Learning Dynamics Equations

\[ h_{t+1} = f(h_t) \]

with \( f \) small

\[ \text{RNN} \]

\[ \frac{dh}{dt} = f(h) \]

DBM

\[ u(x,t) \]

\[ \nabla \nabla \nabla \]

\[ f(x,t) \]

mesh-free