M1 - Apprentissage

Michèle Sebag – Benoit Barbot LRI – LSV

Sept. 2013

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Where we are



You are here





You are here

Harnessing Big Data



Watson (IBM) defeats human champions at the quiz game Jeopardy (Feb. 11)

i 1 2 3 4 5 6 7 8 1000^{*i*} kilo mega giga tera peta exa zetta yotta bytes

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- Google: 24 petabytes/day
- Facebook: 10 terabytes/day; Twitter: 7 terabytes/day
- Large Hadron Collider: 40 terabytes/seconds

Types of Machine Learning problems

$\mathsf{WORLD} - \mathsf{DATA} - \mathsf{USER}$

Observations	+ Target	+ Rewards
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Understand	Predict	Decide
Code	Classification/Regression	Action Policy/Strategy
Unsupervised	Supervised	Reinforcement

LEARNING

LEARNING

Reinforcement LEARNING

Supervised Machine Learning





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MNIST

Yann Le Cun, since end 80s

Fig. 4. Size-normalized examples from the MNIST database.

The 2005-2012 Visual Object Challenges

A. Zisserman, C. Williams, M. Everingham, L. v.d. Gool







Supervised learning, notations

Input: set of (\mathbf{x}, y)

- An instance \mathbf{x} e.g. set of pixels, $\mathbf{x} \in {\rm I\!R}^D$
- A label y in $\{1, -1\}$ or $\{1, \dots, K\}$ or ${\rm I\!R}$

Supervised learning, notations

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Pattern recognition

Classification Does the image contain the target concept ?

$$h: \{ \mathsf{ Images} \} \mapsto \{1, -1\}$$

Detection Does the pixel belong to the img of target concept?

$$h: \{ \text{ Pixels in an image} \} \mapsto \{1, -1\}$$

Segmentation

Find contours of all instances of target concept in image

Unsupervised learning

Clustering avemaria branden HOMPLES frozen lovsisintheair ellaca. vm-bash kielsoene beethoven fuguedminor therose វេរវរាទ dancingqueen manicmonday lovemetender fatherandson foreveryoung conga mindfiels rainbow threetimesalady eternalflame californiadream firsttime unigreakinyheart ironic sexbomb revolution Risingsun americanpie bfmc_ffeestyler CO-DOSDEED angels lifernication rhep-work missathing sl-summertime sl-whatigot vesterday-b addict limp-gebody limp-n2gether bongobong pebroken newwork korn-freak ofme-instere limp-pollution ofme-rocking blaworld lovedwoman ga-iwanfi acaren afine-skylinit pr-revenc bfme-uprocking

http://www.ofai.at/ elias.pampalk/music/

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Unsupervised learning, issues

Hard or soft ?

- Hard: find a partition of the data
- Soft: estimate the distribution of the data as a mixture of components.



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Parametric vs non Parametric ?

- Parametric: number K of clusters is known
- ▶ Non-Parametric: find K

(wrapping a parametric clustering algorithm)

Unsupervised learning, 2



Netflix Challenge 2007-2008

Collaborative filtering, notations

Input

- A set of users
- A set of movies
- ► A n_m × n_u matrix: person, movie, rating Very sparse matrix: less than 1% filled...

Output

Filling the matrix !

n_u, ca 500,000 *n_m*, ca 18,000

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Collaborative filtering, notations

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Output

Filling the matrix !

Criterion

- (relative) mean square error
- ranking error

Reinforcement learning



Reinforcement learning, notations

Notations

- State space S
- Action space \mathcal{A}
- Transition model $p(s, a, s') \mapsto [0, 1]$
- Reward r(s)

Goal

• Find policy $\pi: \mathcal{S} \mapsto \mathcal{A}$

Maximize $E[\pi] =$ Expected cumulative reward

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(detail later)

Some pointers

- My slides: http://tao.lri.fr/tiki-index.php?page=Courses
- Andrew Ng courses: http://ai.stanford.edu/~ang/courses.html
- PASCAL videos http://videolectures.net/pascal/
- Tutorials NIPS Neuro Information Processing Systems http://nips.cc/Conferences/2006/Media/
- About ML/DM http://hunch.net/

