

Machine Learning for Constraint Solving

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Position of the problem

Algorithms, the vision

- Software editor vision : A GO button
- Researcher vision : more is better

add other functionalities (with control parameters)

 Community vision : different is interesting devise new algorithms (with control parameters)

Crossing the chasm : software life beyond research labs

- Automatically adjust algorithm parameters depending on current problem
- Select best (expected) algorithm depending on current problem

Meta-Learning



Meta-learning

for ML

Select automatically best ML algorithm

Bradzil, Bensoussan, Giraud-Carrier, Kalousis, Kietz, Maloberti...

Main difficulty : devise problem descriptors

for Evolutionary Computation

Adjust on-line operator rates

Thierens et al 07, 08; Fialho et al. 08, 09, 10

 Main difficulty : devise operator "reward" ; adjust operator rate depending on its reward (Exploration vs Exploitation).

for Constraint Solving

Rice 1976

- Context : Microsoft / INRIA / CNRS
- Give the user the best performance she can get



- State of the art
- 2 Goal
- 3 The algorithm : lifelong learning
- 4 Results
- 5 Discussion & perspectives



Notations

- Variables X₁...X_n
- X_i belongs to domain D_i
- Constraints C₁...C_m
 - in closed form : $X_i + X_j = X_k$; all different $(X_1, X_2, ...)$
 - in extension : $C(X_1, X_2)$ holds for $\{(1, 2), (2, 1), \ldots\}$.

Example : Sudoku

	1	2	3	4	5	6	7	8	9
1	8					1		4	
2	2	VI-	6	8	12	2		13	3
3			9			6		8	
4	1	2	4						9
5		V/2			15	5		VIE	5
6	9						8	2	4
7	_	5		4			1		
8		8	ľ		78	8	2	VIS	5
9		9		5					7

Variables	$X_{11}\ldots X_{99}$
Domains	$D_i = \{1 \dots 9\}$
Constraints	All different $(X_{1,i} \dots X_{9,i})$

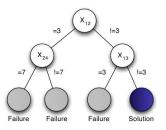


Formal background, 2

Types of problem

- Constraint Solving
- Constraint Satisfaction
- Constraint Optimization
- Quantified Boolean Formulae

complete and incomplete search boolean domains min. # constraints insatisfied Benedetti, Mangassarian 08



select variable

select value





Some heuristics

Value selection Variable selection

- mindom
- domdeg
- weighted degree and wdomdeg
- score(variable)
- Novelty
- Novelty+ : wp Novelty + (1 wp) WalkSat Hoos 99 Novelty+p : with anticipation Li Wei Zhang 07
- Adaptive Novelty+ : tune wp depending on history Hoos 02
- Scaling and Probability Smoothing (weighting clauses) Hutter Tompkins Hoos 02, Li Wei Zhang 07

min, max, mid, random

First Fail Principle

Boussemart et al 04

Selman Levêque Mitchell 92

McAllester Selman Kautz 97



Some other heuristics

Restart schedule

 $(t_1, H_1, t_2, H_2, \ldots)$

- spend t_1 with H_1 (cutoff time)
- then increase cutoff time (often $t_{i+1} = c \times t_i$), and use another heuristics.

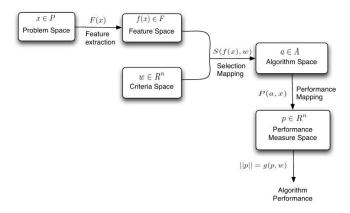
Note that using H_i might modify the choices for H_{i+1} .

