

# Artificial Intelligence: News and Questions

Michele Sebag  
CNRS – INRIA – Univ. Paris-Saclay

ArenbergSymposium – Leuven – Nov. 27th, 2019

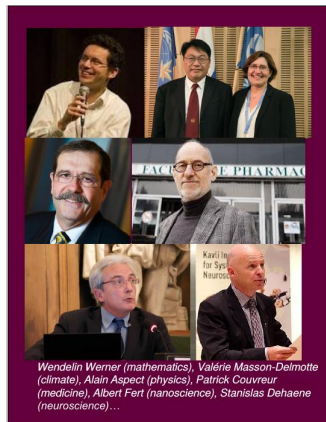
*Credit for slides: Yoshua Bengio; Yann LeCun; Nando de Freitas; Léon Gatys; Max Welling; Victor Berger*



# Université Paris-Saclay in 1 slide

## 14 partners

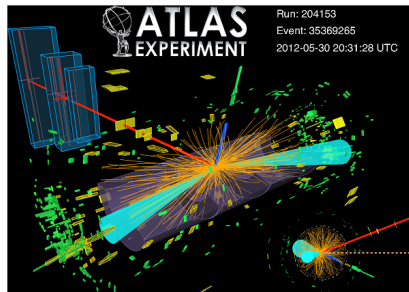
- ▶ 3 Univ.
- ▶ 4 Grandes écoles
- ▶ 7 Research Institutes



**15% of French Research**  
5,500 PhD; 10,000 Faculty members  
10 Field medals; 3 Nobel; 160 ERC.

## Some AI projects

- ▶ Center for Data Science  
ML Higgs Boson Challenge (2015)
- ▶ Institute DataIA: AI for Society
- ▶ Big Data, Optimization and  
Energy (See4C challenge)





# Two visions of AI – 1950 - 1960

## Logical calculus can be achieved by machines !

- ▶ All men are mortal.
- ▶ Socrates is a man.
- ▶ Therefore, Socrates is mortal.

**Primary operation:** Deduction (reasoning) ? or Induction (learning)?

- ▶ Should we learn what we can reason with ?
- ▶ Should we reason with what we can learn ?

	Alan Turing	John McCarthy
HOW	Learning	Reasoning
VALIDATION	Human assessment	Pb Solving

# Alan Turing (1912-1954)

Muggleton, 2014



## 1950: Computing Machinery and Intelligence

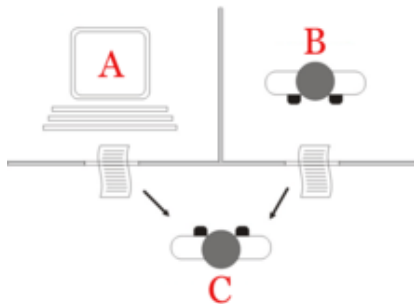
- ▶ Storage will be ok
- ▶ But programming needs *prohibitively large human resources*
- ▶ Hence, machine learning.

*by (...) mimicking education, we should hope to modify the machine until it could be relied on to produce definite reactions to certain commands.*

*One could carry through the organization of an intelligent machine with only two interfering inputs, one for pleasure or reward, and the other for pain or punishment.*

# The imitation game

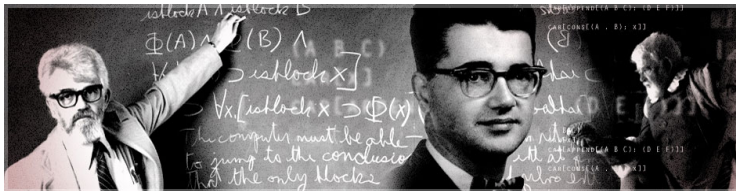
## The Turing test



## Issues

- ▶ Human assessment; no golden standard.

