



I A O

# Inference, Apprentissage & Optimisation

Head: Michele Sebag

Joint INRIA project



UNIVERSITÉ  
PARIS-SUD 11





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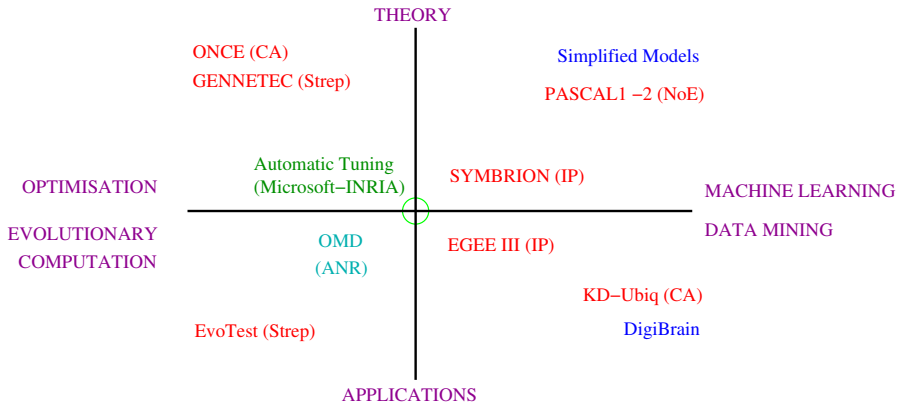
Fabien Teytaud

Xiangliang Zhang

10PhDs defended → 2 MdC; 3 post-docs; 4 engineers



# Scientific Themes / Objectives



Optimization for Machine Learning – Machine Learning for Optimization



# Optimal Decision Under Uncertainty

## Monte-Carlo Tree Search

In each position (search tree):

1. Select a move *Multi-armed Bandits*
2. Assess it using a “default partner”

*Monte-Carlo*

3. Update reward



$$\text{Select arg max } \hat{\mu}_i + \sqrt{\frac{\log \sum_j n_j}{n_i}}$$

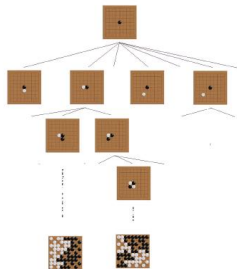
## Applications

- MoGo
- Active Learning
- News Web site

ICML 2007, Gelly PhD 07

Simplified Models

won OTEE Pascal Challenge



## Collaborations

INRIA-Sequel

University of Alberta

CEA-DM2S

LRI Parall, Bull, Microsoft



# Contributions to Evolutionary Computation

- ▶ Convergence of Evolution Strategies as Markov Chain TCS 05
- ▶ Consistency of Genetic Programming - regularization RIA 06
- ▶ Lower Bounds for Comparison-based Algs PPSN 06, ECJ 08
- ▶ Derandomization PPSN 06
- ▶ Continuous Lunches are Free ! GECCO 07, Algorithmica 09
- ▶ Robustness w.r.t. condition number CEC Challenge 05; GECCO 08
- ▶ Robustness w.r.t. noise PPSN 08, Jebalia PhD 08
- ▶ Approximate Dynamic Programming Gelly PhD 07, OpenDP platform 07

## Collaborations

ETH Zurich  
Lab. Maths UPS  
U. Dortmund

## Transfert

OMD, EADS, Renault, Dassault,  
Thalès  
EZCT



## Log-Linear Convergence of Evolution Strategies

TCS 05

Drift conditions for Harris-recurrent Markov Chains:

First proof of convergence on actual Self-Adaptive ES

⇒ Optimal rate

ECJ 08

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## Genetic Programming == EC on space of programs

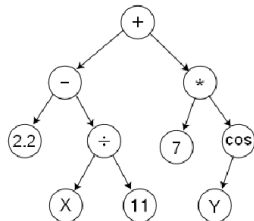
RIA 06

Limitation: bloat

uncontrolled solution growth

Results:

- $VC(\text{pgm with } k \text{ nodes}) \leq F(k)$
- Penalization with  $R(k).R'(n)$ :  
a.s. Universal Consistency and no-bloat



$$\left(2.2 - \left(\frac{X}{11}\right)\right) + (7 * \cos(Y))$$



# Contributions to Machine Learning/Data Mining

- ▶ Regularisation for Graphical Models Gelly PhD 07
- ▶ Dynamic Multi-Armed Bandits CAP 07
- ▶ Data Streaming with Affinity Propagation ECML 08
  
