  $\implies$  huge dimension
- But strong derandomization possible :  
with  
dim 3, place 3 points with ad hoc  
distribution



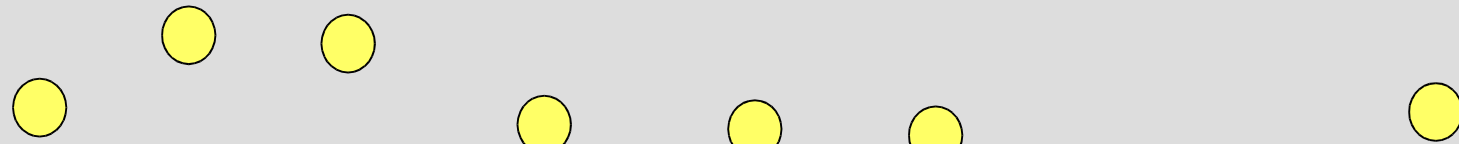
# Why not for random walks ?

- 500 steps of random walks  $\implies$  huge dimension
- But strong derandomization possible :  
dim 4 and 5 provide two more points



# Why not for random walks ?

- 500 steps of random walks  $\implies$  huge dimension
- But strong derandomization possible :



see e.g. Hickernel 1998 for nice generalizations

# Very different approaches for derandomization ?

- **Symetries** : instead of  $x$  in  $[0,1]$  try  
use  $x$  and  $1-x$
- $2 \times (n/2)$  points better than  $n$  points
- $\implies$  antithetic variables
- $\implies$  roughly, it is almost always better, whereas quasi-random might be disappointing

# Very different approaches for derandomization ?

- **Control** : instead of estimating  $E f(x)$
- Choose  $g$  looking like  $f$  and estimate  $E (g-f)(x)$
- Then  $E f = E g + E(g-f)$  is much better
- Troubles:
  - You need a good  $g$
  - You must be able of evaluating  $Eg$

# Very different approaches for derandomization ?

- **Pi-estimation** : instead of estimating  $E f(x)$
- Look for  $y$  with density  $\simeq \sigma(f)d(x)$
- Then  $E f(x) = E f(y) d(x)/d(y)$   
 $\implies$  *Variance is much better*
- Troubles:
  - You have to generate  $y$
  - You have to know  $\sigma(f)$

# Very different approaches for derandomization ?

- **Stratification (jittering) :**
- Instead of generating  $n$  points i.i.d
- Generate
  - $k$  points in stratum 1
  - $k$  points in stratum 2
  - ...
  - $k$  points in stratum  $m$   
with  $m \cdot k = n$   $\implies$  more stable  
 $\implies$  depends on the choice of strata

# Biblio (almost all on google)

- Owen, A.B. "Quasi-Monte Carlo Sampling", A Chapter on QMC for a SIGGRAPH 2003 course.
- Fred J. Hickernell, A generalized discrepancy and quadrature error bound, 1998
- B. Tuffin, On the Use of low-Discrepancy sequences in Monte-Carlo methods, 1996
- Matousek, Geometric Discrepancy (book 99)

these slides : <http://www.lri.fr/~teytaud/btr2.pdf>  
or <http://www.lri.fr/~teytaud/btr2.ppt>