# John McCarthy (1927-2011)



## 1956: The Dartmouth conference

- ▶ With Marvin Minsky, Claude Shannon, Nathaniel Rochester, Herbert Simon, et al.
- ▶ *The study is to proceed on the basis of the conjecture that every aspect of learning or any other feature of intelligence can in principle be so precisely described that a machine can be made to simulate it. An attempt will be made to find how to make machines use language, form abstractions and concepts, solve kinds of problems now reserved for humans, and improve themselves.*



# Computational Logic for AI

- ▶ Declarative languages
- ▶ Symbolic methods, deduction
- ▶ Focussed domains (expert systems)
- ▶ Games and problem solving

## Issues

- ▶ How to ground symbols ?
- ▶ Where does knowledge come from ?

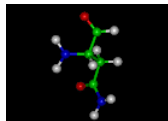
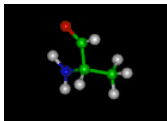
# Automating Science using Robot Scientists

King et al, 04-19

## From facts to hypotheses to experiments to new facts...

- ▶ A proper representation and domain theory

*Benzene( $A_1, A_2, A_3, A_4, A_5, A_6$ ) :  $\neg \text{Carbon}(A_1), \text{Carbon}(A_2), \dots$   
 $\text{Bond}(A_1, A_2), \text{Bond}(A_2, A_3), \text{Bond}(A_3, A_4) \dots$*

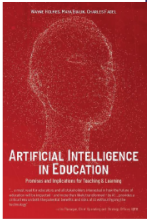


- ▶ Active Learning — Design of Experiments
- ▶ Control of noise

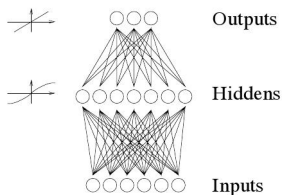




# The Wave of AI



# Neural Nets, ups and downs in AI



(C) David McKay - Cambridge Univ. Press

## History

- 1943 A neuron as a computable function  $y = f(\mathbf{x})$  Pitts, McCullough  
Intelligence  $\rightarrow$  Reasoning  $\rightarrow$  Boolean functions
- 1960 Connexionism + learning algorithms Rosenblatt
- 1969 AI Winter Minsky-Papert
- 1989 Back-propagation Amari, Rumelhart & McClelland, LeCun
- 1992 NN Winter Vapnik
- 2005 Deep Learning Bengio, Hinton

# The revolution of Deep Learning

- ▶ Ingredients were known for decades
- ▶ Neural nets were no longer scientifically exciting (except for a few people)
- ▶ Suddenly... 2006

# Revival of Neural Nets

Bengio, Hinton 2006

1. Grand goal: AI
2. Requisites
  - ▶ Computational efficiency
  - ▶ Statistical efficiency
  - ▶ Prior efficiency: architecture relies on human labor
3. Compositionality principle: skills built on the top of simpler skills

Piaget 1936

# Revival of Neural Nets

Bengio, Hinton 2006

1. Grand goal: AI
2. Requisites
  - ▶ Computational efficiency
  - ▶ Statistical efficiency
  - ▶ Prior efficiency: architecture relies on **student** labor
3. Compositionality principle: skills built on the top of simpler skills

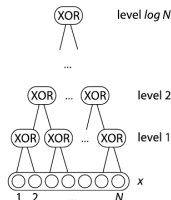
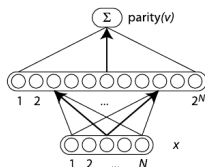
Piaget 1936



# The importance of being deep

## A toy example: $n$ -bit parity

Hastad 1987



## Pros: efficient representation

Deep neural nets are exponentially more compact

## Cons: poor learning

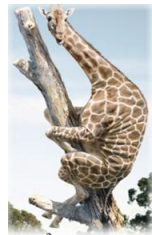
- ▶ More layers  $\rightarrow$  more difficult optimization problem
- ▶ Getting stuck in poor local optima.
- ▶ **Handled through smart initialization**

