

2) Maximum Entropy formulation of GMM → stat. Phys.

- Let's define an energy cost associated with assigning data x_i to the cluster l : $E_l(x_i)$

In average, the total cost is: $\langle E \rangle = \sum_l \underbrace{\sum_i E_l(x_i) p_l}_{P} \underbrace{p_l}_{\sim \text{clustering measure}}$

- Find a distribution:
 - it fixes in averages the energy cost
 - with the highest possible entropy

$$\text{the entropy } S(\lambda, \beta) = - \sum_k p_k \log p_k + \underbrace{\beta \left(\sum_k p_k E_k - c_k \right)}_{\text{imposing fix on } E} + \underbrace{\lambda \left(\sum_k p_k - 1 \right)}_{\text{imposing normaliz. of } p_k \text{ with lagrange param. } \lambda}$$

$$\begin{aligned} \frac{\partial S}{\partial p_k} &= -p_k - 1 + \beta E_k + \lambda = 0 \\ &\Rightarrow p_k = e^{-(1-\lambda) - \beta E_k} \\ \frac{\partial S}{\partial \lambda} &= \sum_k \underbrace{e^{(1-\lambda)}}_{p_k} = 1 \end{aligned} \quad \left. \begin{aligned} p_k^{(x)} &= \frac{-\beta E_k(x)}{\sum_l e^{-\beta E_k(x)}} \\ &\text{if fix } e^{(1-\lambda)} = \frac{1}{\sum_k e^{-\beta E_k}} \end{aligned} \right\}$$

$$\text{If we take: } E_k(x) = (x - \mu_k)^2 : p_k^{(x)} = \frac{e^{-\beta(x - \mu_k)^2}}{\sum_l e^{-\beta(x - \mu_l)^2}} : \text{ the resp. (without } \rho)$$

→ $\beta \leftrightarrow \frac{1}{2\sigma^2}$: fixed # clusters.

$$\begin{aligned} \text{If we max the free-energy: } -\beta F &= \mathcal{J}(z) = \sum_i \log \left(\sum_k e^{-\beta(x - \mu_k)^2} \right) \end{aligned}$$

$$0 = \frac{\partial -\beta F}{\partial \mu_h} ? : \boxed{\sum_i \frac{(\vec{x}_i - \vec{\mu}_h)^{-\beta(\vec{x}_i - \vec{\mu}_h)}}{\sum_k e^{-\beta(\vec{x}_i - \vec{\mu}_k)^2}} = 0} \Rightarrow \begin{matrix} \text{max likelihood} \\ \text{for } G_{NN} \end{matrix}$$

(□)

Phase transition in Learning

- when β is very small (high T, high variance)

The probability to belong to any cluster is $\sim \frac{1}{K}$
 where K is the total number of clusters

$$\Rightarrow \text{all } \vec{\mu}_h \sim \text{center of mass} = \vec{0} \quad \left\{ \begin{array}{l} \text{center the determinant} \\ \sum_i \vec{x}_i = 0 \end{array} \right.$$

$$\vec{\mu}_h = 0 \text{ should be a solution of (□)}: \underbrace{\sum_i \frac{\vec{x}_i e^{-\beta \|\vec{x}_i\|^2}}{\sum_k e^{-\beta \|\vec{x}_i\|^2}}}_{\frac{1}{K} \sum_i \vec{x}_i} = 0$$

Is it stable? (for small β)

Linear perturbation analysis: we add a small perturbation to μ : $\vec{\mu}_h = \vec{0} + \vec{\epsilon}_h$
 $\oplus \sum_h \vec{\epsilon}_h = 0$

$$\begin{aligned}
 & (\square) : \sum_i \frac{(\vec{x}_i - \vec{\Sigma}_h)^{-\beta \|\vec{x}_i - \vec{\Sigma}_h\|^2} e}{\sum_e e^{-\beta \|\vec{x}_i - \vec{\Sigma}_e\|^2}} = 0 \\
 \Leftrightarrow \frac{1}{\vec{\Sigma}_h} &= \frac{\sum_i \vec{x}_i (e^{-\beta \|\vec{x}_i - \vec{\Sigma}_h\|^2} / \sum_e e^{-\beta \|\vec{x}_i - \vec{\Sigma}_e\|^2}) p_h(\vec{x}_i)}{\sum_j e^{-\beta \|\vec{x}_j - \vec{\Sigma}_h\|^2} / \sum_e e^{-\beta \|\vec{x}_j - \vec{\Sigma}_e\|^2}} = \frac{\sum_i \vec{x}_i p_h(\vec{x}_i)}{\sum_i p_h(\vec{x}_i)} \\
 p_h(\vec{x}_i) &= \frac{e^{-\beta \|\vec{x}_i - \vec{\Sigma}_h\|^2}}{\sum_e e^{-\beta \|\vec{x}_i - \vec{\Sigma}_e\|^2}} = \frac{e^{-\beta \|\vec{x}_i\|^2 + 2\vec{x}_i^\top \vec{\Sigma}_h - \beta \|\vec{\Sigma}_h\|^2}}{\sum_e e^{-\beta \|\vec{x}_i\|^2 + 2\beta \vec{x}_i^\top \vec{\Sigma}_h - \beta \|\vec{\Sigma}_h\|^2}} \sim O(\varepsilon^2)
 \end{aligned}$$