Other

Use a taboo list in incomplete search



After Rice 1976



Importance of pbs descriptors



Meta-Search Approaches

Characterize runtime

short vs long predict runtime (Empirical Hardness Model) Horvitz et al. 01

Nudelman et al. 02, 04, 09 Haim & Walsh 08, 09

predict time-to-solution

SATzilla : given problem instances

- training : collect (instance description, solver performance)
- testing : identify candidate solvers; run all of them for short time; run the expected best one.
- Extensions : mixture of experts Xu et al. 07 other ML approaches Devlin and O'Sullivan 08



Meta-Search Approaches, 2

CP Hydra

O'Mahony et al. 08

- portfolio + case-based reasoning
- build an archive of cases (problem instances)
- for a new instance, find k-nearest neighbor cases
- build a switching policy, running and stopping black-box solvers

Description

- Syntactic features (XSCP specifications)
- Semantic features : use a preliminary testing phase (2s) and collect general search statistics
- Pragmatic features
 Beck Freuder 04
 (Time *I*, algo *A*) = 1 iff *A* yields best solution at *I*.
 (learning curve slope for each algo).



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No Free Lunch

There is no such thing as a Universal Best CP strategy

The need

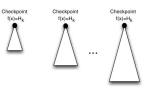
- Each user has a specific distribution of problem instances
- There exists a best strategy for this problem distribution
- This distribution is not known in advance; it is prone to evolve

The opportunity

- The computer is idle most of its time
- Idle time can be used to self-play and learn the best strategy.

Continuous Search for CP

General setting



Framework : Default

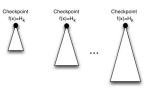
f = heuristic model

- Checkpoint *i* : compute problem description *x*, find the best heuristics $H_i = f(x)$
- **2** Apply H_i until cutoff time t_i
- **3** Goto 1 (x has changed !)

(personal comment : more a reinforcement learning algorithm...) Lagoudakis and Littman 2001

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Continuous Search for CP, 2

Framework

Production/Exploitation mode : use Default us

• Learning/Exploration mode during idle time

use f revise f

- try variants (use $H \ll f(x)$)
- collect examples ((x,1_H), y
- relearn f



Representation : 95 features in toto

Static features

Problem Size Features:

- 1. Number of clauses: denoted c
- 2. Number of variables: denoted v
- 3. Ratio: c/v

Variable-Clause Graph Features:

4-8. Variable nodes degree statistics: mean, variation coefficient, min, max and entropy.
9-13. Clause nodes degree statistics: mean, variation coefficient, min, max and entropy.

Variable Graph Features:

14-17. Nodes degree statistics: mean, variation coefficient, min and max.

Balance Features:

18-20. Ratio of positive and negative literals in each clause: mean, variation coefficient and entropy.

21-25. Ratio of positive and negative occurrences of each variable: mean, variation coefficient, min, max and entropy.

26-27. Fraction of binary and ternary clauses

Proximity to Horn Formula:

28. Fraction of Horn clauses

29-33. Number of occurrences in a Horn clause for each variable: mean, variation coefficient, min, max and entropy.

DPLL Probing Features:

34-38. Number of unit propagations: computed at depths 1, 4, 16, 64 and 256.

39-40. Search space size estimate: mean depth to contradiction, estimate of the log of number of nodes.

Local Search Probing Features:

41-44. Number of steps to the best local minimum in a run: mean, median, 10th and 90th percentiles for SAPS.

45. Average improvement to best in a run: mean improvement per step to best solution for SAPS.

45-47. Fraction of improvement due to first local minimum: mean for SAPS and GSAT.

 Coefficient of variation of the number of unsatisfied clauses in each local minimum: mean over all runs for SAPS.

Figure: Features from [Xu, Hutter, Hoos, Leyton-Brown, CP 2007].



