

Learning Shape Metrics based on Deformations and Transport

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Introduction

Motivation : shape metrics : needed for shape evolutions, shape matchings, shape priors...; how to choose **the right metric** ?

Aim : estimate a suitable metric automatically from a training set of shapes

Difficulties :

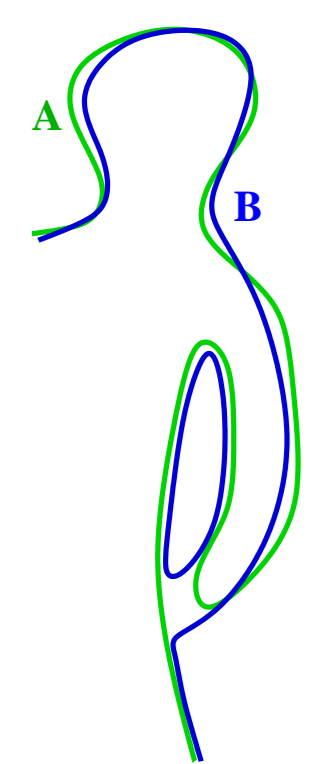
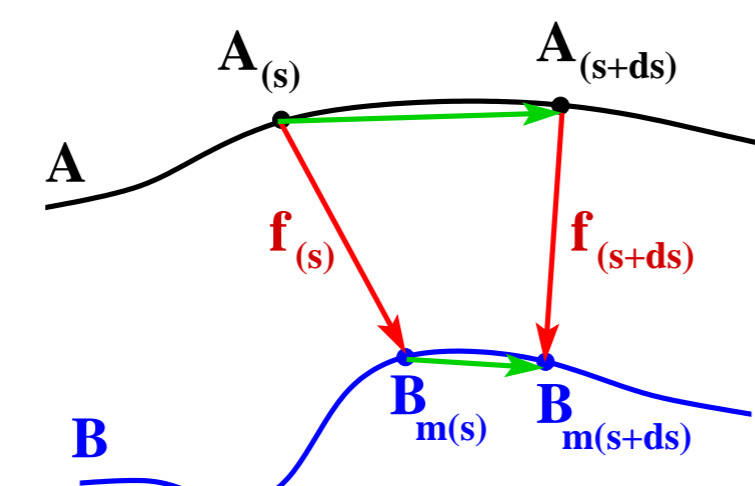
- sets of shapes : **high-dimensional** and **sparse** (human silhouettes ≥ 30 dim.)
- much **variability** : no meaningful *mean* shape
- probable deformations differ depending on the shape of interest
- no reliable matching between very different shapes; topological changes
- kernel methods : no explicit deformation priors + unaffordable density (high dim.)

Method : search for the **optimal metrics**, based on:

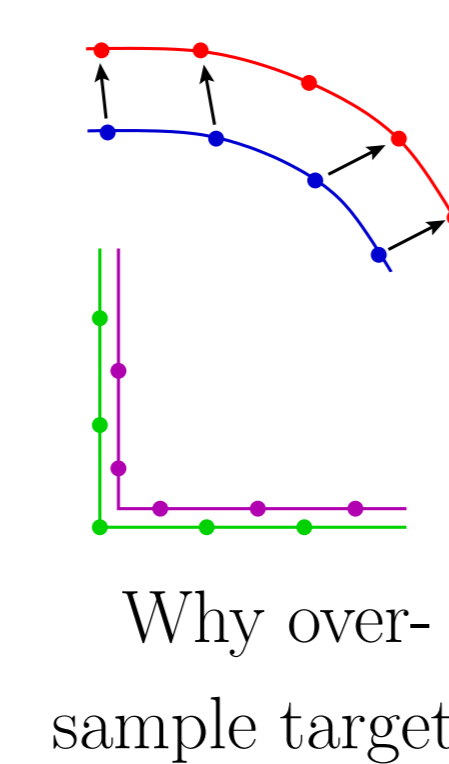
- **matchings between close shapes**, possibly **topologically different**
- **transport**, from matchings, with **reliability weights**
- **increased density** with transported deformations
- **inner products fit empirical distributions** of deformations (local PCAs)
- regularizer : *shape* \mapsto *metric* is **smooth** for Kullback-Leibler div.
- result is **global optimum of a criterion on metrics**

Matching close shapes

$$E_{\text{match}}(m) = \|B \circ m - A\|_{H^1}^2 + \gamma \|\angle(\mathbf{n}_A, \mathbf{n}_{B \circ m})\|_{L^2}^2$$



- Optimization : dynamic time warping
- Possible matching to \emptyset (vanishing points)
- Oversampling of targets
- Convergence proof in the simple case when sampling rates get finer



Why over-sample targets.