This course

WHO

Michèle Sebag, machine learning

WHAT

- 1. Introduction
- 2. Supervised Machine Learning
- 3. Unsupervised Machine Learning
- 4. Reinforcement Learning

WHERE: http://tao.lri.fr/tiki-index.php?page=Courses

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LRI

Exam

Final:

- Questions
- Problems

Volunteers

Some pointers are in the slides More ?

here a paper or url

 Volunteers: read material, write one page, send it (sebag@lri.fr), oral presentation 5mn.

Overview

The roots of $\mathsf{ML}:\mathsf{AI}$

AI as search

AI and games

Promises?

What's new



Roots of Al

Bletchley

- Enigma cypher 1918-1945
- Some flaws/regularities
- Alan Turing (1912-1954) and Gordon Welchman: the Bombe



Colossus

Dartmouth: when AI was coined



We propose a study of artificial intelligence [..]. The study is to proceed on the basis of the conjecture that **every aspect of learning or any other feature of intelligence** can in principle be so precisely described that a machine can be made to simulate it.

An attempt will be made to find how to make machines use language, form abstraction and concepts ... and improve themselves.

Dartmouth: when AI was coined



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We propose a study of artificial intelligence [..]. The study is to proceed on the basis of the conjecture that **every aspect of learning or any other feature of intelligence** can in principle be so precisely described that a machine can be made to simulate it.

An attempt will be made to find how to make machines use language, form abstraction and concepts ... and improve themselves. John McCarthy, 1956

Before AI, the vision was there:



Machine Learning, 1950 by (...) mimicking education, we should hope to modify the machine until it could be relied on to produce definite reactions to certain commands.

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Before AI, the vision was there:



More ?

http://www.csee.umbc.edu/courses/471/papers/turing.pdf

Machine Learning, 1950 by (...) mimicking education, we should hope to modify the machine until it could be relied on to produce definite reactions to certain commands.

How ?

One could carry through the organization of an intelligent machine with only two interfering inputs, one for pleasure or reward, and the other for pain or punishment.

The imitation game

The criterion:

Whether the machine could answer questions in such a way that it will be extremely difficult to guess whether the answers are given by a man, or by the machine

Critical issue

The extent we regard something as behaving in an intelligent manner is determined as much by our own state of mind and training, as by the properties of the object under consideration.

The imitation game, 2

A regret-like criterion

- Comparison to reference performance (oracle)
- More difficult task \Rightarrow higher regret

Oracle = human being

- Social intelligence matters
- Weaknesses are OK.



Great expectations ! Promises

1955 : Logic Theorist

Newell, Simon, Shaw, 1955

- Reading Principia Mathematica
 - Whitehead and Russell, 1910-1913 ... an attempt to derive all mathematical truths from a well-defined set of axioms and inference rules in symbolic logic
- General Problem Solver

Newell, Shaw, Simon, 1960

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Within 10 years, a computer will

- be the world's chess champion
- prove an important theorem in maths
- compose good music
- set up the language for theoretical psychology

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Position of the problem

Symbols	Operators
numbers	2 + 2 = 4
concepts	$A, \ A o B$ $\models B$

Symbol manipulation

- Numbers and arithmetic operators interpretation (+, ×, ...) Arithmetics, Constraint Satisfaction
- Concepts, logical operators
 - Propositional
 Inference, Constraint Satisfaction
 - Relational + unification (man(X), mortal(X), man(Socrates))

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Logic programming
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Unification + Interpretation = Constraint Programming

Symbolic calculus: ingredients

Reasoning; navigate in a search tree

- States; tree nodes
- Navigation: select operators (= edges)

How

- Select promising operators
- Evaluate a state node
- Prune the search tree

Languages

- Lists
- Actions

IPL, Lisp, Prolog

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Artificial Intelligence as Search



Inference

Deduction

 $A, A \rightarrow B$ Modus ponens $\neg B, A \rightarrow B$

 $\models B$

 $\models \neg A$

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Modus tollens

Comment

- \blacktriangleright Truth preserving \models
- Which déduction

More ?

http://homepages.math.uic.edu/ kauffman/Robbins.htm

Inference, 2

$\begin{array}{l} \text{Induction} \\ \neg A, B \\ (\text{inference}) \ A \rightarrow B \end{array}$

Inference, 2

$\begin{array}{l} \text{Induction} \\ \neg A, B \\ (\text{inference}) \ A \rightarrow B \end{array}$

Correlation & causality

- Many tuberculous people die in mountain regions
- Therefore ?



