

Cycle Ingénieur – 2ème année Département Informatique

# Verification and Validation

Part IV:

Deductive Verification (I)

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Is it « correct »?
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(system under test must behave deterministically, or have controlled non-determinism, must be initializable)

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Limits in perfection:

We know only up to a given "certainty" that the program meets the specification ...

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  - verify that a program "fits" to a concrete design model.

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- Recently, Microsoft has agreed in a Monopoly-Lawsuit against the European Commission to provide a formal Spec of the Windows-Server-Protocols
  - the tools validating them use internally automated proofs

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#### Nous, on le fera à la main ...

#### How to do Verification?

In the sequel, we concentrate on

**Deductive Verification** 

(Proof Techniques)

#### Standard example

#### The specification in UML/MOAL (Classes in USE Notation):

```
class Triangles inherits_from Shapes
  attributes
  a : Integer
  b : Integer
  c : Integer

  operations
  mk(Integer,Integer,Integer):Triangle
  is_Triangle(): triangle
  end
```

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#### Standard example: Triangle

```
procedure triangle(j,k,l : positive) is
eq: natural := 0;
begin
if j + k \le 1 or k + 1 \le j or l + j \le k then
   put("impossible");
else if j = k then eg := eg + 1; end if;
    if j = 1 then eq := eq + 1; end if;
    if l = k then eq := eq + 1; end if;
     if eq = 0 then put("quelconque");
    elsif eq = 1 then put("isocele");
    else put("equilateral");
    end if;
end if;
end triangle;
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    (* pre : N≥0 *)
    S:=1; P:=N;
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  (* pre : N \ge 0 *) 
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These programs have the following characteristics:

- one is more efficient, but more complex
- But both have the same specification!

#### How to do Verification?

# How to PROVE that programs meet the specification?

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  A rule with n=0 is an elementary fact. Variables occurring in the formulas  $A_n$  can be arbitrarily substituted.
- Assumptions and conclusions are terms in a logic containing variables

$$x = x$$

$$\frac{x=y}{x=x}$$
  $\frac{x=y}{y=x}$ 

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  $x = y$   $y = z$ 
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An Inference System for the equality operator (or "Equational Logic") looks like this:

$$x = y$$
  $x = y$   $y = z$ 
 $x = x$   $y = x$ 

$$x = y$$

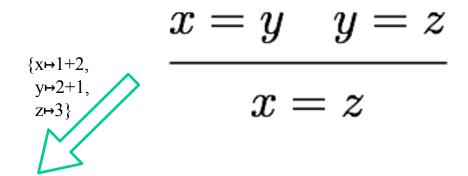
$$x = y$$

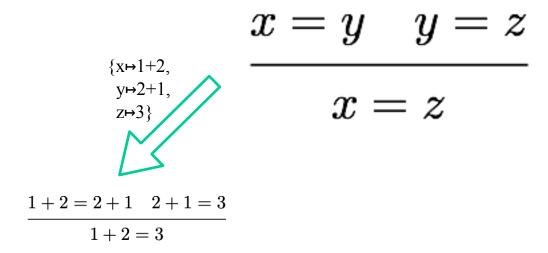
$$P(x)$$

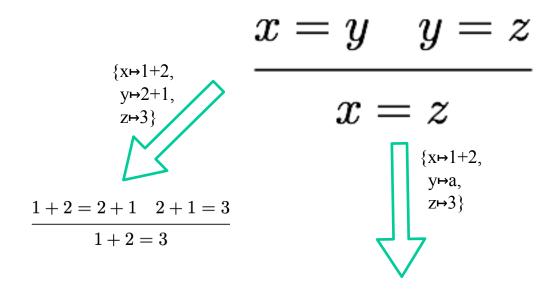
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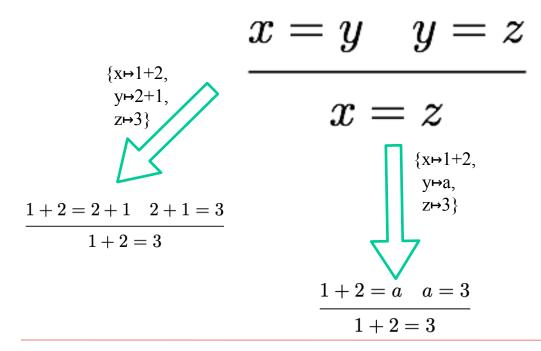
where the first rule "reflexivity" is an elementary fact.

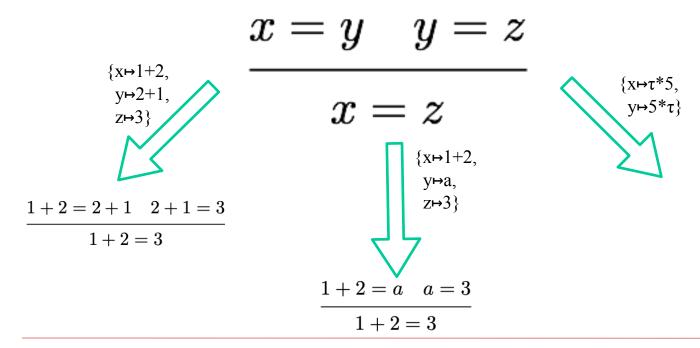
$$\frac{x = y \quad y = z}{x = z}$$

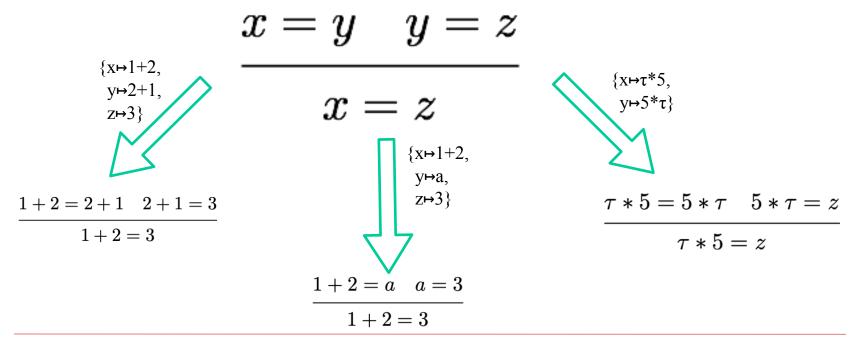












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$$\frac{f(a,b) = a}{a = f(a,b)} \quad \frac{f(a,b) = a}{f(a,b) = c}$$

$$a = c$$

$$g(a) = g(c)$$

$$\frac{f(a,b) = c}{g(a) = g(a)}$$

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The non-elementary facts at the leaves are the *global* assumptions (here f(a,b) = a and f(f(a,b),b) = c).

