

Forms of weak supervision

Small data

Data augmentation:

e.g.: image classification

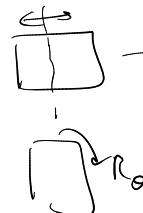
add transformations



label: invariant
equivariant

dataset: $D \cup D_D$

e.g.: flip:



1 datapoint

4 points → same label

- rotation:

- translate

- crop



- color balance

- pixel noise

- contrast

value-based
transforms

geometric
transforms

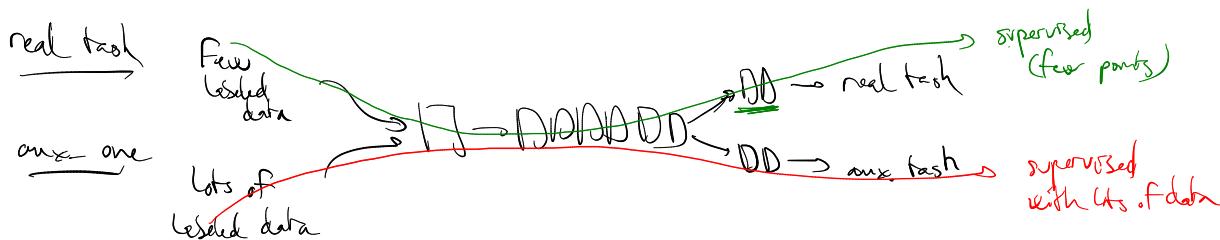
Use a simulator

- generate a lot of data

- how realistic? (model the sys)

Mix/Hr-tasking

- one real task + one (several) auxiliary tasks



Transfer learning

sequential training:

→ first: on auxiliary task

→ then: on real task

e.g.: classify images

of rare animals (few priories)

ImageNet: 1000 classes

× 1000 images/

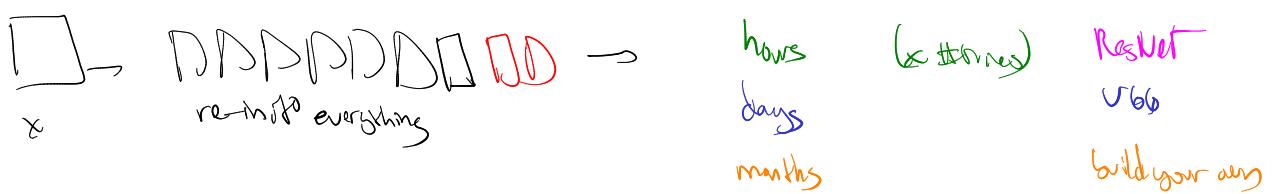
class

↳ lots of

= networks already trained

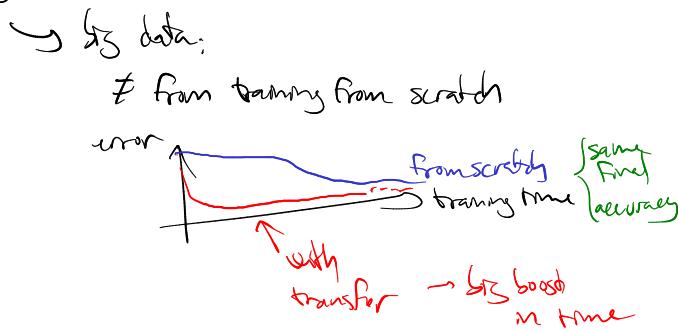


minutes / x times trying & hyperparameters



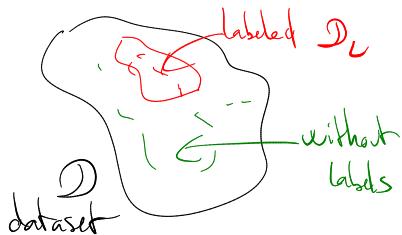
Analysis from [Rethinking ImageNet pre-training]

Small data:
helps in getting good features



II forms of weak supervision

amount of data, but only few are labeled

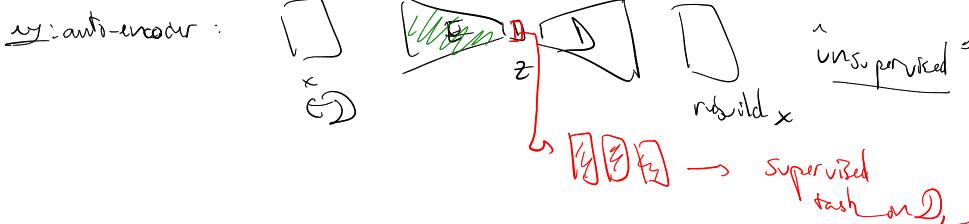


ex: when labeling is costly
(requires time, expert knowledge...)

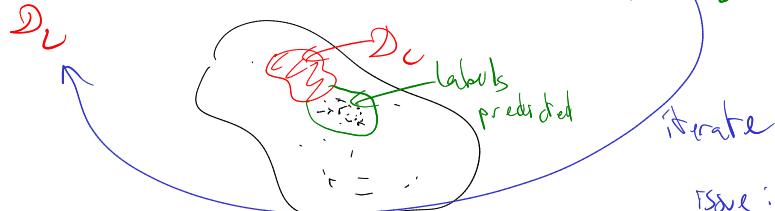
⇒ "semi-supervised"

Several approaches:

1) unsupervised training on full dataset D_L → good representation → supervised task on D_L

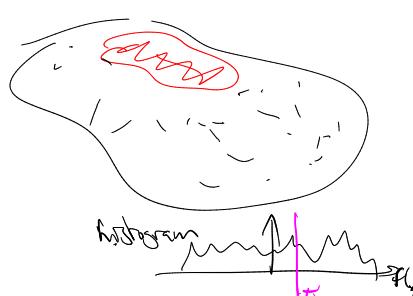


2) supervised training → label some of the non-labeled data → bigger dataset $D'_L = D_L \cup D_{new\ labels}$



Issue: what about confident mistakes?