Glorot et al. 10

# Convolutional NNs: Enforcing invariance

LeCun 98

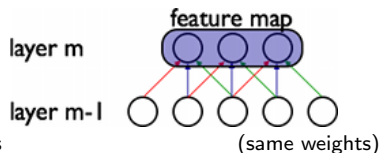
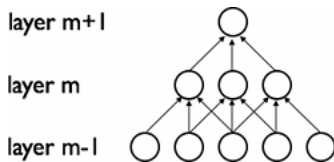
## Invariance matters



- ▶ Visual cortex of the cat
  - ▶ cells arranged in such a way that
  - ▶ ... each cell observes a fraction of the visual field
  - ▶ ... their union covers the whole field

Hubel & Wiesel 68

receptive field

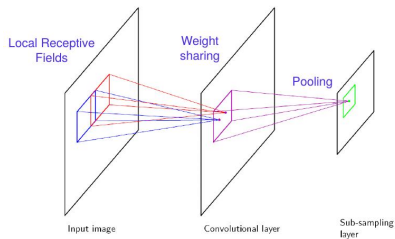


- ▶ Layer  $m$ : detection of local patterns
- ▶ Layer  $m+1$ : non linear aggregation of output of layer  $m$

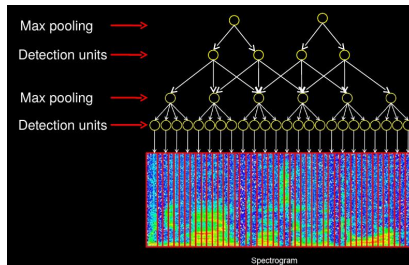
# Convolutional architectures

LeCun 1998

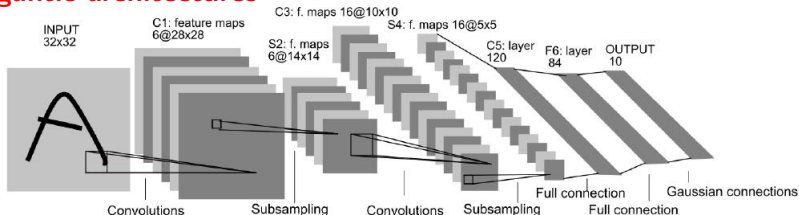
## For images



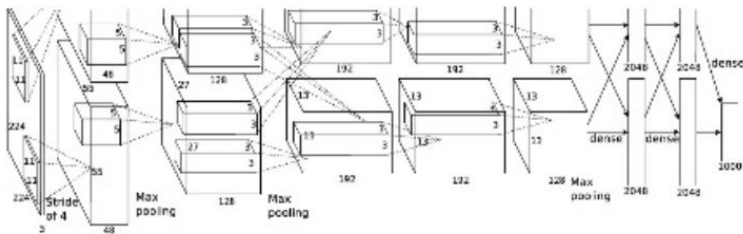
## For signals



# Gigantic architectures



LeCun 1998



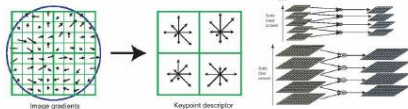
Kryzhevsky et al. 2012

## Properties

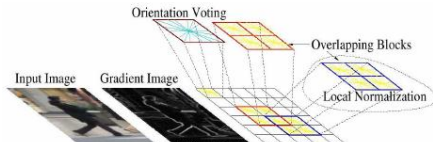
- ▶ Invariance to small transformations (over the region)
- ▶ Reducing the number of weights by several orders of magnitude

# What is new ?

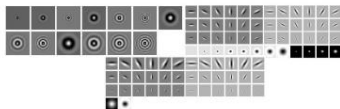
Former state of the art



SIFT



HoG



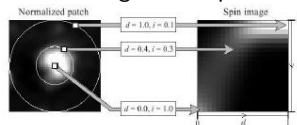
Textons

SIFT: scale invariant feature transform

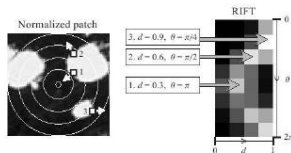
HOG: histogram of oriented gradients

Textons: "vector quantized responses of a linear filter bank"