Link between Kullback-Leibler and PCA

In the tangent space of one shape :

Empirical distribution of deformations : $\mathcal{D}_{\text{emp}} = \sum_j w_j \delta_{\mathbf{f}_j}$
possibly smoothed by a kernel : $\mathcal{D}_{\text{emp}}^{\mathcal{K}}(\mathbf{f}) = \sum_j w_j \mathcal{K}(\mathbf{f}_j - \mathbf{f})$

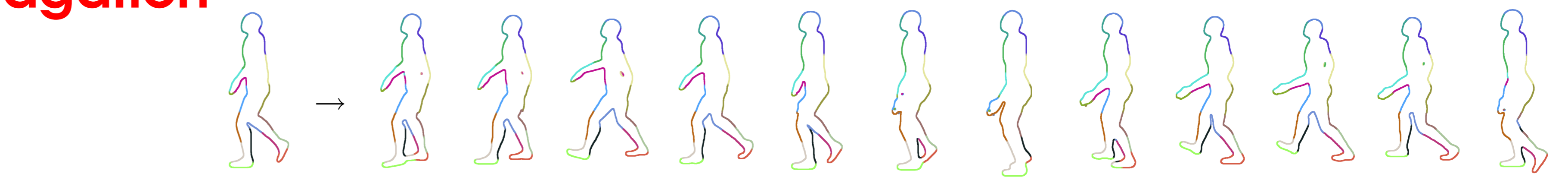
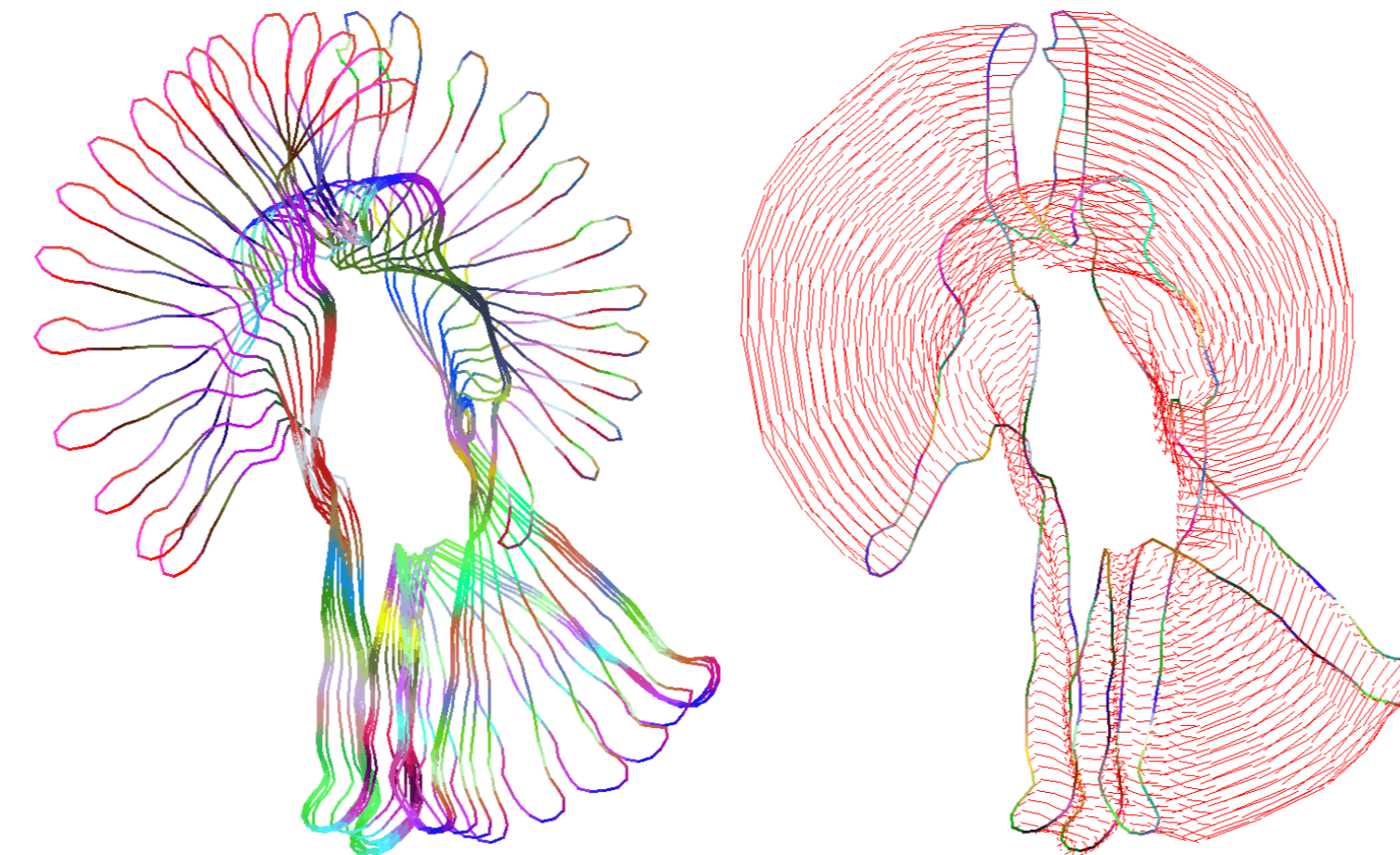
Given an inner product of reference P_0 (here H^1_α),