- ▶ Ensemble Feature Ranking Mary PhD 05
- ▶ Spatio-Temporal D.Mining / MultiObjective Opt. IJCAI 05, PPSN06
- ▶ Learning Kernels, Learning Ensembles PPSN06, GECCO 07
  
- ▶ Competence Maps IJCAI 05, Maloberti PhD 05, ILP 07
- ▶ Active Learning in a Graph IJCAI 07, Baskiotis PhD 08

## Collaborations

La Pitié Salpêtrière  
EPFL  
U. Laval, Quebec  
U. Sapporo, Japan

## Wshops

2nd Pascal Challenges Wshop 06  
Multiple Simultaneous Hypothesis Testing 07  
Large Scale Learning Challenge 08



## Ensemble Feature Ranking

Mary PhD 05

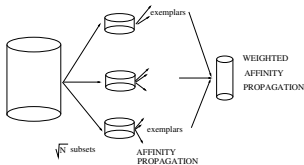
Theorem: Let  $O_t$  be a r.v. ranking /  $Pr((Err(i, j, O_t)) < 1/2 - \epsilon)$   
 Then  $\tilde{O} = Aggr(O_1, \dots, O_T)$  is consistent, with  
 $Pr(|rank_{\tilde{O}}(i) - rank^*(i)| > k)$  exponentially small with  $k$  and  $T$

## Data Streaming with Affinity Propagation

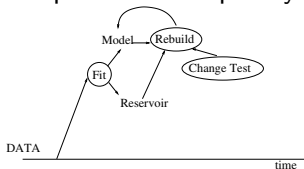
ECML 08

Affinity Propagation: Frey & Dueck 07

+ no artefact, stable optimization, – quadratic complexity.



Hierarchical AP ( $n^{\frac{3}{2}}$ )



Non-stationary AP



# Applications - 1. Representations/Search Spaces

## Shape representations

coll. U. San Luis, EZCT

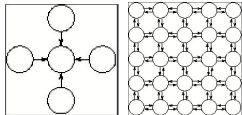
GECCO 05, PhD Kavka, PhD Singh

Voronoi



## Developmental representations

coll. MIT, GECCO 07



gen 79



82



89

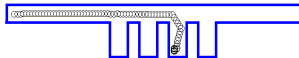


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## Reservoir Computing

coll. INRIA-Alchemy, LIMSIS

Solving the Tolman maze





## Scheduling and Reinforcement Learning

ICAC08

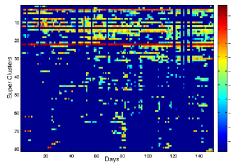
Multi-objective rewards  
Continuous representation of users.

$$Q_t(s, a) = Q_{t-1}(s, a) + \alpha(r + \gamma Q_{t-1}(s', a') - Q_{t-1}(s, a))$$

## Job streaming and profiling

ECML08

Build snapshots  
Build chronicles





## Extended Bandits

Dynamic environments  
Delayed and partial rewards  
Multi-objective rewards  
Multi-variate bandits  
Bounded Reasoning

won OTEE Challenge

PASCAL

Exploration vs Safety

Junction with RL

Finite horizon



## Swarm Robotics

Decentralized control  
Robotics Log Mining

SYMBRION IP; Coll. U. Kyushu, Japan



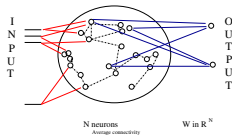


# Longer-term Perspectives

## Hardware-aware Software

Coll. Alchemy, GECCO08, ECML08

Algorithms as fixed point systems  
Reservoir computing

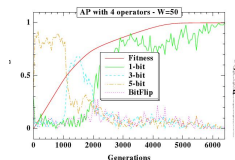


## Crossing the Chasm

Joint INRIA-Microsoft project

PPSN08, GECCO08

Parameter/Alg. Selection  
Multi-Armed Bandits  
Change Test Detection





# Summary 2005-2008

Training 10 PhDs, 2 HdRs

Publications 190 papers (9 A+ ; 43 A) ; 1 patent (IFP)

## Animation

2nd Pascal Challenge Wshop 2006  
Dagstuhl Seminar on EC theory 2008  
Multiple Simultaneous Hypothesis Testing, Pascal Wshop 2007  
Large Scale Learning Challenge & Wshop 2008  
Franco-Japanese Wshops: Sapporo 2007, Paris 2008.  
Apprentissage: la carte, le territoire et l'horizon, 2008

## Evaluation

Editorial Boards: 8 journals (ECJ MIT, editor in chief)  
PC: All major international conf. in ML & EC

Contracts 1 861 k€