Representation : 95 features in toto

Static features

Problem definition : density, tightness, ... Variable size and degree (min, max, average, variance) Constraint degree and cost category (exp, cubic, quadratic, lin. cheap, lin. expensive)

Dynamic features

Heuristic criteria(variable) : wdeg, domdeg, impact : min, max, averageover all var15Constraint weight (wdeg) : min, max, average12Constraint filtering : min, max, average of number of times called by12propagation3Checkpoint information : number of nodes, max depth, number ofassigned var/sat constraints for the last non-failed node, wdeg andimpact of non-assigned var33

Everything normalized in $\left[-1,1\right]$



Gathering examples and improving

During idle time consider the problem instance last solved, generate new trials

- each trial : everything as in production mode except for *i*-th checkpoint
- 2 at *i*-th checkpoint, try the second best heuristics after the current h.model f. (x, h)
- see if it improves on default

4 Finally
$$\mathcal{E} = \bigcup \{((x, h), y)\}$$

5 Learn f from $\mathcal E$

у

Gaussian SVM

Difficulty

Hugely imbalanced problem;

•
$$y = 1$$
 if $time(trial) \sim time(default)$.



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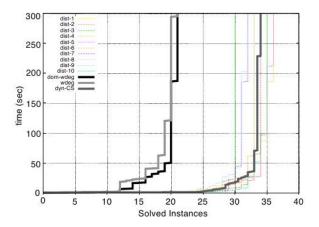
496 CSP from MiniZinc and XCZP repositories

1 Nurse scheduling	100
2 Balance Incomplete Block Design	83
Job shop scheduling	130
4 Geometric	100
5 Langford numbers	83
Experimental setting	
Gecode 2.1.1	
• cutoff 1,000 (increase $ imes$ 1.5)	
 Heuristics : mindom, domdeg, wdeg, dom-wdeg, impacts 	
Value selection : min-dom	

Perf : average on 10 random orderings of CS instances.

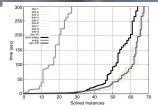


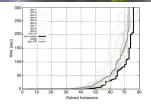
Langford numbers





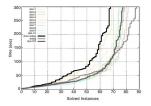
More results

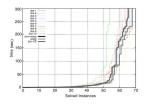




Geom







nurse

bibd

More results

Time out 5 min

Problem	dom-wdeg				wd	2g	dyn-CS		
	#sol	time(h)	avg-time(m)	#sol	time(h)	avg-time(m)	#sol	time(h)	avg-time(m)
nsp	68	3.9	2.34	88	2.6	1.56	77	2.9	1.74
bibd	68	1.8	1.37	68	1.8	1.37	65	2.0	1.44
js	76	4.9	2.26	73	5.1	2.35	73	5.2	2.4
lfn	21	5.2	3.75	21	5.3	3.83	33	4.1	2.96
geom	64	3.9	2.34	27	6.8	4.08	67	3.3	1.98
Total	297	19.7	2.39	274	21.6	2.61	315	17.5	2.11

Time out 3 min

Problem	dom-wdeg				wde	eg	dyn-CS		
	#sol	time(h)	avg-time(m)	#sol	time(h)	avg-time(m)	#sol	time(h)	avg-time(m)
nsp	61	2.8	1.68	81	2.1	1.26	75	2.2	1.32
bibd	62	1.3	0.94	62	1.3	0.94	60	1.4	1.01
js	74	3.1	1.43	69	3.3	1.52	67	3.4	1.57
lfn	20	3.2	2.31	20	3.2	2.31	32	2.5	1.81
geom	56	2.6	1.56	20	4.3	2.58	63	2.2	1.32
Total	273	13.0	1.57	252	14.2	1.72	297	11.7	1.42



Benefits of online learning

- Can quickly converge to best heuristics 3 out of 5
- Can switch to hybrid strategy

3 out of 5 2 out of 5

Meta-search accuracy vs model accuracy

Timeout	bibd	nsp	geom	js	lfn	Total
3 Min	64.5%	64.2%	79.2%	65.6%	68.2%	68.3%
5 Min	63.2%	58.8%	76.9%	63.6%	73.8%	67.3%
Average	63.9%	61.5%	78.0%	64.6%	71.0%	67.8%



Most approaches are offline

- SATzilla
- CPHydra
- self-AQME

Xu, Hutter, Hoos, Leyton-Brown 08 O'Mahony et al. 08 Pulina Tacchella 09

lssues

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- Passive vs Active learning
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- Reinforcement learning...



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