$\begin{array}{c} \textbf{Abduction} \\ B, \ A \to B \\ (\text{inférence}) \ A \end{array}$



Abduction $B, A \rightarrow B$ (inférence) A

Multiple causes

- Drunk \rightarrow Staggering. And you're staggering.
- Therefore ?

Halt

1972 : Winter Al

Dreyfus report

- Driving application: automatic translation
- Conjecture: cannot be syntactical (one must understand)
 - Paul is on the bus way; he is a friend; I push him (away)
 - Paul is on the bus way; he is an ennemy; I push him (under)

Discussion

- Everyone is able of deduction; the expert is able of reasoning
- ► The chinese room Sear

Turing test

Searle, "strong AI"

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Artificial Intelligence as Search



Expert systems



SYSTEME EXPERT

At the core of ES

- Knowledge base $A \rightarrow B$
- Inference engine
 inference

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Expert systems



Lessons learned

Declarative style

From orders/instructions to statements

Success

- Dendral: organic chemistry
- Mycin: medicine
- Molgen: molecular biology
- R1: computer assembly

Limitations

- Decreasing returns
- Human factors
- Statements...

Bottleneck

Where do the knowledge base come from ?

Feigenbaum et al. 60s Shortliffe, 76

Stefik, 81

McDermott, 82

but control needed

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Artificial Intelligence as Search



Why games ?

- Micro-worlds
- Simple rules
- Profound complexity

finite number of states, actions known transitions (no simulator needed) proof of principle of AI



MiniMax algorithm: brute force

backward induction; Nash equilibrium

The algorithm

- 1. Deploy the full game tree
- 2. Apply utility function to terminal states
- 3. Backward induction
 - On Max ply, assign max. payoff move
 - On Min ply, assign min. payoff move
- 4. At root, Max selects the move with max payoff.



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MiniMax algorithm: brute force

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Comments

- Perfect play for deterministic, perfect information games
- Assumes perfect opponent
- Impractical: time and space complexity in $\mathcal{O}(b^d)$



Alpha-Beta: MiniMax with pruning

alphabeta(node, depth, α , β , Player)

- if depth = 0, return H(node)
- if Player = Max
 For each child node,

 $\alpha := max(\alpha, \mathsf{alphabeta}(\mathsf{child}, \, \mathsf{depth-1}, \alpha, \beta, \mathsf{not}(\mathsf{Player})))$

- $\begin{array}{ll} \mbox{if } \beta \leq \alpha \mbox{, cut} & \mbox{ beta cut-off} \\ \mbox{return } \alpha \end{array}$
- if Player = Min
 For each child node,



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 $\beta := min(\beta, alphabeta(child, depth-1, \alpha, \beta, not(Player)))$

 $\begin{array}{ll} \text{if } \beta \leq \alpha \text{, cut} & \quad \textit{alpha cut-off} \\ \text{return } \beta & \end{array}$

Alpha-Beta: MiniMax with pruning

Comments

- Pruning does not affect final result
- Good move ordering \rightarrow complexity $\mathcal{O}(b^{\frac{d}{2}})$
- Same as √branching factor for chess: 35 → 6.