Inner product P (\mathcal{C}^0 wrt. P_0) = Gaussian distribution : $\mathcal{D}_P(\mathbf{f}) \propto e^{-\|\mathbf{f}\|_P^2}$

$\inf_P KL(\mathcal{D}_P | \mathcal{D}_{\text{emp}}^{\mathcal{K}}) \implies P_0$, weighted PCA(\mathbf{f}_j, w_j)

In case of \mathcal{K} , add second moment matrix of \mathcal{K} to correlation matrix

Transport : information propagation



Set of shapes (S_i) \implies weighted graph

Pairwise matching costs : $C_{ij}^m = E_{\text{match}}(m_{i \rightarrow j})$

Local transport : $\forall h : S_j \rightarrow \mathcal{X}$,

$$T_{S_j \rightarrow S_i}^L(h) : S_j \rightarrow \mathcal{X} : s \mapsto h(m_{i \rightarrow j}(s))$$

Reliability : $w_{ij}^L = e^{-\alpha r C_{ij}^m}$

Optimal path from S_{i_0} to S_{j_0} : $(i_0, i_1, \dots, i_k = j_0)$

$$C_{i_0 j_0}^G = \sum_n C_{i_0 i_{n+1}}^m$$

Possibility of individualized paths $C_{ij}^m(h)$

Optimal transport : $T_{i_0 \rightarrow j_0}^G = T_{i_{k-1} \rightarrow j_0}^L \circ \dots \circ T_{i_1 \rightarrow i_2}^L \circ T_{i_0 \rightarrow i_1}^L$

Reliability : $w_{ij}^G = e^{-\alpha r C_{ij}^G}$ (series of small reliable steps)

Inner products : deformation priors



Samples from the training set (video, 9s, 24Hz)

Local deformations : $\mathbf{f}_{i \rightarrow j} = S_j \circ m_{i \rightarrow j} - S_i$

Shape of interest : S_k

Transport : $\mathbf{f}_{i \rightarrow j}^k = T_{i \rightarrow k}(\mathbf{f}_{i \rightarrow j})$, $w_{i \rightarrow j}^k = w_{ij}^L w_{ik}^G$

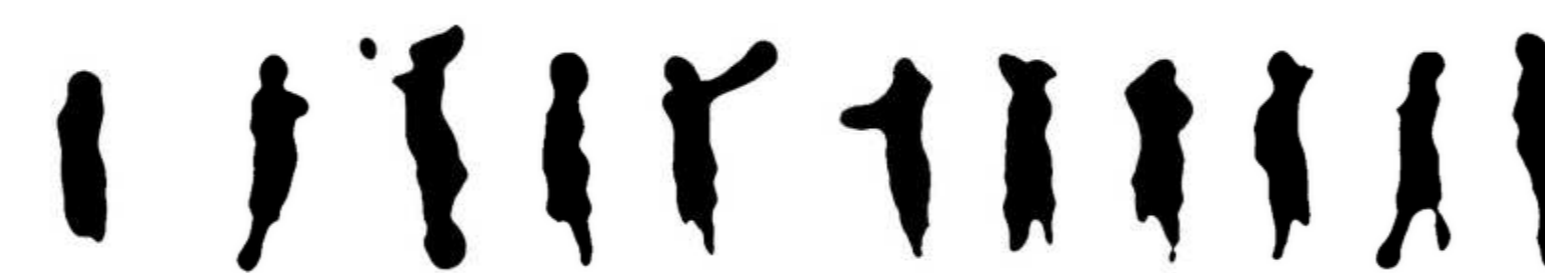
Modes from H^1_α , weighted PCA :