3) supervised training on D_L → apply network to full dataset → check statistics / properties of your estimator and adjust global parameters



ex: global bias also: margin (sum)

binary class p: A / B

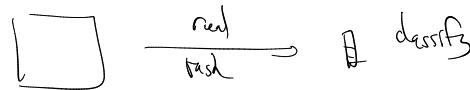
40% target
55% current estimation
60% target
45% current estimation

Self-supervision (approach 1)

↳ used for pre-training

= no supervision \Rightarrow design supervised task so that labels are automatically assigned
(aux.)

ex: image classif^o



puzzle:



scramble g pieces



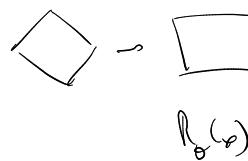
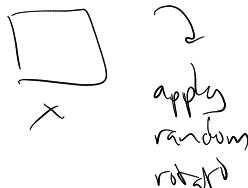
permuted image

dummy task:

where was the middle piece?

g classes

rotation:



what was the angle θ ?
(regression task)

ex: video classif^o:

- predict next frame

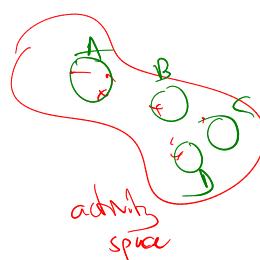
- give 3 frames: $\square \square \square$ ask temporal order?

Teacher-student techniques (distillation)

"ClusterFit":



train new network to predict cluster class



DINO:

student: $\boxed{x} \rightarrow \boxed{D} \rightarrow \boxed{D} \rightarrow \boxed{D} \rightarrow \boxed{D} \rightarrow \boxed{D} \rightarrow \boxed{y}$

$x = \text{augmented } x$

randomly initialized (fixate architecture bias)

teacher: $\boxed{x} \rightarrow \boxed{D} \rightarrow \boxed{D} \rightarrow \boxed{D} \rightarrow \boxed{D} \rightarrow \boxed{D} \rightarrow \boxed{y}$

average of the last past students

ex: $x' = R_\theta(x)$] group of
or noisy x transforms

ask student (x') to be close to
teacher (x)

learning to be invariant
to the group of transform

ask student

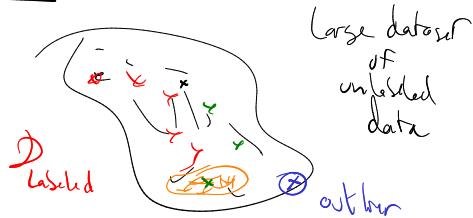
to have high variance (to prevent collapse)

Key:

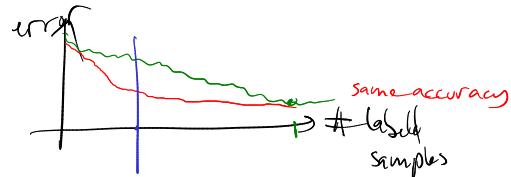
train linear classifier on top

\Rightarrow almost as good as supervised techniques

Active learning



→ ask someone to label more samples (costly)



Modeling 2 quantities:

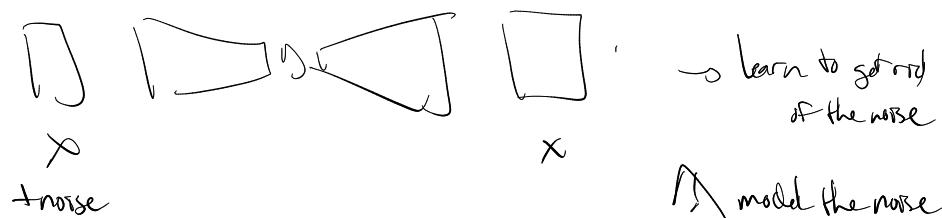
- how non-confident are current predictions for that sample
- how similar the sample is to many other unlabeled samples

Goal: pick the most informative samples to label

↳ loss improvement over all dataset

III Noisy data

1) Noisy inputs → denoising auto-encoder



2) Classification with noisy labels



If 1% labels wrong → ok

10%

50%

99%

random :

noise cancels out on average

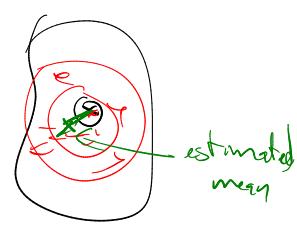
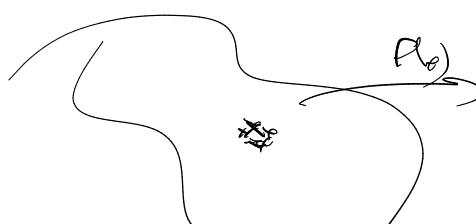


3) Regression with noisy labels

noise: centered (biasless)

↓
quantify similarity

↓
show: NTK



$$\sum_i \|f(x_i) - y_i\|^2$$

$$\rightarrow P(x) = \bar{y} + \frac{1}{N} \sum_{i=1}^N \text{similar samples}$$