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This is what theorems are: derivable facts from assumptions in a certain logical system ...

$$\frac{\neg \neg A}{A} \frac{A}{\neg \neg A}$$

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$$\begin{array}{c|c} [A,B] \\ \vdots \\ A & B \\ \hline A \wedge B & Q \end{array}$$

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$$\frac{A}{A \vee B} \quad \frac{B}{A \vee B}$$

$$\frac{\neg \neg A}{A} \frac{A}{A} \frac{A}{\neg \neg A} \qquad \frac{A \quad B}{A \land B} \qquad \frac{A \land B}{Q} \qquad \frac{A \land B}{A} \qquad \frac{A \land B}{Q} \qquad \frac{False}{A}$$

$$\begin{bmatrix} A \\ A \end{bmatrix} \qquad \begin{bmatrix} A \\ \vdots \\ \vdots \\ A \\ A \lor B \end{bmatrix} \qquad \frac{B}{A \lor B} \qquad \frac{\neg A}{B} \qquad \frac{B}{A \to B} \qquad \frac{P \to Q \quad P}{Q}$$

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We consider the Hoare-Logic (Sir Anthony Hoare ...), technically an inference system PL + E + A + Hoare

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  - $\succ$  the conditional IF cond THEN  $c_1$  ELSE  $c_2$
  - the loop
    WHILE cond DO c

where c,  $c_1$ ,  $c_2$ , are cmd's, V variables,

E an arithmetic expression, and cond a boolean expression.

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 $\succ$  P and Q are formulas over the variables V, so they can be seen as set of possible states.

## Hoare Logic vs. Symbolic Execution

 Hoare Logic is also based notion of a symbolic state.

$$state_{sym} = V \rightarrow Set(D)$$

## Hoare Logic vs. Symbolic Execution

#### Intuitively:

$$\vdash \{P\} \ cmd \ \{Q\}$$
 -

#### means:

If a program cmd starts in a state admitted by P if it terminates, that the program must reach a state that satisfies Q.

PL + E + A + Hoare (simplified binding) at a glance:

 $\vdash \{P\} \text{ SKIP } \{P\}$ 

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$$\vdash \{P[x \mapsto E]\}$$
 x :== E $\{P\}$ 

$$\frac{\vdash \{P\} \ c \ \{Q\} \ \vdash \{Q\} \ d \ \{R\}}{\vdash \{P\} \ c; \ d \ \{R\}} \quad \frac{\vdash \{P \land cond\} \ c \ \{P\}}{\vdash \{P\} \ \text{WHILE} \ cond \ \text{DO} \ c \ \{P \land \neg cond\}}$$

PL + E + A + Hoare (simplified binding) at a glance:

$$\frac{P \to P' \quad \vdash \{P'\} \ cmd \ \{Q'\} \quad Q' \to Q}{\vdash \{P\} \ cmd \ \{Q\}}$$

 $\vdash \{P\} \ c; \ d \ \{R\}$ 

 $\vdash \{P\} \text{ WHILE } cond \text{ DO } c \text{ } \{P \land \neg cond\}$ 

#### Test

 Requires Testability of Programs (initialisable, reproducible behaviour, sufficient control over non-determinism)

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- Can be also Work-Intensive !!!
- Requires Test-Tools
- Requires a Formal Specification
- Makes Test-Hypothesis, which can be hard to justify!

#### Formal Proof

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- Makes assumptions on language, method, tool-correctness, too!

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... and extreme ends of a continuum: from static
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Well, no.

But when can we ever be entirely sure that we know what we have in mind? But at least, we can gain confidence validating specs, i.e. by animation and test, thus, by experimenting with them ...

$$\vdash \{P \land \neg cond\} \text{ WHILE } cond \text{ DO } c \text{ } \{P \land \neg cond\}$$

$$\frac{P = P' \quad \vdash \{P'\} \ cmd \ \{Q'\} \quad Q' = Q}{\vdash \{P\} \ cmd \ \{Q\}}$$