$$\inf_{\langle \mathbf{e}_n | \mathbf{e}_n \rangle_{H^1_\alpha} = \delta_{n=n'}} \sum_{i,j} w_{i \rightarrow j}^k \left\| \mathbf{f}_{i \rightarrow j}^k - \sum_n \langle \mathbf{f}_{i \rightarrow j}^k | \mathbf{e}_n \rangle_{H^1_\alpha} \mathbf{e}_n \right\|_{H^1_\alpha}^2$$

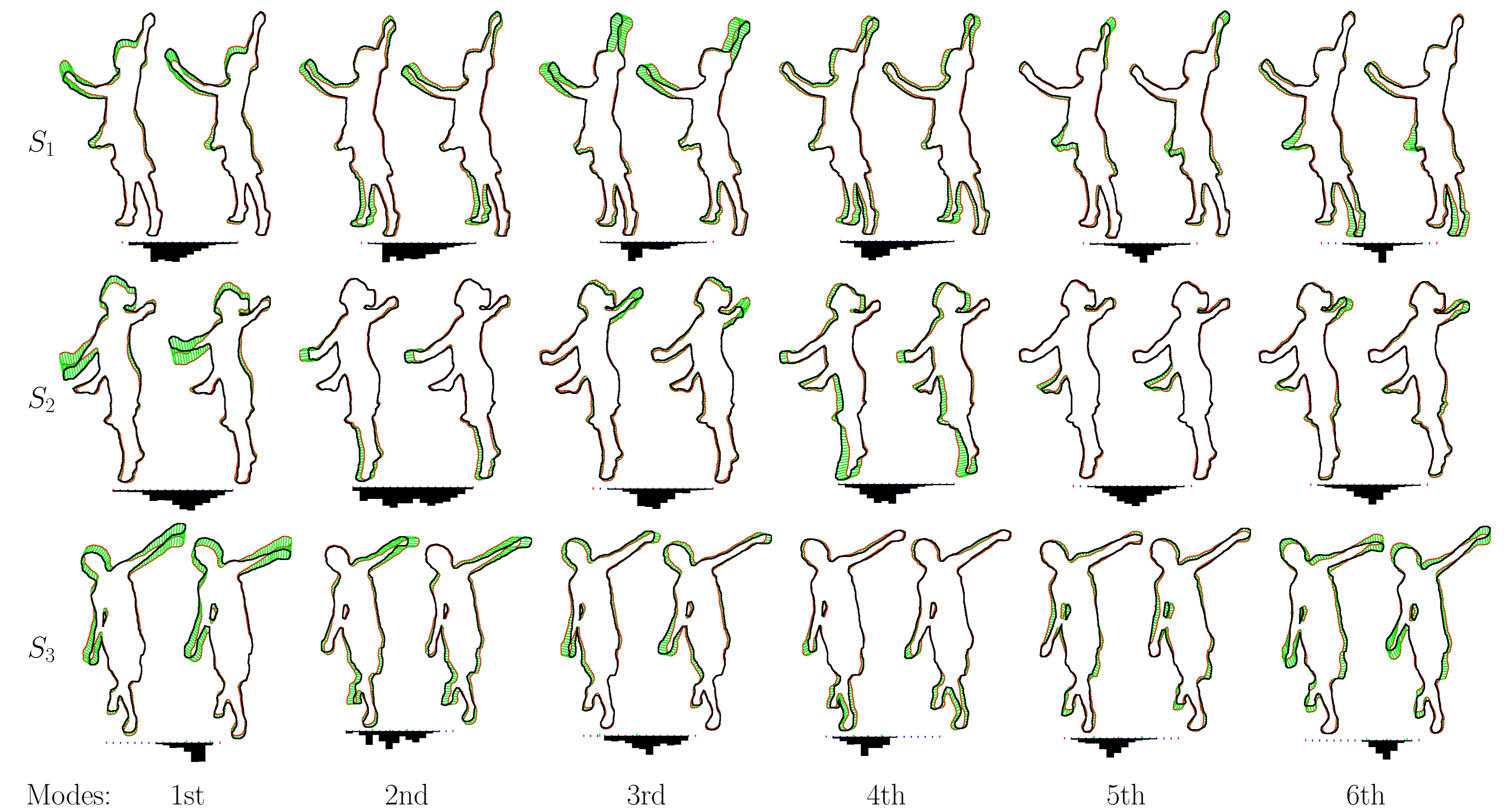
Modes $(\mathbf{e}_n, \lambda_n) \implies$ inner product $\langle \cdot | \cdot \rangle_{P_k}$