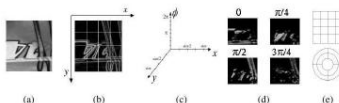
e.g. in computer vision



Spin image



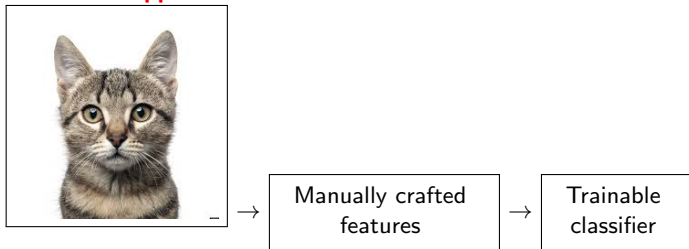
RIFT



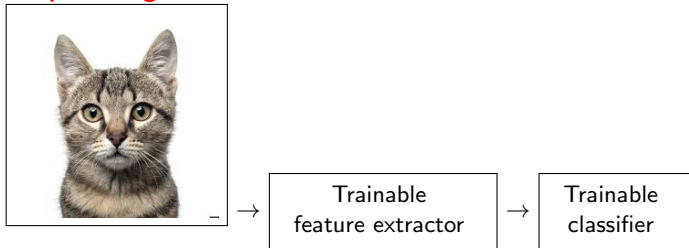
GLOH

## What is new, 2

### Traditional approach

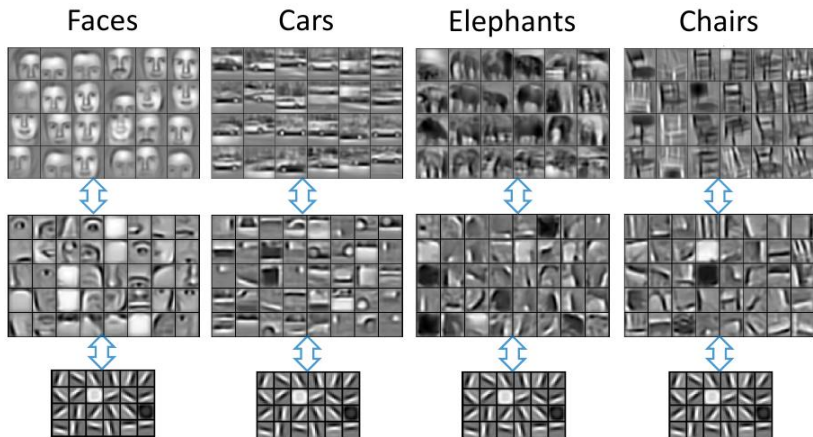


### Deep learning



## A new representation is learned

Bengio et al. 2006



# Why Deep Learning now ?

## CONS

- ▶ a non-convex optimization problem
- ▶ no theorems
- ▶ delivers a black box model

## PROS

- ▶ Linear complexity w.r.t. #data
- ▶ Performance leaps if **enough data and enough computational power.**



# A leap in the state of the art: ImageNet

Deng et al. 12

15 million labeled high-resolution images; 22,000 classes.



## Large-Scale Visual Recognition Challenge

- ▶ 1000 categories.
- ▶ 1.2 million training images,
- ▶ 50,000 validation images,
- ▶ 150,000 testing images.