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Chess: Deep Blue vs Kasparov

Ingredients

- Brute force; 200 million positions per second
- Look-ahead 12 plies
- Alpha-beta
- Tuning the heuristic function on a game archive
- Branching factor b ~ 35 good move ordering b ~ 6

Controversy

http://www.slideshare.net/toxygen/ kasparov-vs-deep-blue





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Dynamic programming

Principle

- Recursively decompose the problem in subproblems
- Solve and propagate

An example



Dynamic programming & Learning



Backgammon

Gerald Tesauro, 89-95

- State: raw description of a game (number of White or Black checkers at each location)
- Data: set of games
- ► A game: sequence of states x₁,...x_T; value on last y_T: wins or loses

Dynamic programming & Learning



Learning

• Learned:
$$F : \mathbb{R}^D \mapsto [0, 1]$$
 s.t.

Minimize
$$|F(x_T) - y_T|$$
; $|F(x_\ell) - F(x_{\ell+1})|$

Search space: F is a neural net = w
 Learning rule
 200,000 games

$$\Delta w = \alpha (F(x_{\ell+1}) - F(x_{\ell})) \sum_{k=1}^{\ell} \lambda^{\ell-k} \nabla w F(x_k)$$

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La promesse (1960)

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The world's chess champion ?





Discussion

Entre intelligence et force brute.

Prouver un théorème ?



The robot scientist

- ▶ Faits → Hypothèses
- ► Hypothèses → Expériences
- ► Expériences → Faits
- King R. D., Whelan, K. E., Jones, F. M., Reiser, P. G. K., Bryant, C. H., Muggleton, S., Kell, D. B. and Oliver, S. G. (2004) Functional genomic hypothesis generation and experimentation by a robot scientist. Nature 427 (6971) p247-252
- King R.D., Rowland J., Oliver S.G, Young M., Aubrey W., Byrne E., Liakata M., Markham M., Pir P., Soldatova L., Sparkes A., Whelan K.E., Clare A. (2009). The Automation of Science. Science 324 (5923): 85-89, 3rd April 2009

Composer de la bonne musique ?

Musac

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Set up the language for theoretical psychology ?





Neuro-imagerie – Interfaces Cerveau-Machine

Set up the language for theoretical psychology ?



Test d'hypothèses multiples

http://videolectures.net/msht07_baillet_mht/

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AI: The map and the territory



The 2005 DARPA Challenge

Al Agenda: What remains to be done Thrun 2005 Reasoning Dialog Perception



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AI: Complete agent principles

Rolf Pfeiffer, Josh Bongard, Max Lungarella,

Jurgen Schmidhuber, Luc Steels, Pierre-Yves Oudeyer...

Situated cognition

Intelligence: not a goal, a means

brains are first and foremost control systems for embodied agents, and their most important job is to help such agents flourish.

Agent's goals: Intelligence is a means of

- Surviving
- Setting and completing self-driven tasks
- Completing prescribed tasks

What are the designer's goals ?

Research modes

Historical AI

- Identify sub-tasks
- Solve them

Bounded rationality

In complex real-world situations, optimization becomes approximate optimization since the description of the real world is radically simplified until reduced to a degree of complication that the decision maker can handle.

Satisficing seeks simplification in a somewhat different direction, retaining more of the detail of the real-world situation, but settling for a satisfactory, rather than approximate best, decision. Herbert Simon, 1982

Lessons from 50 years

- We need descriptive knowledge: perceptual primitives, patterns, constraints, rules,
- ► We need control knowledge: policy, adaptation
- Knowledge can hardly be given: must be acquired
- We need interaction knowledge: retrieving new information, feedback

Meta-knowledge

J. Pitrat, 2009

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- Each goal, a new learning algorithm ?
- Problem reduction ? John Langford, http://hunch.net/

Artificial Intelligence

Search space	ML	
 Representation 	(Un) Supervised L.	
 Patterns, Rules, Constraints 	(knowledge) (Un) Supervised L. Data Mining	
 Navigation policy 	Reinforcement L.	
Navigation		
► Inference	Optimisation	
Validation, control, feedback		
► Criteria	Statistics	

Questions

- Document: Perils and Promises of Big Data http://www.thinkbiganalytics.com/uploads/Aspen-Big_Data.pdf
- Quand les données disponibles augmentent qu'est-ce qui est différent ?
- Des limitations ?