Use of inner products as shape matching energy :

$$\inf_{m, \vec{a}} C(\vec{a}) + \frac{1}{\lambda_{\text{noise}}^2} \left\| B \circ m - A - \sum_n a_n \mathbf{e}_n \right\|_{H^1_\alpha}^2$$



Comparison: PCA on level-sets: mean + first modes



Modes: 1st 2nd 3rd 4th 5th 6th

Optimum of a criterion on metrics

In general, **no best smooth direction field** (hairy ball theorem)

Criterion for a smooth metric: $\sum_{i,k} w_{ik}^G KL(\mathcal{D}_{P_k} | T_{i \rightarrow k}(\mathcal{D}_{\text{emp}_i}))$

with $\mathcal{D}_{\text{emp}_i} = \sum_j w_{ij}^L \delta_{\mathbf{f}_{i \rightarrow j}}$ and $T_{i \rightarrow k}(\delta_{\mathbf{f}}) = \delta_{T_{i \rightarrow k}(\mathbf{f})}$

$= \sum_k KL(\mathcal{D}_{P_k} | \mathcal{D}_{\text{emp}_k}^T)$, sum of independent terms, where $\mathcal{D}_{\text{emp}_k}^T = \sum_{i,j} w_{i \rightarrow j}^k \delta_{\mathbf{f}_{i \rightarrow j}^k}$

\implies our inner products

Criterion for smooth probability distributions:

$$\inf_g \sum_i \|g_i - g_i^0\|_{L^2(T_i)}^2 + \sum_{ij} w_{ij} \|T_{i \rightarrow j}(g_i) - g_j\|_{L^2(T_j)}^2$$

with $g_i = d\mathcal{D}_{P_i}/d\mu$, $g_i^0 = d\mathcal{D}_{\text{emp}_i}/d\mu$

Inner products that best fit the optimal $g \implies$ ours

Discussion

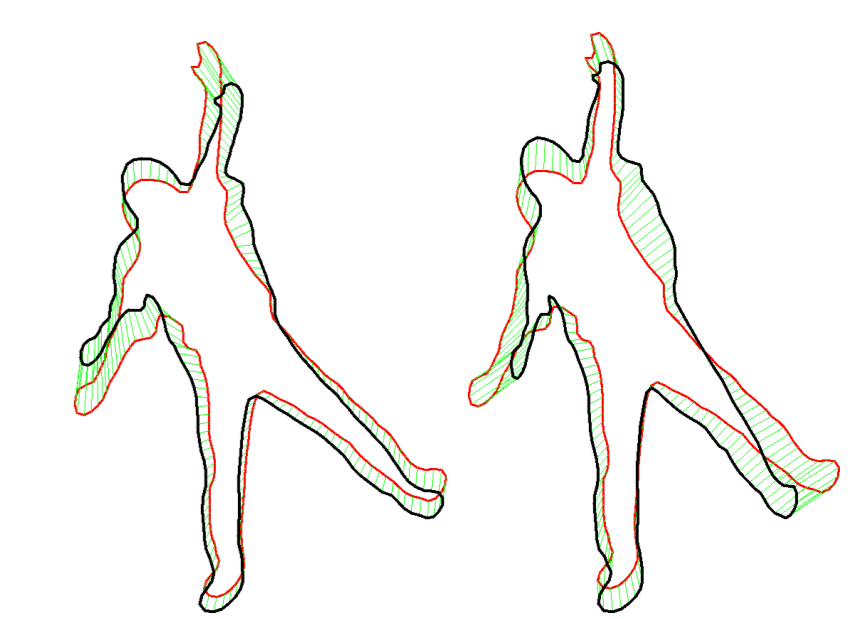
	require a mean	handle high variability	global coherency	handle sparse sets	explicit deformation prior	criterion on metrics
mean + modes (PCA)	yes	no	-	-	yes	yes
kNN + local PCAs	no	yes	no	no	yes	no
kernels on distances	no	yes	yes	no	no	yes
transport + KL reg.	no	yes	yes	yes	yes	yes

Conclusions :

- Transport = density enhancer, more representative neighborhoods

- Particular suitability to video datasets

- Link Kullback-Leibler \iff PCA



5NN and 10NN means