## A leap in the state of the art, 2

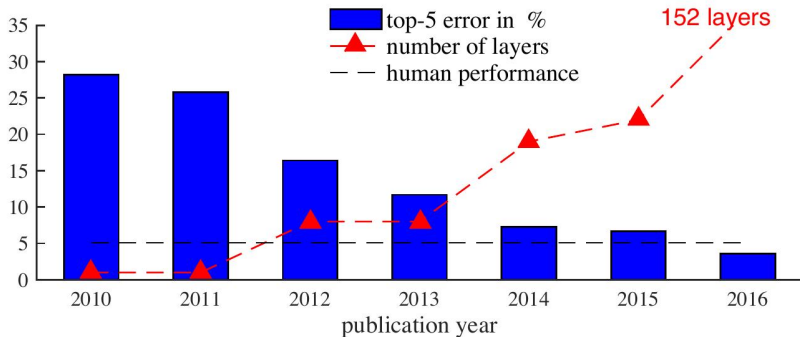
2012 Teams	%error	2013 Teams	%error	2014 Teams	%error
Supervision (Toronto)	15.3	Clarifai (NYU spinoff)	11.7	GoogLeNet	6.6
ISI (Tokyo)	26.1	NUS (singapore)	12.9	VGG (Oxford)	7.3
VGG (Oxford)	26.9	Zeiler-Fergus (NYU)	13.5	MSRA	8.0
XRCE/INRIA	27.0	A. Howard	13.5	A. Howard	8.1
UvA (Amsterdam)	29.6	OverFeat (NYU)	14.1	DeeperVision	9.5
INRIA/LEAR	33.4	UvA (Amsterdam)	14.2	NUS-BST	9.7
		Adobe	15.2	TTIC-ECP	10.2
		VGG (Oxford)	15.2	XYZ	11.2
		VGG (Oxford)	23.0	UvA	12.1

shallow approaches

deep learning

Y. LeCun StatLearn tutorial

## Super-human performances



2012 Alex Net

2013 ZFNet

2014 VGG

2015 GoogLeNet / Inception

2016 Residual Network



# Playing with representations

Gatys et al. 15, 16



Used for *Content*



Used for *Style*

Decrease  $\alpha/\beta$

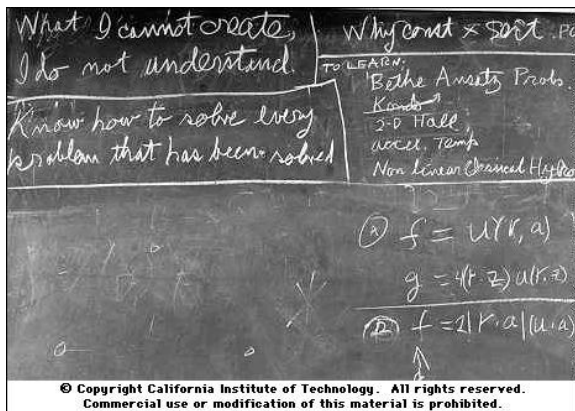


- ▶ Style and contents in a convolutional NN are separable
- ▶ Use a trained VGG-19 Net:
  - ▶ applied on image 1 (content)
  - ▶ applied on image 2 (style)
  - ▶ find input matching hidden representation of image 1 (weight  $\alpha$ ) and hidden representation of image 2 (weight  $\beta$ )

# Beyond classifying, modifying data: generating data

“What I cannot create I do not understand”

Feynman 88



# Generative Adversarial Networks

Goodfellow et al., 14

**Goal:** Find a generative model

- ▶ Classical: learn a distribution hard
- ▶ Idea: replace a distribution evaluation by a 2-sample test

## Principle

- ▶ Find a good generative model, s.t. generated samples **cannot be discriminated** from real samples

(not easy)

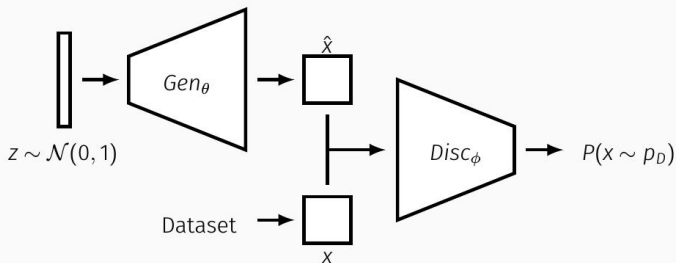
# Generative Adversarial Networks, 2

Goodfellow, 2017

## Elements

- ▶ Dataset, true samples  $\mathbf{x}$  ( **real** )
- ▶ Generator  $G$ , generated samples ( **fake** )
- ▶ Discriminator  $D$ : discriminates *fake* from *real*