$$\underset{\text{small } \varepsilon}{\approx} \frac{\frac{1 + 2\beta \vec{x}_i^\top \vec{\Sigma}_h}{\sum_e (1 - 2\beta \vec{x}_i^\top \vec{\Sigma}_e)}}{\sum_e (1 + 2\beta \vec{x}_i^\top \vec{\Sigma}_h)} = \frac{1}{N} (1 + 2\beta \vec{x}_i^\top \vec{\Sigma}_h)$$

$$\begin{aligned}
 & (\square) : \vec{\Sigma}_h \approx \frac{\sum_i \vec{x}_i (1 + 2\beta \vec{x}_i^\top \vec{\Sigma}_h)}{\sum_j (1 + 2\beta \vec{x}_j^\top \vec{\Sigma}_h)} = \frac{2\beta \sum_i \vec{x}_i \vec{x}_i^\top \vec{\Sigma}_h}{N (1 + 2\beta \frac{\sum_i \vec{x}_i^\top \vec{\Sigma}_h}{N})} \underset{\text{covariance matrix } = C}{\approx} \frac{2\beta \sum_i \vec{x}_i \vec{x}_i^\top \vec{\Sigma}_h}{N}
 \end{aligned}$$

$\vec{\Sigma}_h^{(t+1)} \approx 2\beta C \vec{\Sigma}_h^{(t)}$ - if " ε_{BC} " > 1 : the solution is unstable
- if " ε_{BC} " < 1 : stable

The stability depends on the eigenvalues of C

\Rightarrow can always write $\vec{\Sigma}_h = \sum_i \lambda_i \vec{u}_i$ where the \vec{u}_i are eigenvectors of C

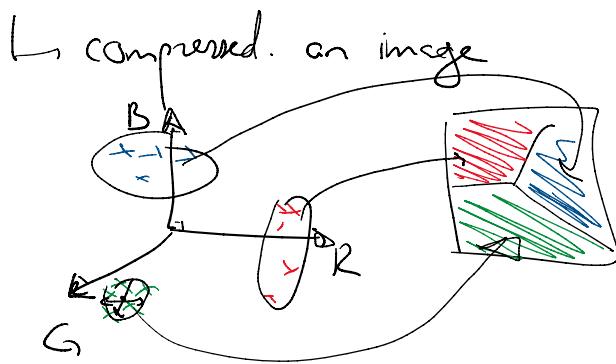
$\vec{\Sigma}_h^{(t+1)} \approx 2\beta \sum_i \lambda_i c_i \vec{u}_i$ where c_i are eigenvalues of C

we have the threshold: $2\beta c_{\max} = 1$ $\beta_C = \frac{1}{2c_{\max}}$

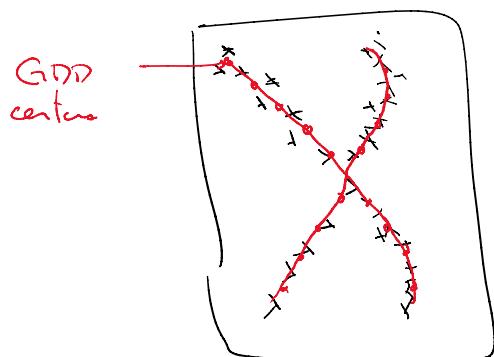
$c_{\max} = \max_i \{c_i\}$: max. eigenvalue of C

2 applications of GNN:

i) Segmented an image



ii) Principal graph.



find the red curve from
its depth

add a prior: $p(\theta) \rightarrow p(\{\vec{p}_a\}_n) = e^{-\lambda \sum_{a,b} [b_{ab}] \|\vec{p}_a - \vec{p}_b\|^2}$

attractive interact.

adjacency matrix

$$b_{ab} : \begin{cases} 1 & \text{if } a \text{ is connected to } b \\ 0 & \text{otherwise} \end{cases}$$

For the graph structure:

→ construct the minimum spanning tree