- Generator  $G_\theta : \mathcal{Z} \rightarrow \mathcal{D}$
- Discriminator  $D_\phi : \mathcal{D} \rightarrow [0, 1]$



**A min-max game**

**Embedding a Turing Test !**

$$\min_G \max_D \mathbb{E}_{\mathbf{x} \in \text{data}} [\log(D(\mathbf{x}))] + \mathbb{E}_{z \sim p_z(z)} [\log(1 - D(z))]$$



# Generative Adversarial Networks: successes

Mescheder, Geiger and Nowozin, 2018



## and monsters



(Goodfellow 2016)

# From Deep Learning to Differentiable Programming

## Principle

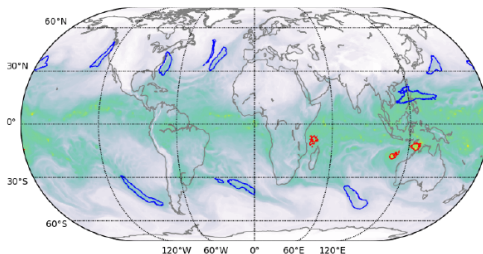
- ▶ Most programs can be coded as a neural net.
- ▶ Define a performance criterion
- ▶ Let the program interact with the world *and train itself*:  
programs that can learn

## Revisiting Partial Differential Equations

### 1. Combining with simulations: recognizing Tropical Cyclones

Kurth et al.

18



1152x768 spatial grid, 3 hours time step

3 classes: TCs (0.1%), Atmospheric Rivers (1.7%) and Background

# Physics Informed Deep Learning

## Data driven solutions of PDE

Raissi 19

Equation:

$$u_t = \mathcal{N}(t, u, x, u_x, u_{xx}, \dots)$$

residual:

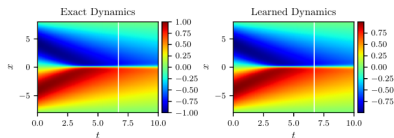
$$f := u_t - \mathcal{N}(t, u, x, u_x, u_{xx}, \dots)$$

Initial and boundary conditions:  $(t_u^i, x_u^i, u^i), i = 1 \dots N$

Training points  $(t_f^j, x_f^j), j = 1 \dots N'$

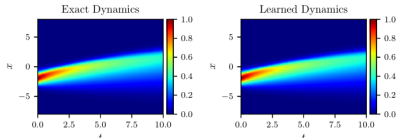
**Train  $u(t, s)$  minimizing**

$$\frac{1}{N} \sum_{i=1}^N |u(x_u^i, t_u^i) - u^i|^2 +$$



train

$$u(0, x) = \sin(\pi x / 8)$$



test

$$u(0, x) = -\exp(-(x + 2)^2)$$

# Physics Informed Deep Learning

## Data driven solutions of PDE

Raissi 19

Equation:

$$u_t = \mathcal{N}(t, u, x, u_x, u_{xx}, \dots)$$

residual:

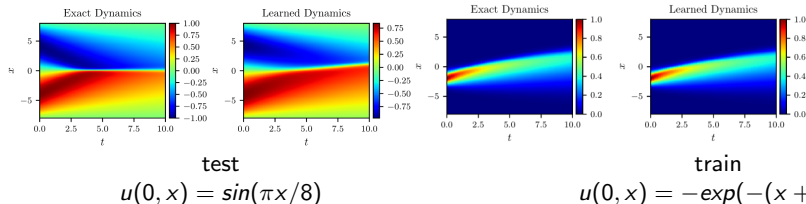
$$f := u_t - \mathcal{N}(t, u, x, u_x, u_{xx}, \dots)$$

Initial and boundary conditions:  $(t_u^i, x_u^i, u^i), i = 1 \dots N$

Training points  $(t_f^j, x_f^j), j = 1 \dots N'$

**Train  $u(t, s)$  minimizing**

$$\frac{1}{N} \sum_{i=1}^N |u(x_u^i, t_u^i) - u^i|^2 +$$





# Issues with black-box models

Good performances  $\nRightarrow$  Accurate model



# Robustness wrt perturbations

What can happen when perturbing an example ? Anything !

## Malicious perturbations

Goodfellow et al. 15

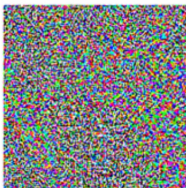


$x$

“panda”

57.7% confidence

+ .007 ×



$\text{sign}(\nabla_x J(\theta, x, y))$

“nematode”

8.2% confidence

=



$x +$

$\epsilon \text{sign}(\nabla_x J(\theta, x, y))$

“gibbon”

99.3 % confidence



## Adversarial examples

### Adversarial Traffic Signs

Original



Adversarial



**Classified as:** Stop

Speed limit (30)

## A Case of Irrational Scientific Exuberance

- ▶ Underspecified goals Big Data cures everything
- ▶ Underspecified limitations Big Data can do anything (if big enough)
- ▶ Underspecified caveats Big Data and Big Brother

## Wanted: An AI with common decency

- ▶ Fair no biases
- ▶ Accountable models can be explained
- ▶ Transparent decisions can be explained
- ▶ Robust w.r.t. malicious examples

# ML & AI, 2

## In practice

- ▶ Data are ridden with biases
- ▶ Learned models are biased (prejudices are transmissible to AI agents)
- ▶ Issues with robustness
- ▶ Models are used out of their scope

## More

- ▶ C. O'Neill, *Weapons of Math Destruction*, 2016
- ▶ Zeynep Tufekci, *We're building a dystopia just to make people click on ads*, Ted Talks, Oct 2017.

# Machine Learning: discriminative or generative modelling

Given a training set

iid samples  $\sim P(X, Y)$

$$\mathcal{E} = \{(\mathbf{x}_i, y_i), \mathbf{x}_i \in \mathbb{R}^d, i \in [[1, n]]\}$$

Find

- ▶ Supervised learning:  $\hat{h} : X \mapsto Y$  or  $\hat{P}(Y|X)$
- ▶ Generative model  $\hat{P}(X, Y)$

**Predictive modelling might be based on correlations**

*If umbrellas in the street, Then it rains*



# The implicit big data promise:

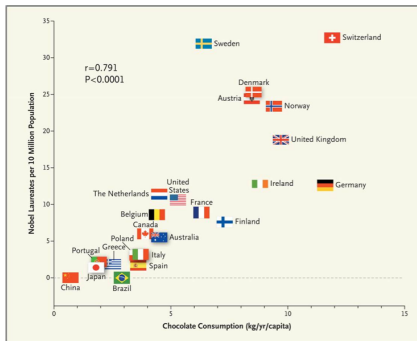
If you can predict what will happen,  
then how to make it happen what you want ?

**Knowledge** → **Prediction** → **Control**

**ML models will be expected to support** *interventions*:

- ▶ health and nutrition
- ▶ education
- ▶ economics/management
- ▶ climate

# Correlations do not support interventions



F. H. Messerli: *Chocolate Consumption, Cognitive Function, and Nobel Laureates*, N Engl J Med 2012

Causal models are needed to support interventions

*Consumption of chocolate enables to predict # of Nobel prizes  
but eating more chocolates does not increase # of Nobel prizes*



# Discussion

## Scientific Caveat

- ▶ Robustness of results
- ▶ Reproducibility of results (gigantic resources)

## Economic Caveat

- ▶ Winner take all:

Value → Data → More Value

## Societal Caveat

- ▶ Learning from biased data → carving prejudices in stone
- ▶ Accurate prediction of individual risks → ruins insurance mechanisms.